

# Environmental wireless sensor networks: a decade's journey from the lab to the field



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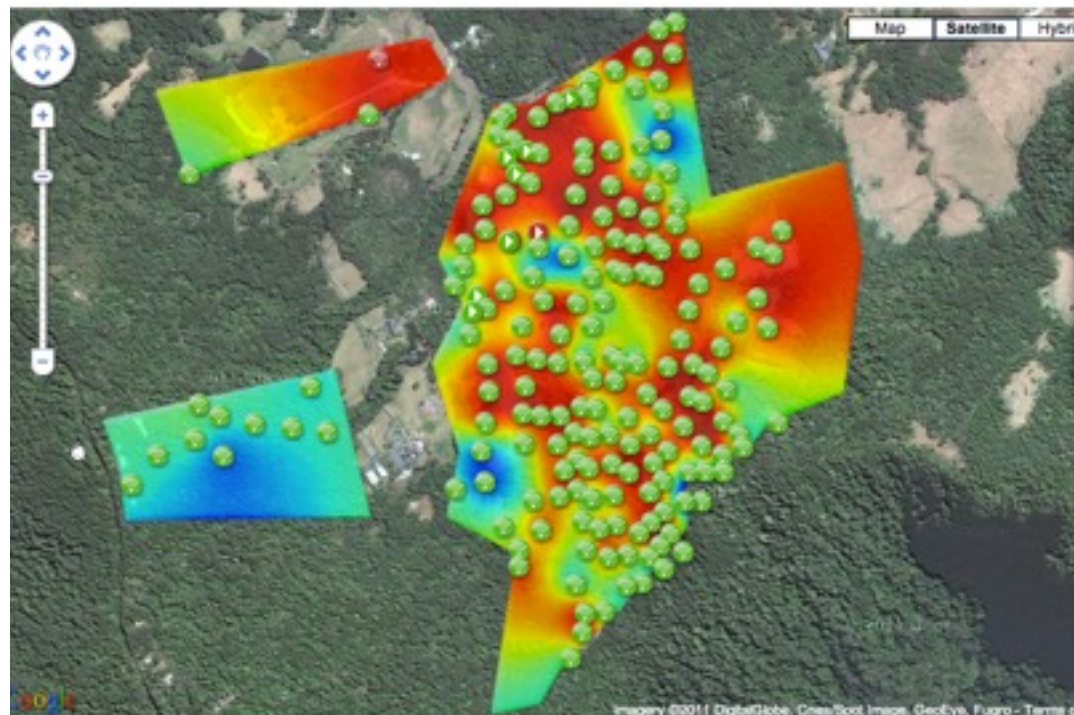
<https://wiki.qut.edu.au/display/cyphy>





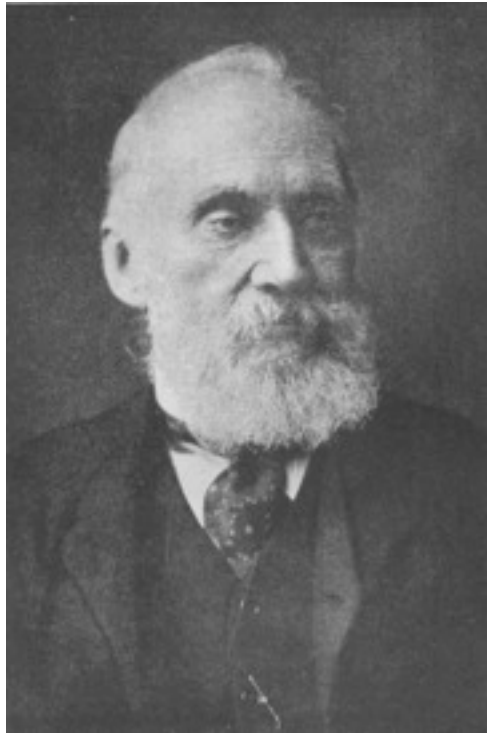
# The ten year journey

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# It's all about measurement

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I often say that when you can measure what you are speaking about, and express it in numbers, you know something about it; but when you cannot measure it, when you cannot express it in numbers, your knowledge is of a meagre and unsatisfactory kind.

— *Lord Kelvin (William Thomson)*

Facts do not cease to exist because they are ignored.

— *Aldous Huxley*

Measurement is the first step that leads to control and eventually to improvement. If you can't measure something, you can't understand it. If you can't understand it, you can't control it. If you can't control it, you can't improve it.

— *H. James Harrington*

# Science is advanced by new measuring tools

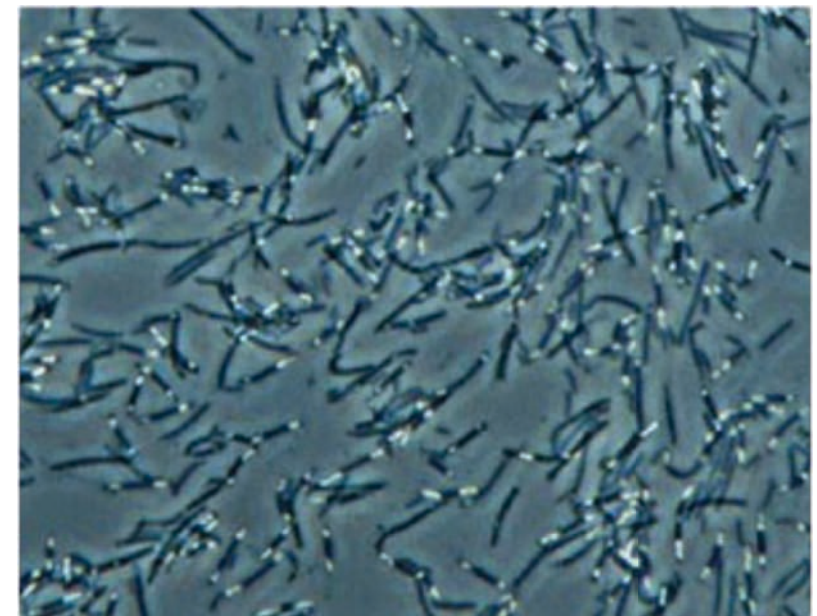
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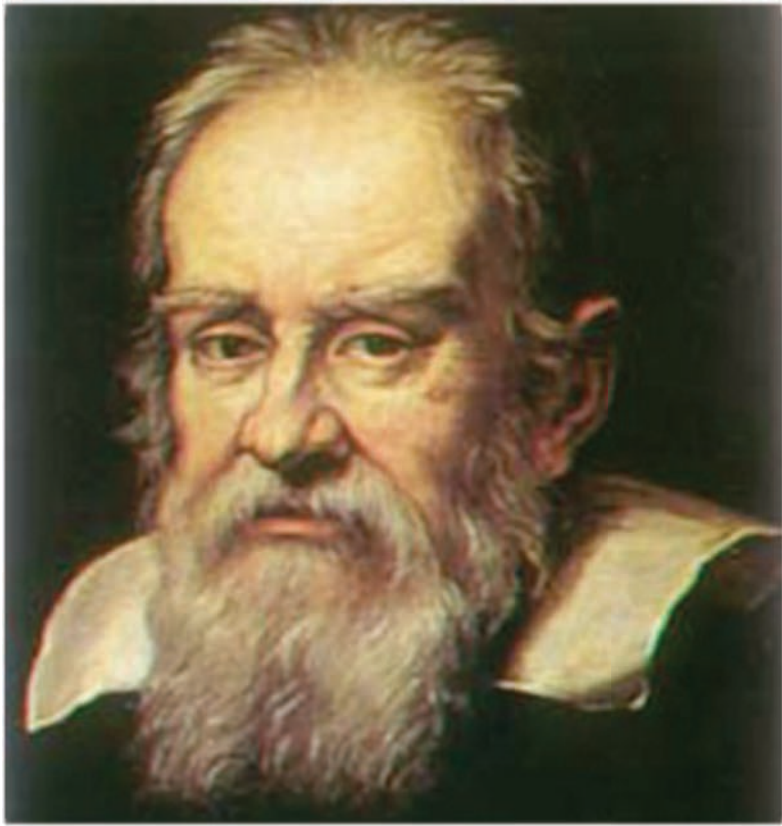


“Nothing tends so much to the advancement of knowledge as the application of a new instrument.”

— *Sir Humphry Davy*





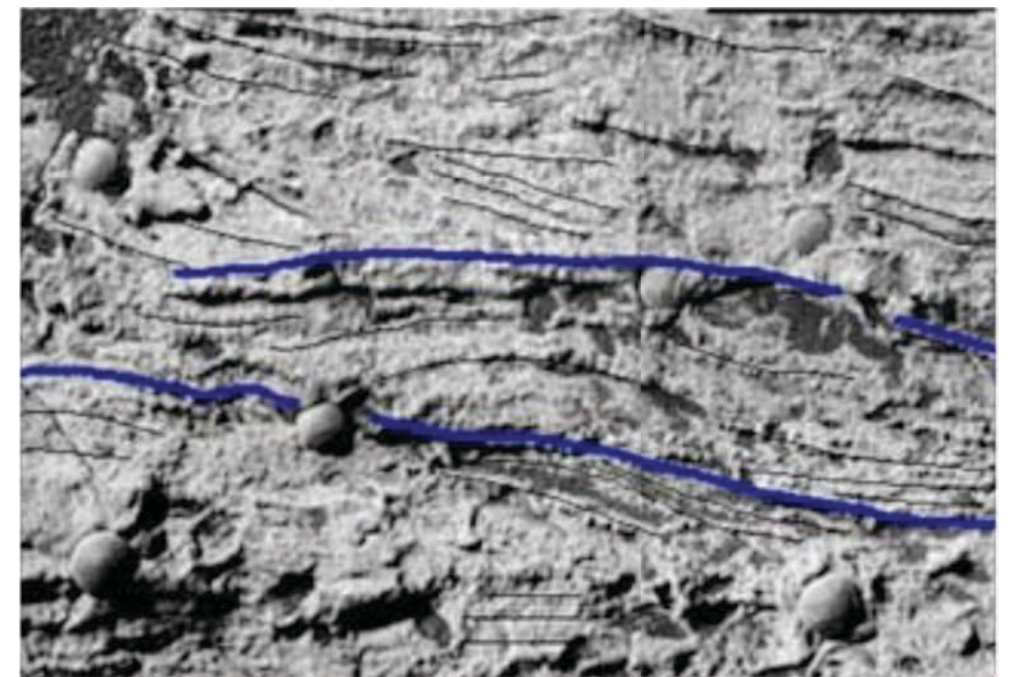
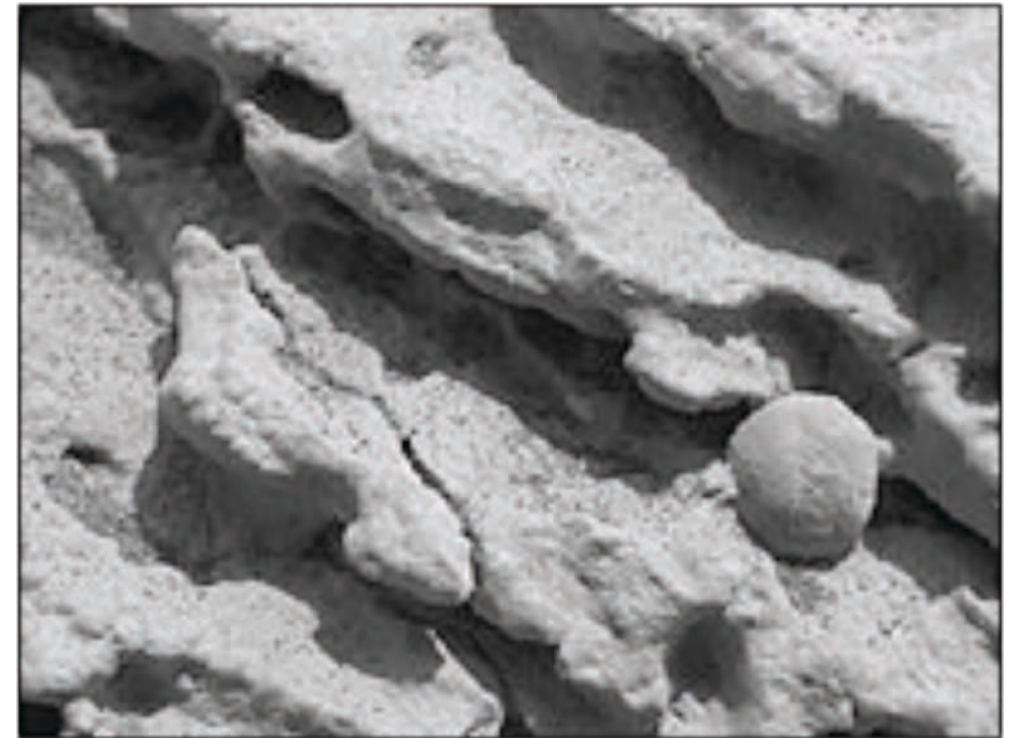
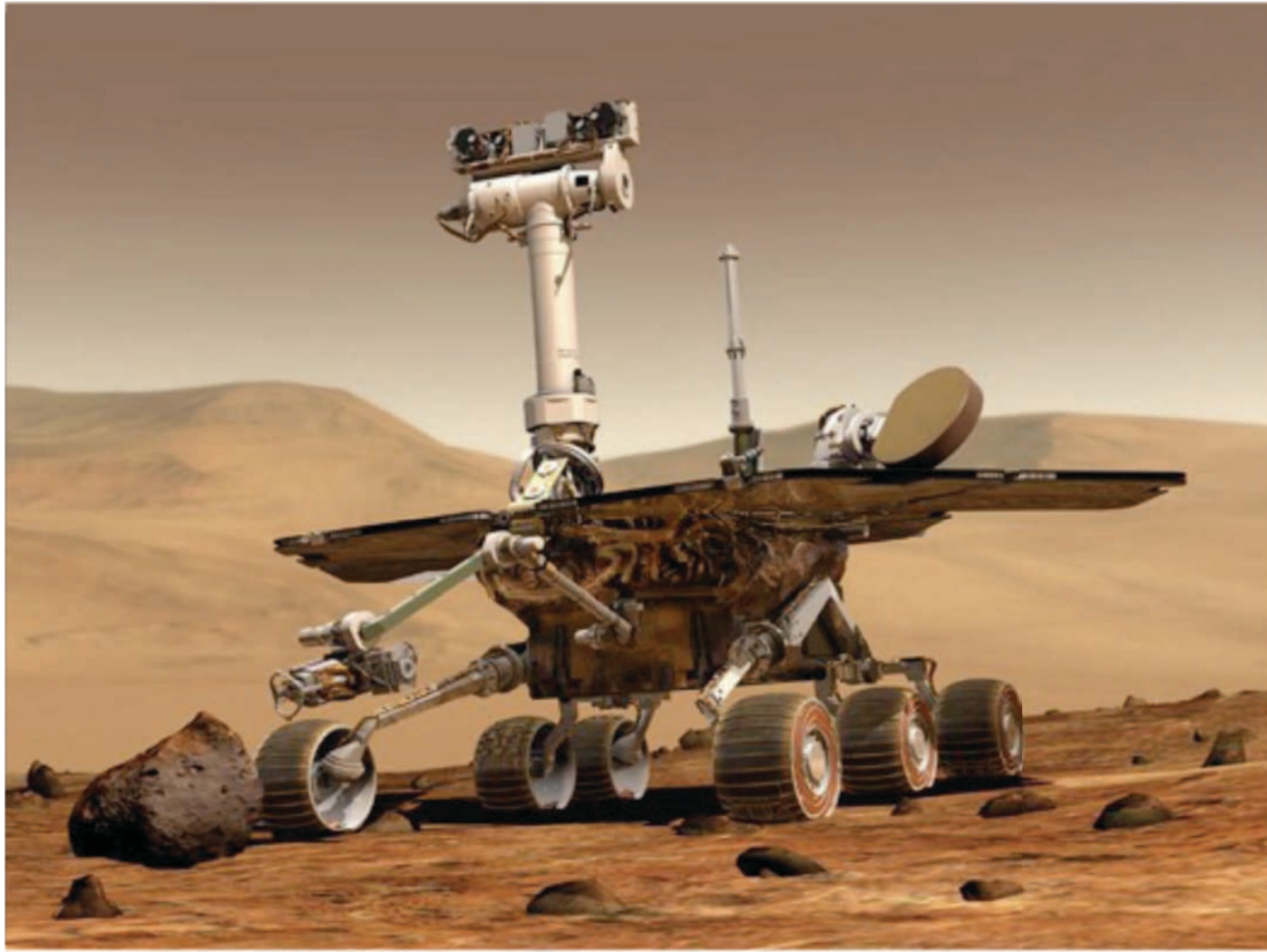












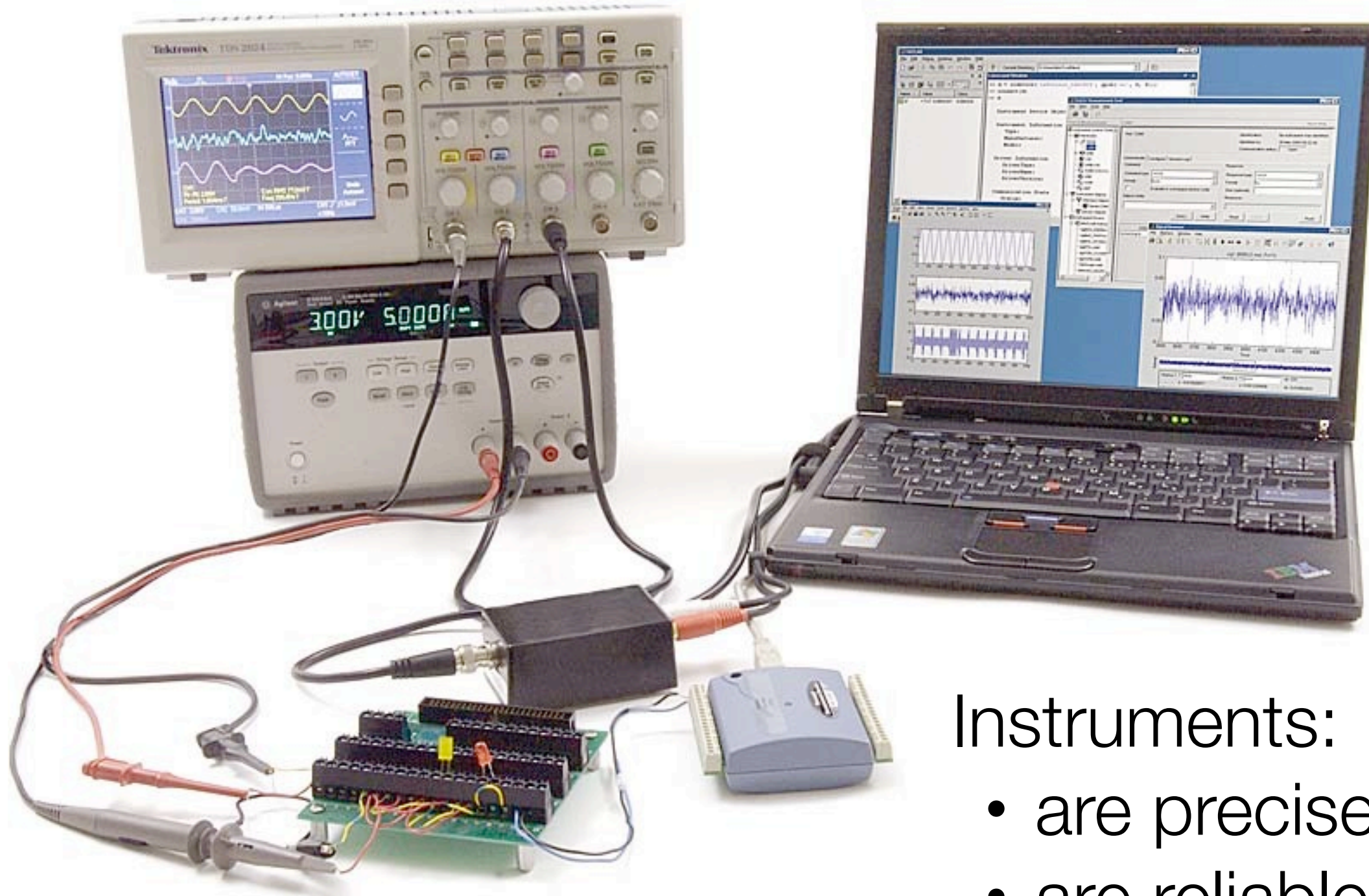












## Instruments:

- are precise
- are reliable
- are easy to use
- have clear display of data





2003	2005-6	2006-7	2007-9	2008-9	2009-9
TOS 1.x	TOS 1.x	TOS1.x	FOS	FOS	FOS
ZTDMA	ZTDMA	MintRoute	Diffusion	LQ/LPL	LQ/LPL
Fleck1C	Fleck1C Fleck2	Fleck3	Fleck3	Fleck3	Fleck3

[1] P. Corke, T. Wark, R. Jurdak, W. Hu, P. Valencia, and D. Moore, “Environmental wireless sensor networks,” *Proceedings of the IEEE*, vol. 98, no. 11, pp. 1903–1917, 2010.

[2] T. Wark, P. Corke, P. Sikka, L. Klingbeil, Y. Guo, C. Crossman, P. Valencia, D. Swain, and G. Bishop-Hurley, “Transforming agriculture through pervasive wireless sensor networks,” *IEEE Pervasive Computing*, vol. 6, pp. 50–57, Apr. 2007.

# The CSIRO's Fleck™ Hardware

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## Fleck nano – fits almost everywhere

Facts: Nordic 433 or 915MHz Radio with built in MCU, Flash and accelerometer



## Fleck with expansion bus boards for almost any sensor



Facts: Atmel 8bit MCU, 915 or 433 MHz Nordic Radio (Range > 1000m), Solar charge Circuit, ~20  $\mu$ A in sleep state

## Gateway module for routing to other networks

Bridging from highly efficient WSN protocols to the internet



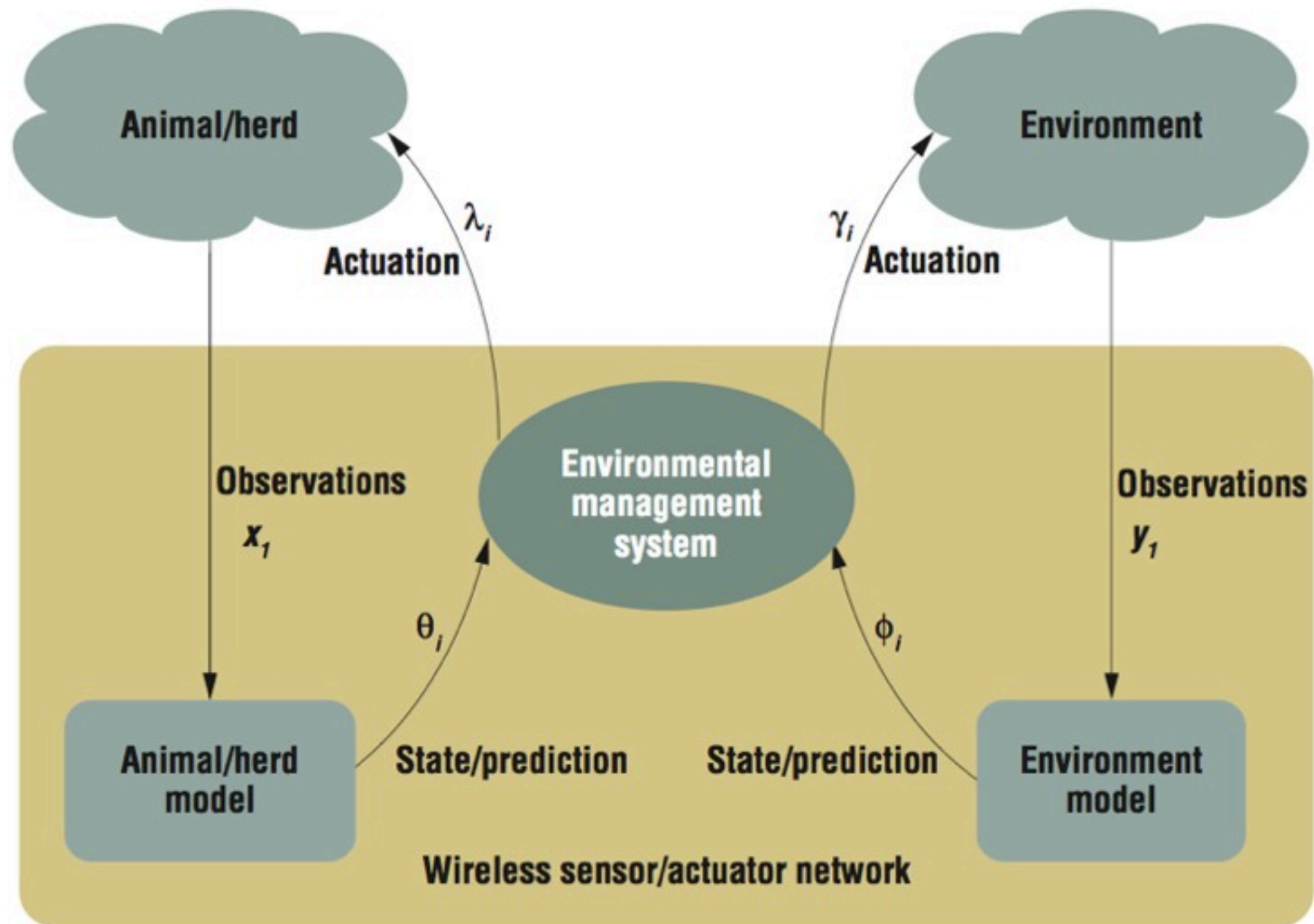




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TOS 1.x	TOS 1.x	TOS1.x	FOS	FOS	FOS
ZTDMA	ZTDMA	MintRoute	Diffusion	LQ/LPL	LQ/LPL
Fleck1C	Fleck2	Fleck3	Fleck3	Fleck3	Fleck3

# Animal agriculture: Closing the loop

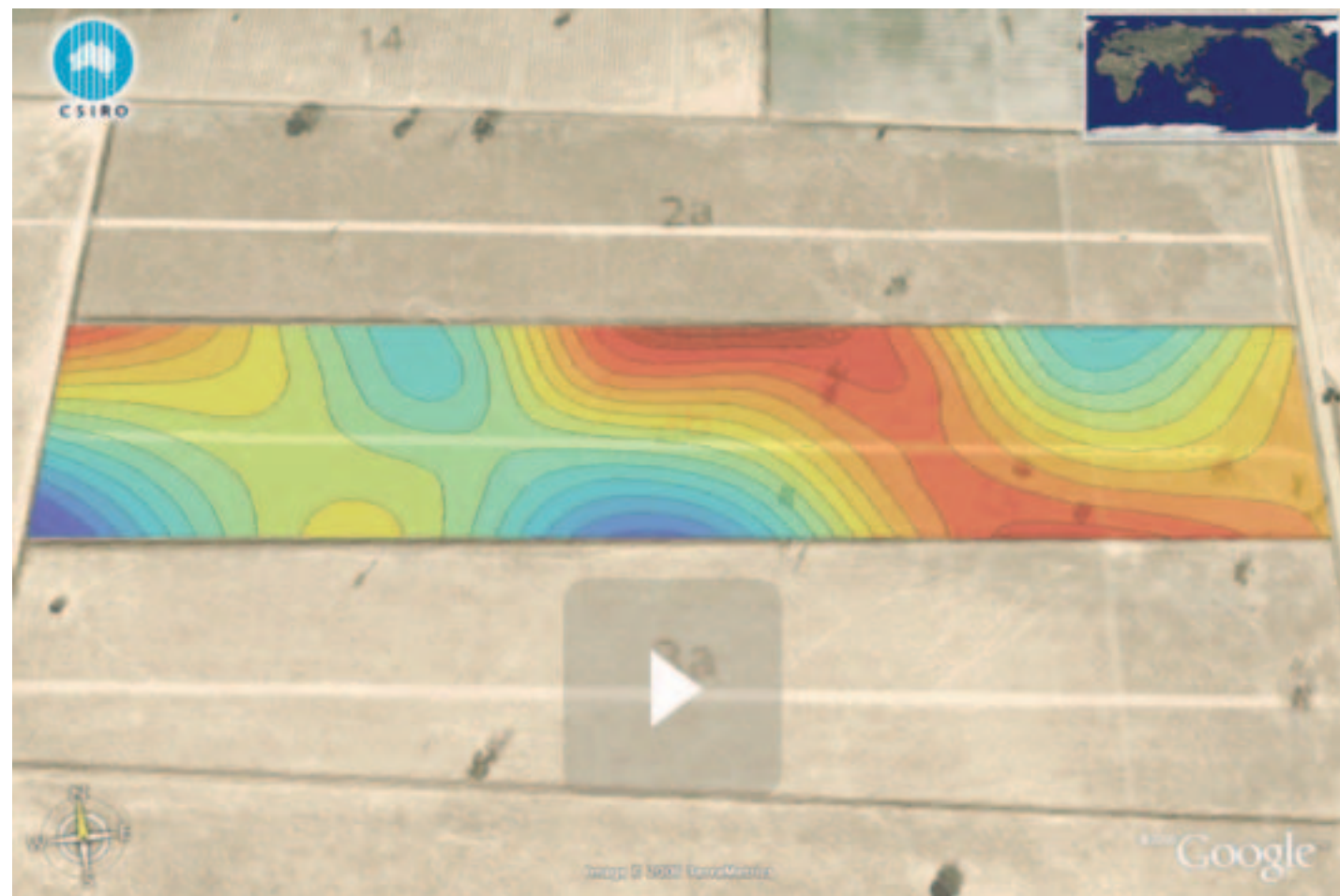
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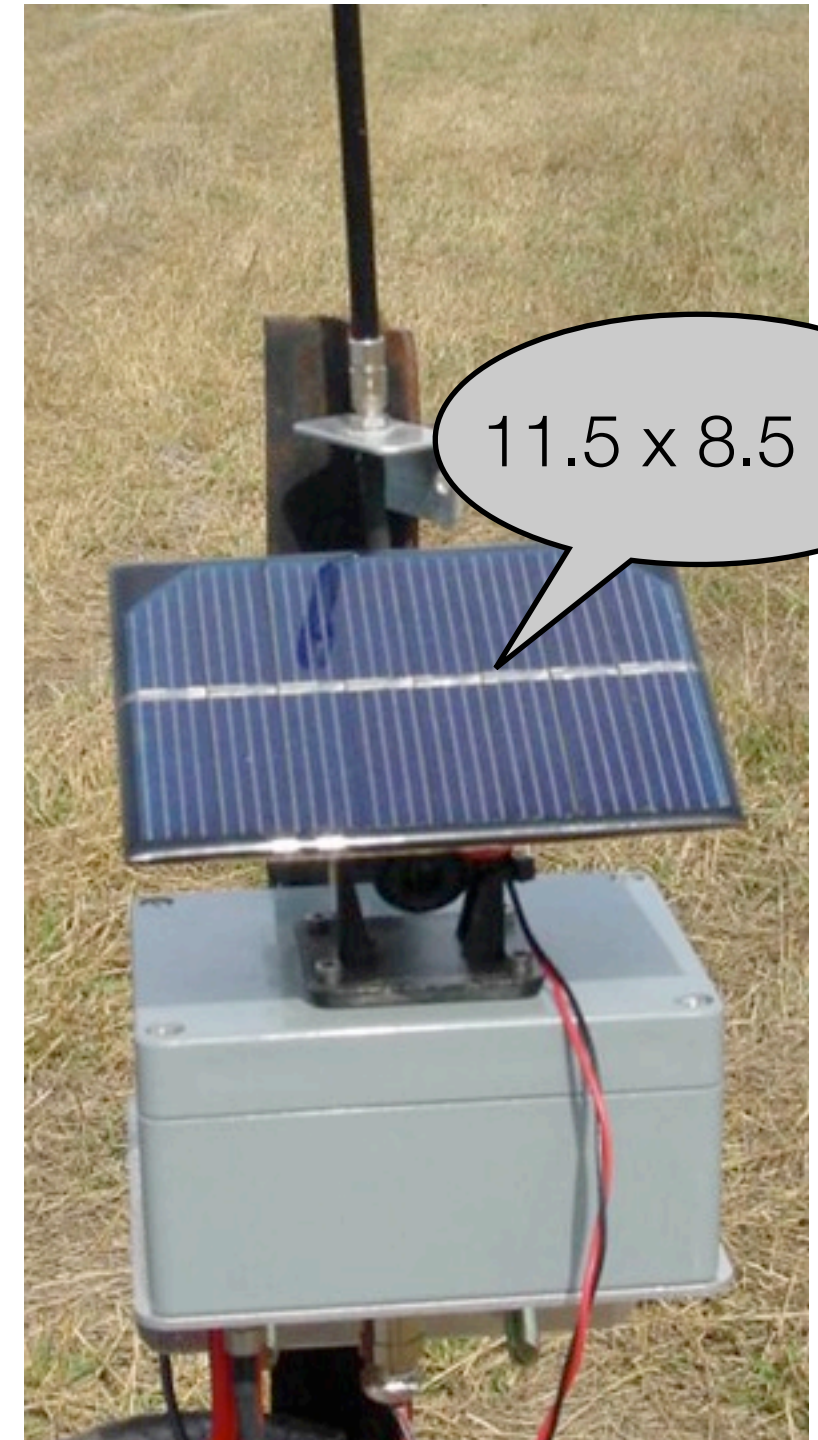
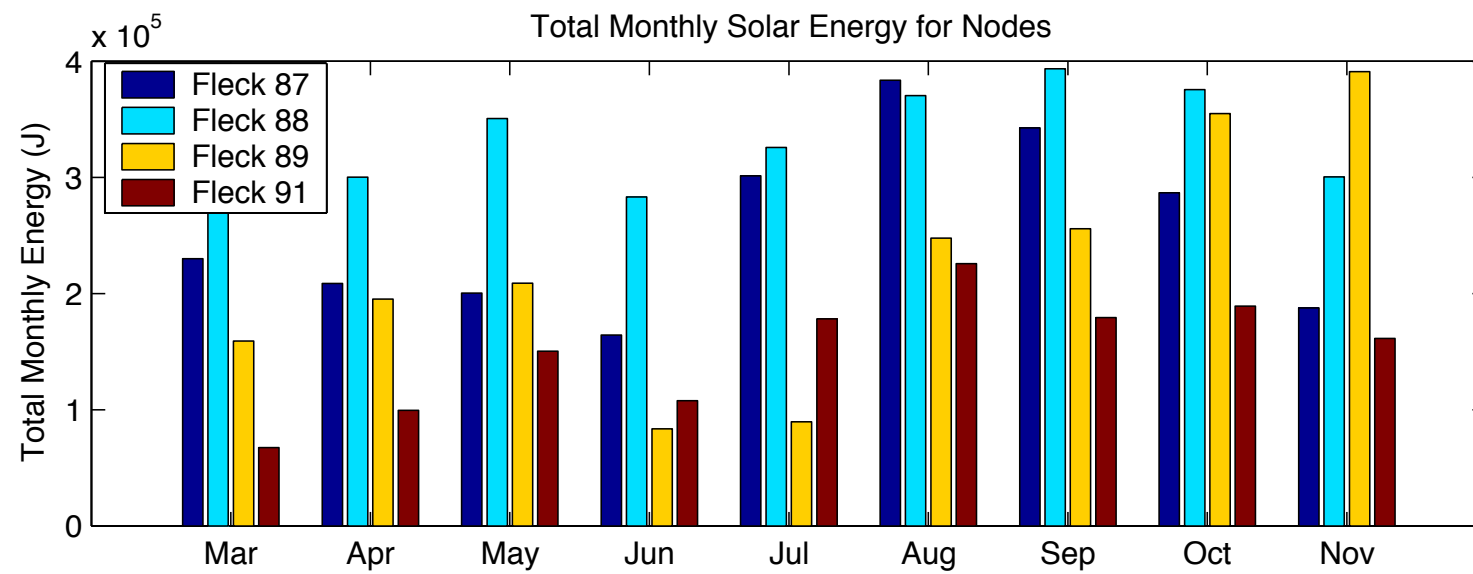
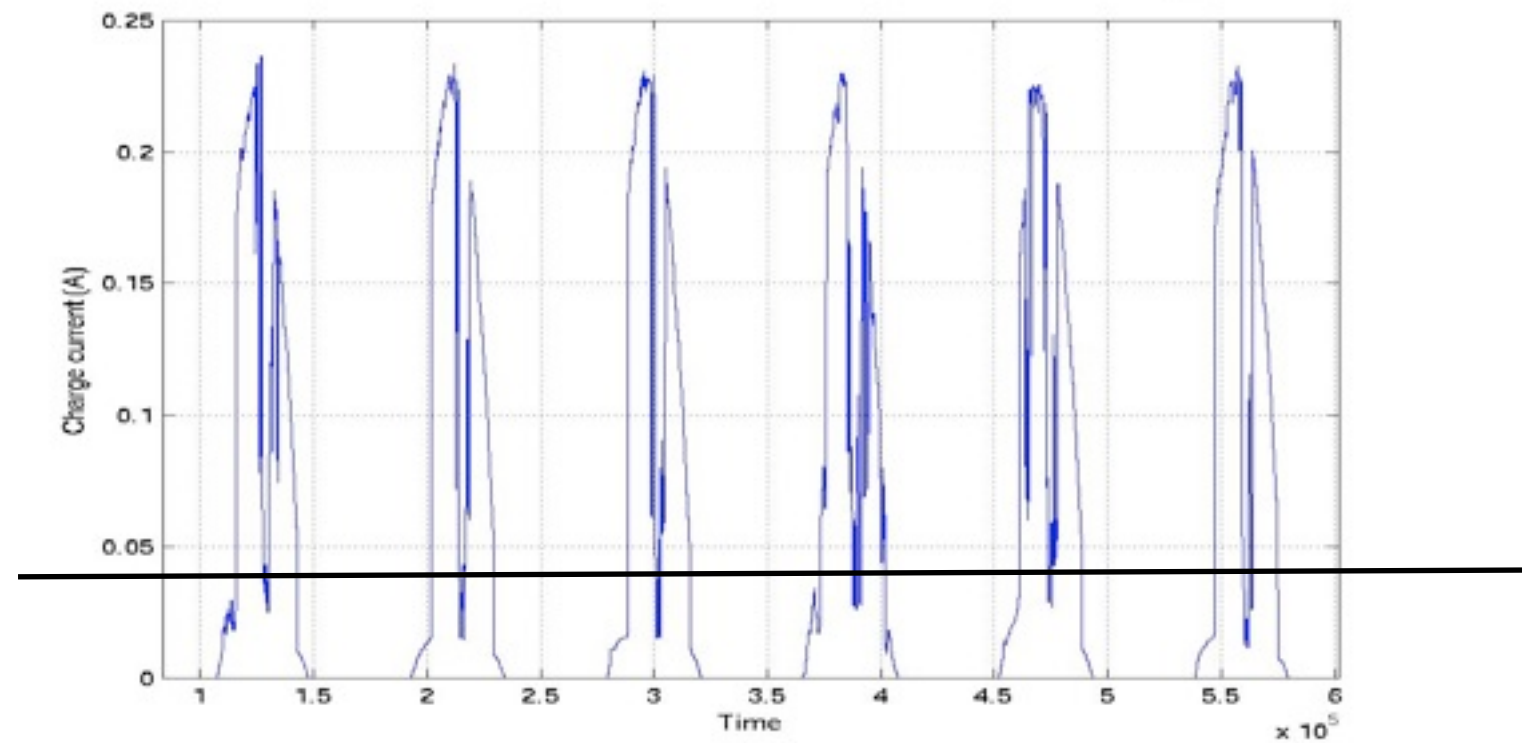
# It all begins with moisture in the ground...

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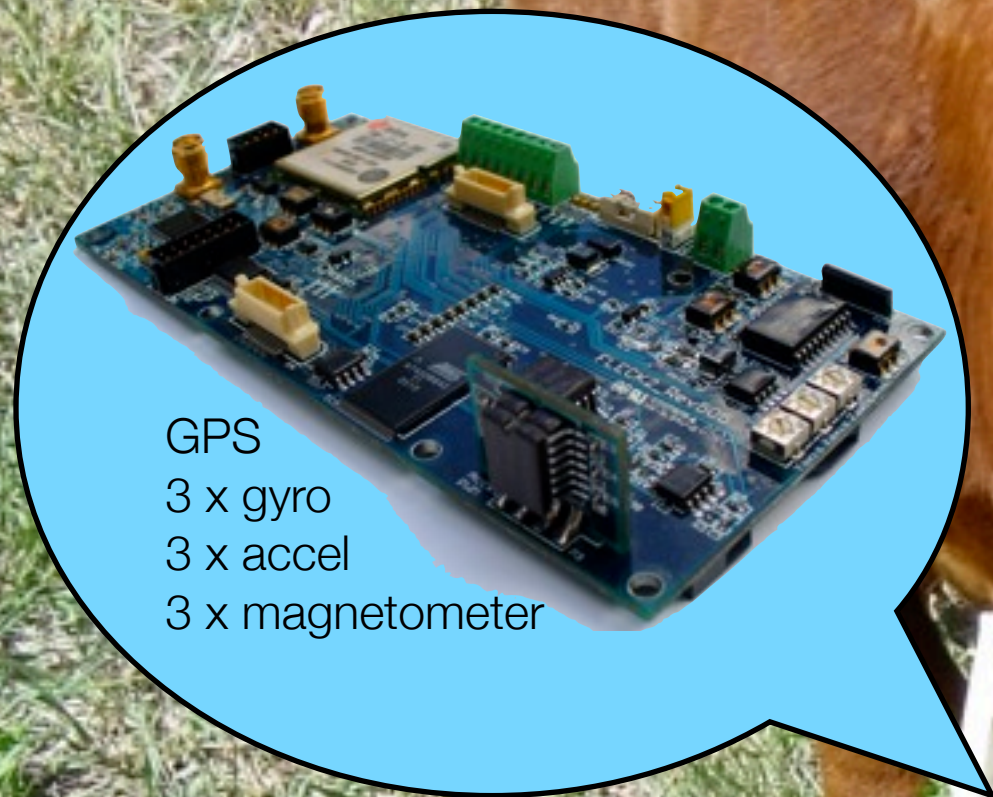




# Solar power supply







GPS  
3 x gyro  
3 x accel  
3 x magnetometer





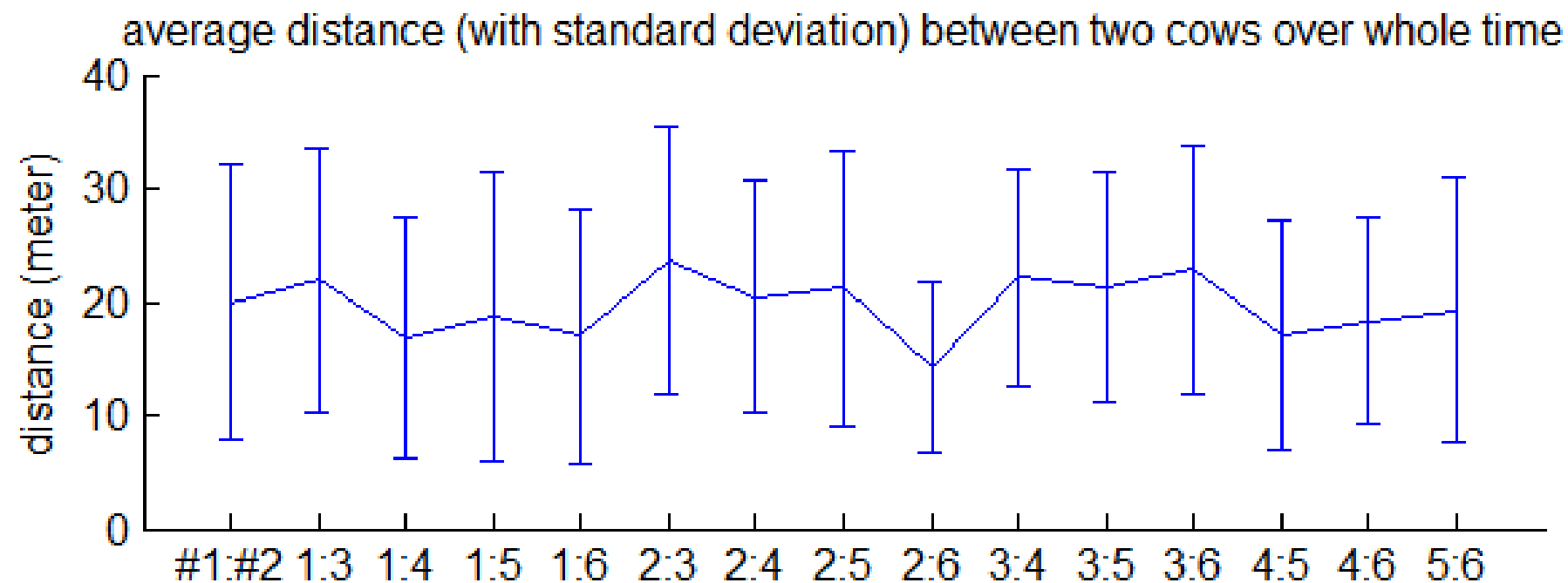
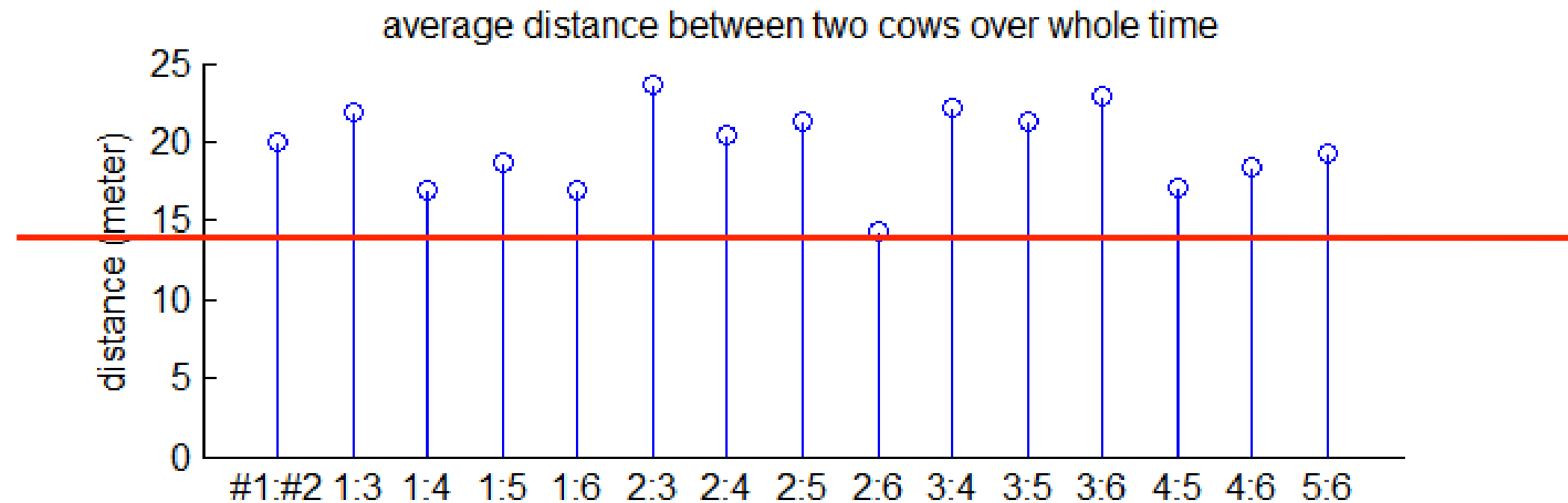
# Animal position

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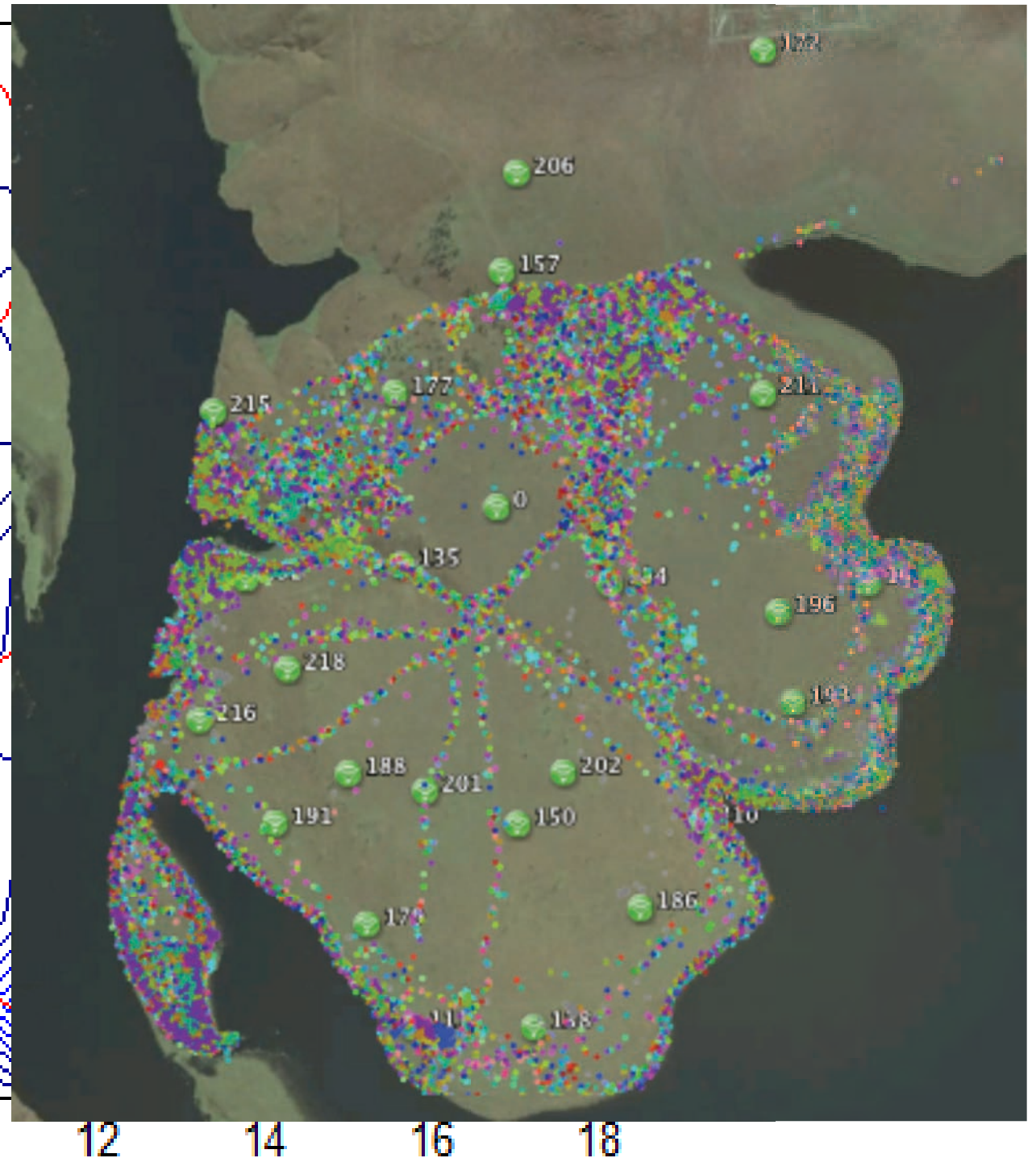
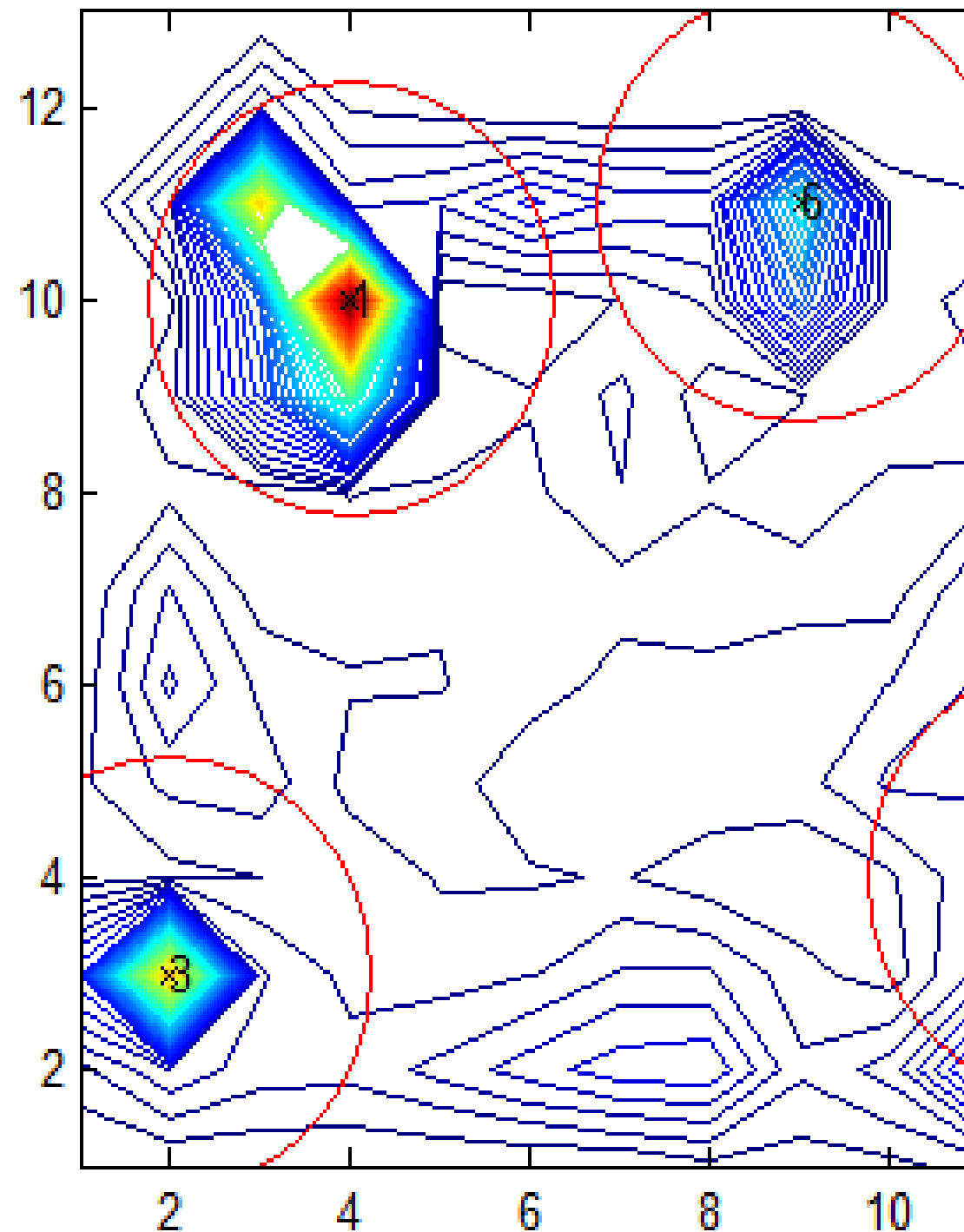




# Animal proximity

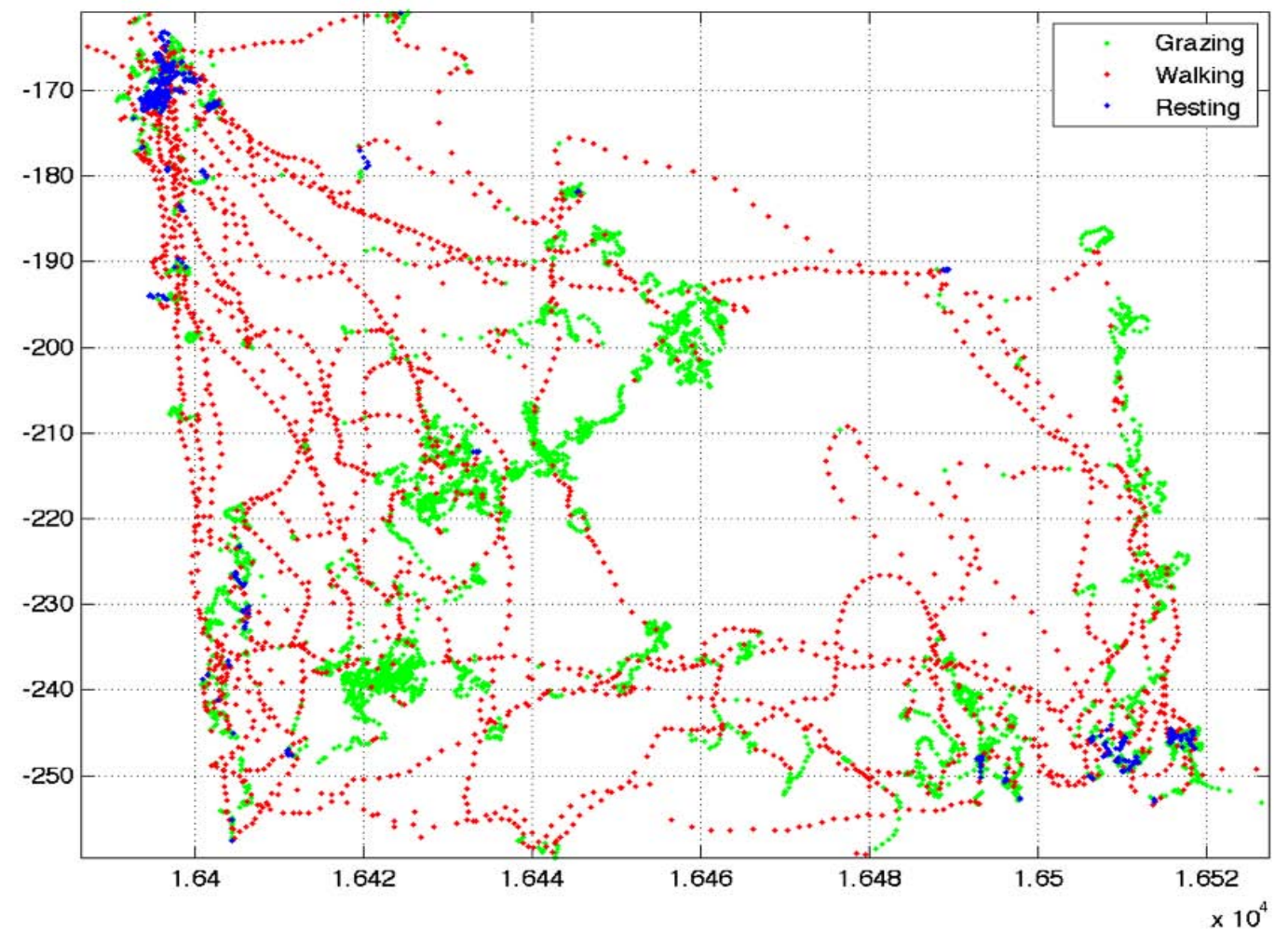
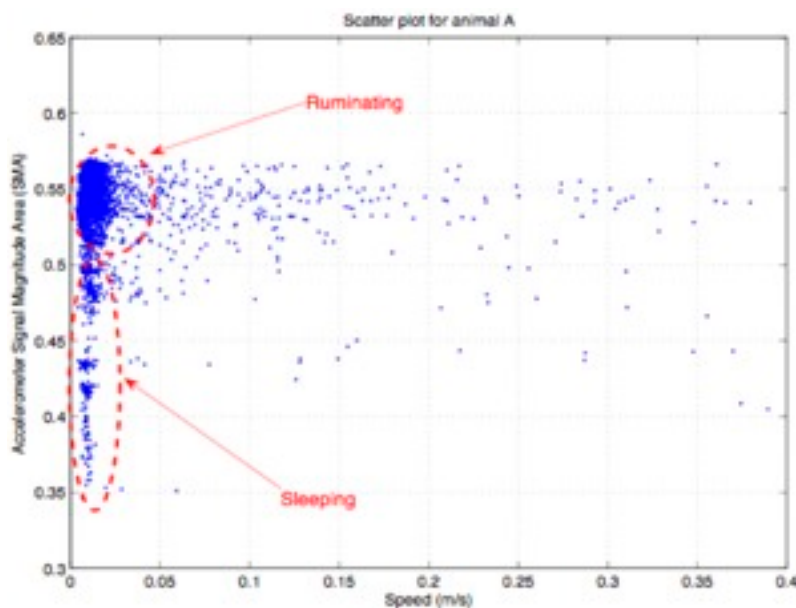
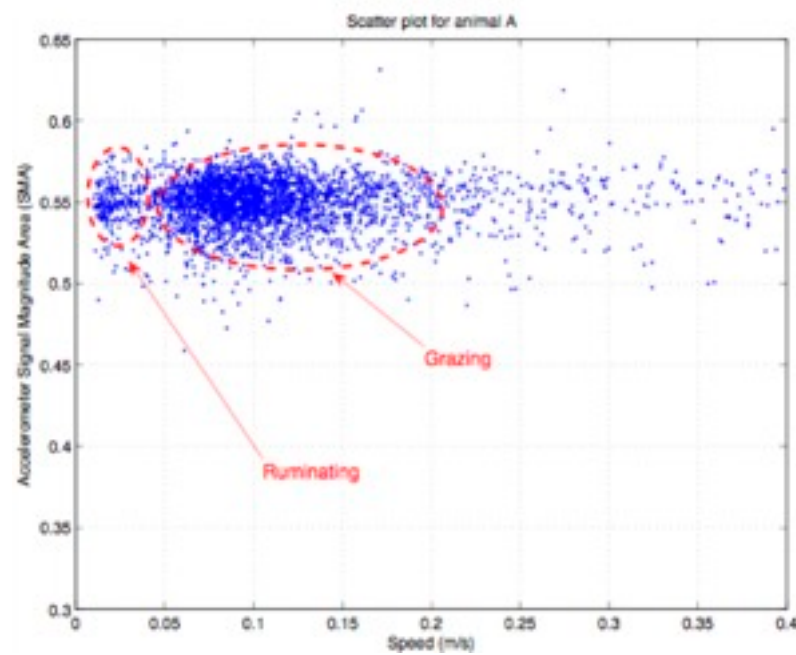


# Pasture utilization





# Spatial behaviour patterns

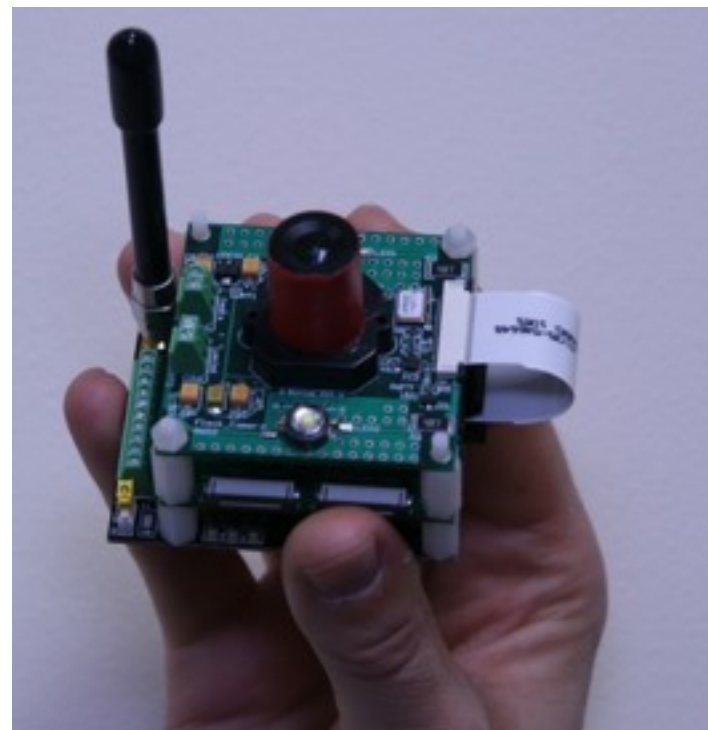


- New information for behavioural scientists
- Important information for new mobile routing protocols



# Can we see what's going on?

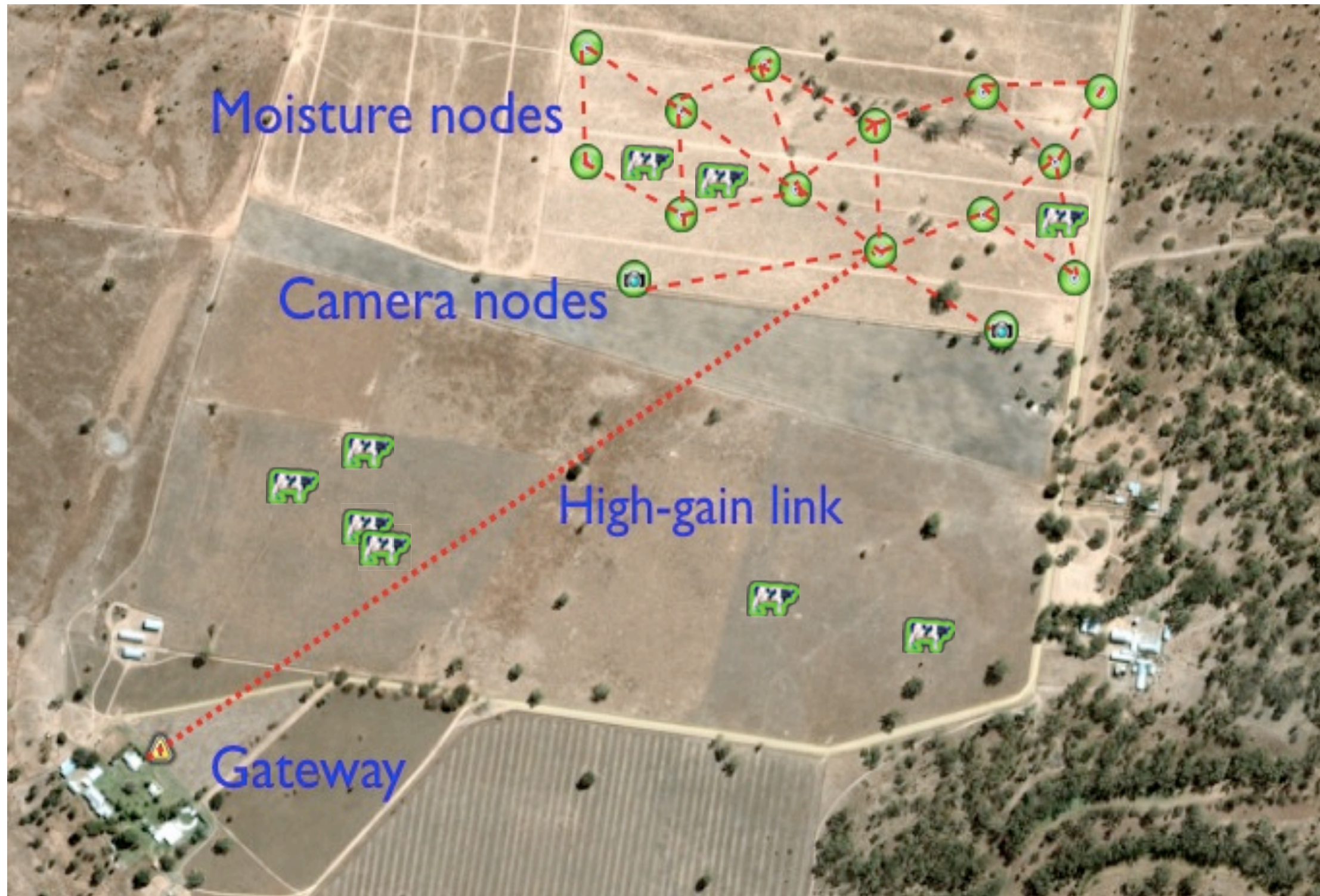
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# Farm sensor network

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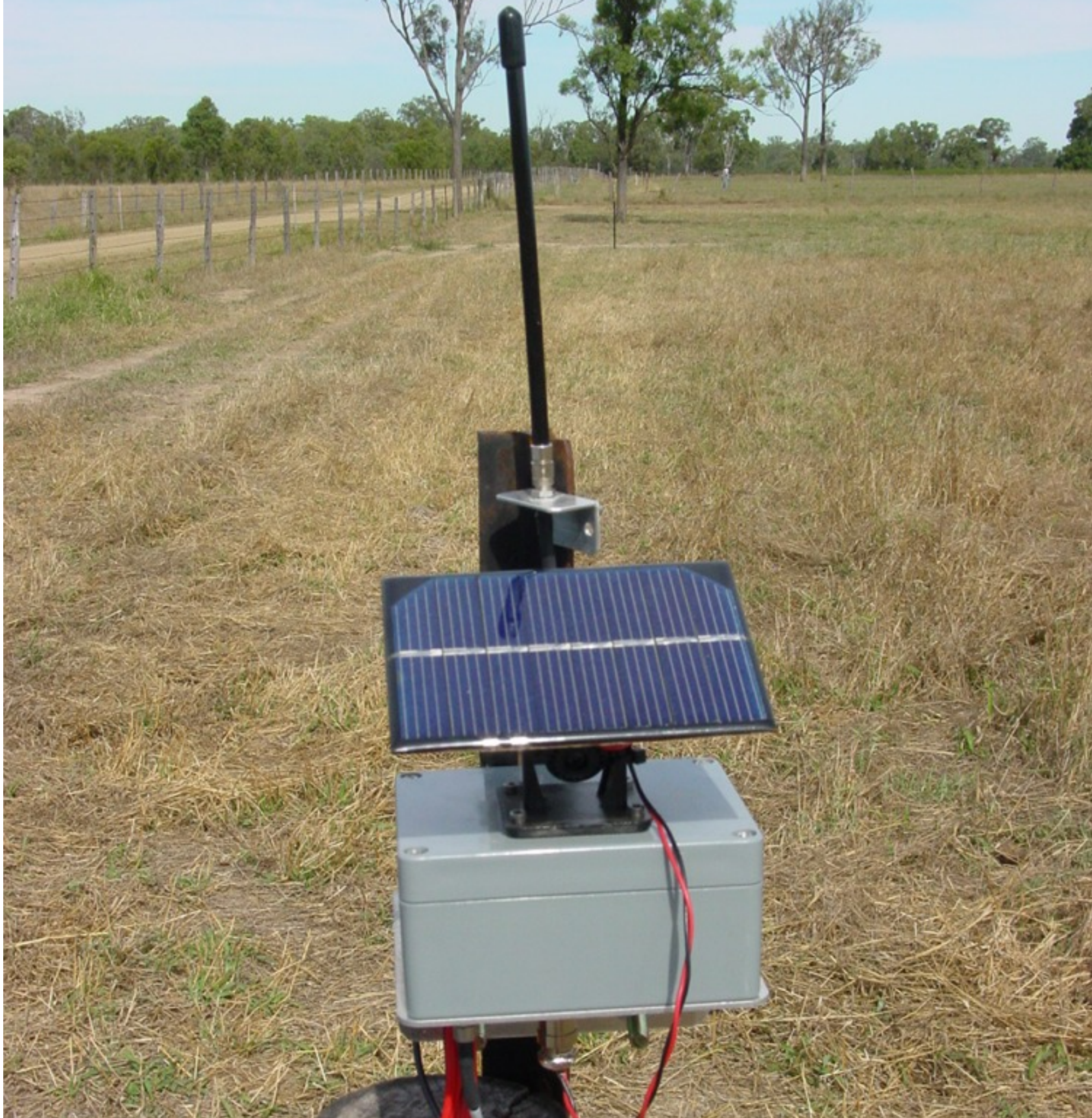


# Learnings

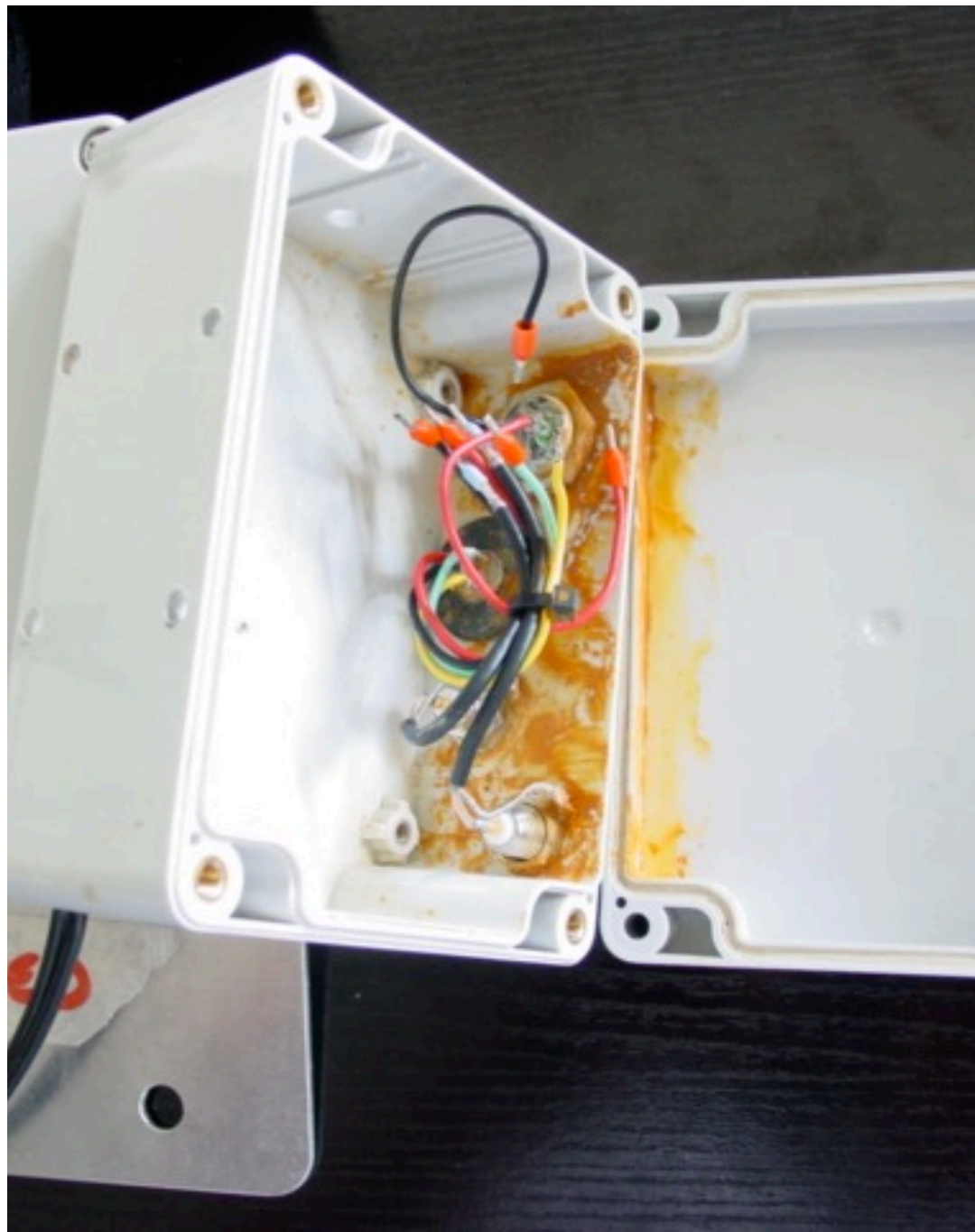
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- ZTDMA worked poorly
- Struggled to keep our TOS port up to date with trunk development
- Software productivity and reliability was low
  - distance
  - over the air reprogramming not adequate
- Environmental housings were inadequate
- Batteries ruined by overcharging

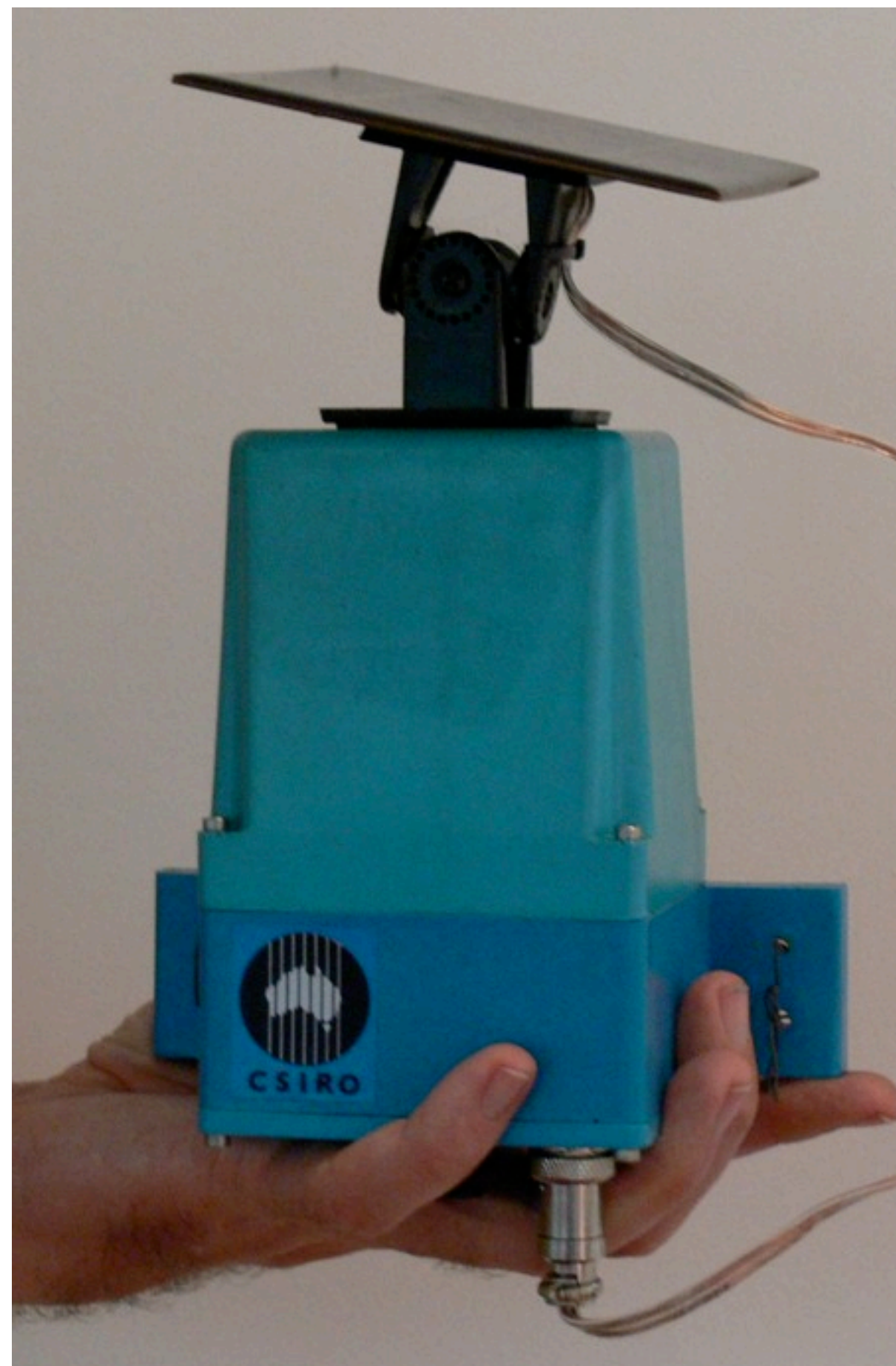
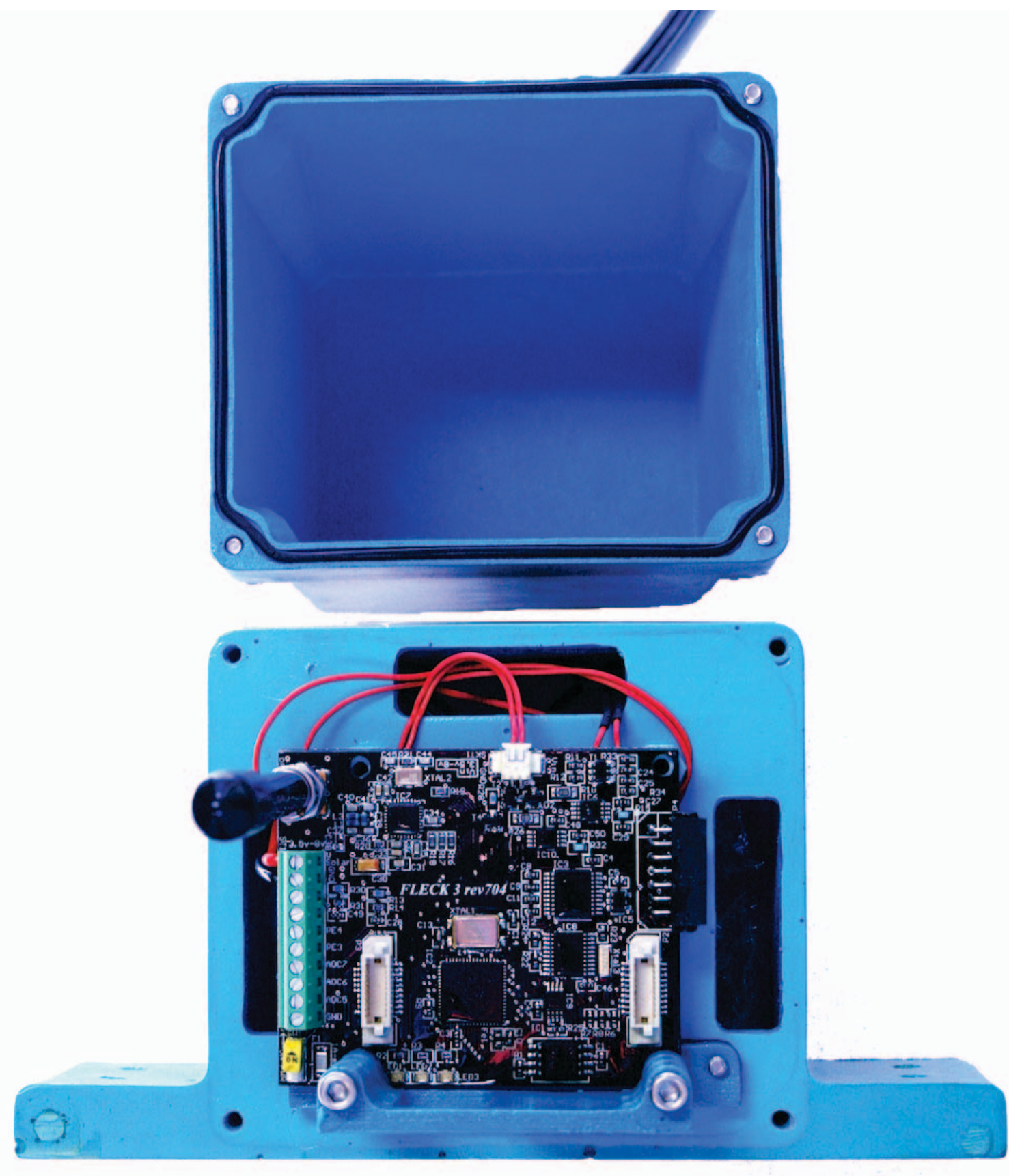




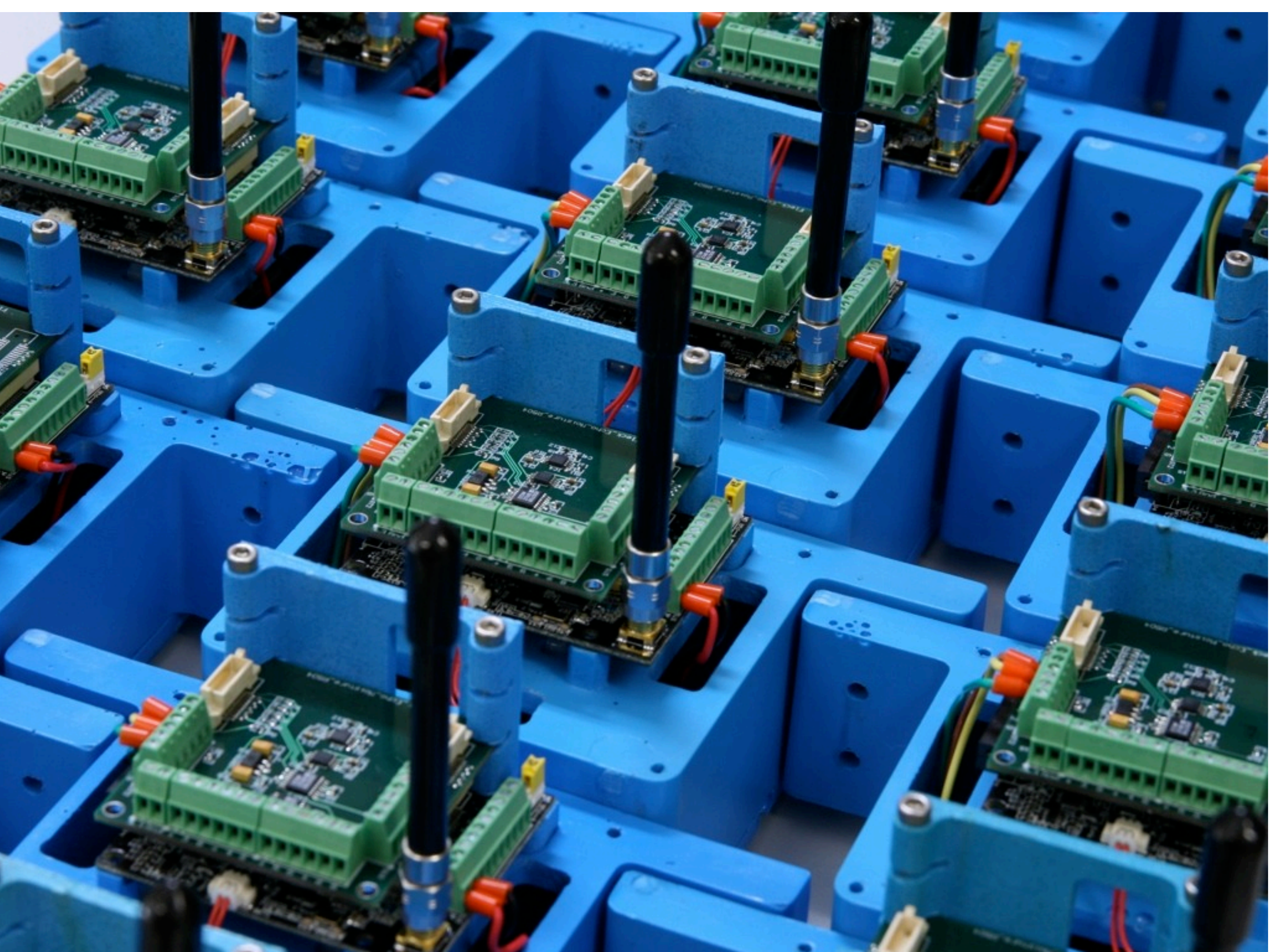










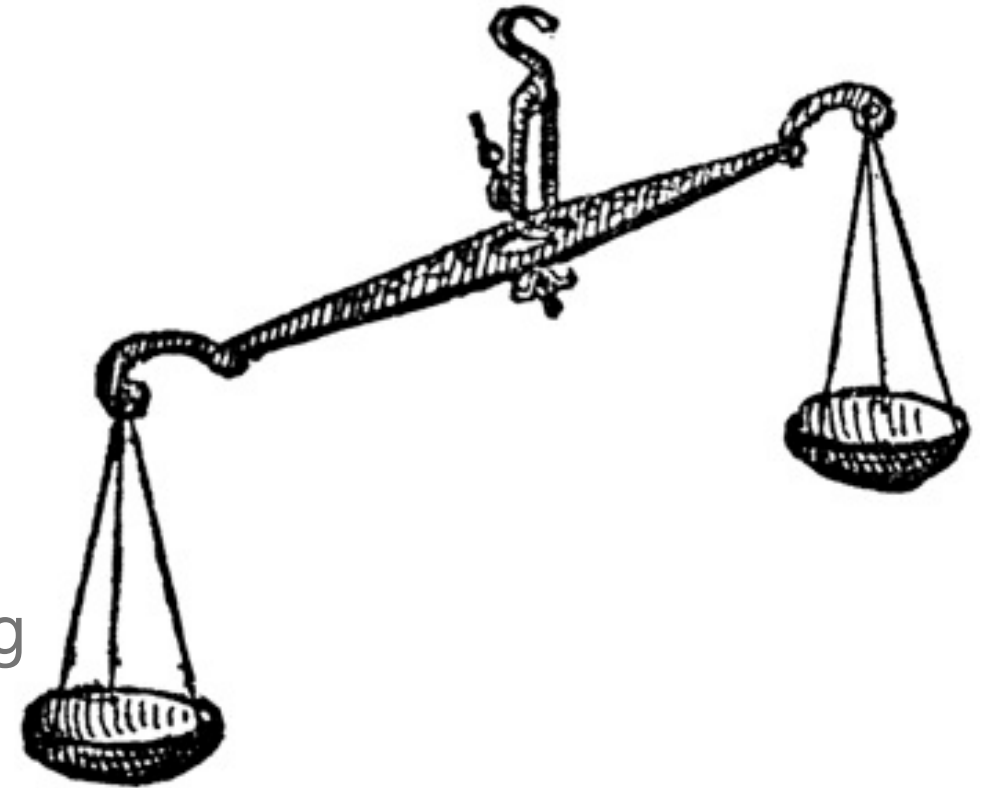




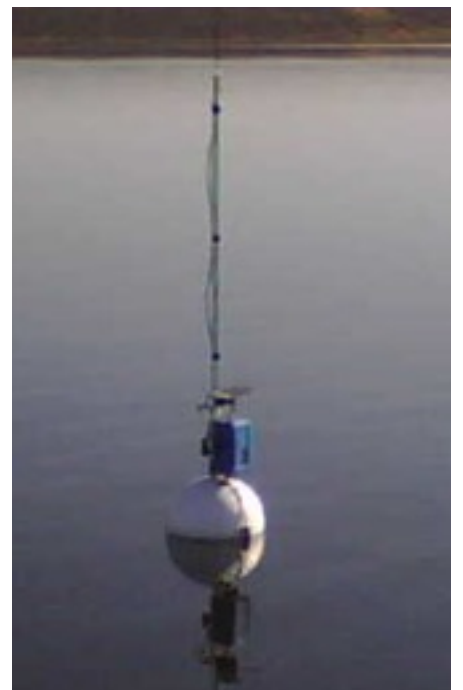
# Events vs threads...

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- What were we thinking ?
- Did we optimize the wrong thing?
- Memory size versus application development convenience
  - In the early days most people were developing small apps
  - Do we care about 1k vs 2k RAM usage if the chip has 4k RAM?
- We wrote our own tiny kernel with cooperative threading, static analyzer for thread sizing, crash dump analyzer etc.







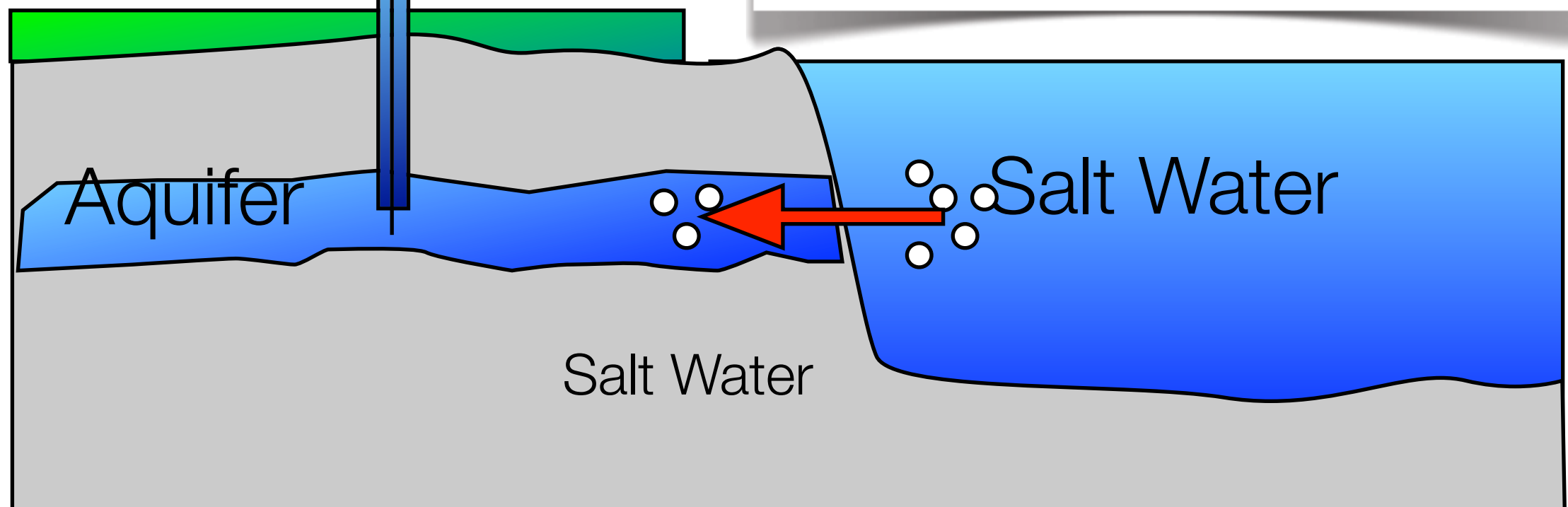
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Fleck1C	Fleck2	Fleck3	Fleck3	Fleck3	Fleck3



# Application: Salt Water Intrusion



Detect Salinity &  
Stop Pumping  
Pump Fresh





# Learnings

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- MintRoute worked well
- Radio survey is important.
  - Do the right radio survey!
- Channels really do vary (a lot!)
- An electrical storm can ruin an entire network











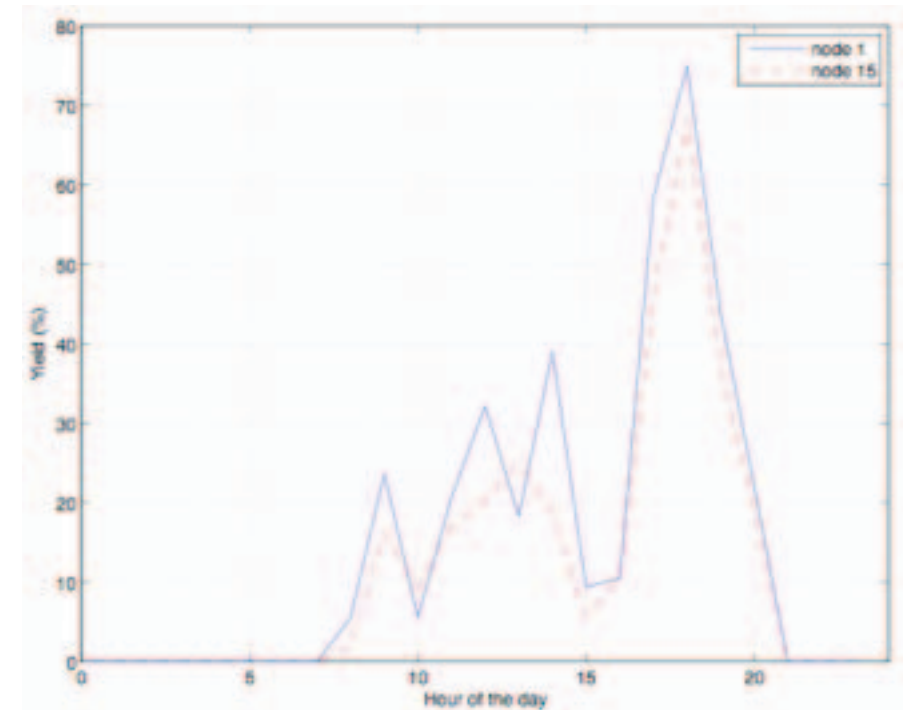
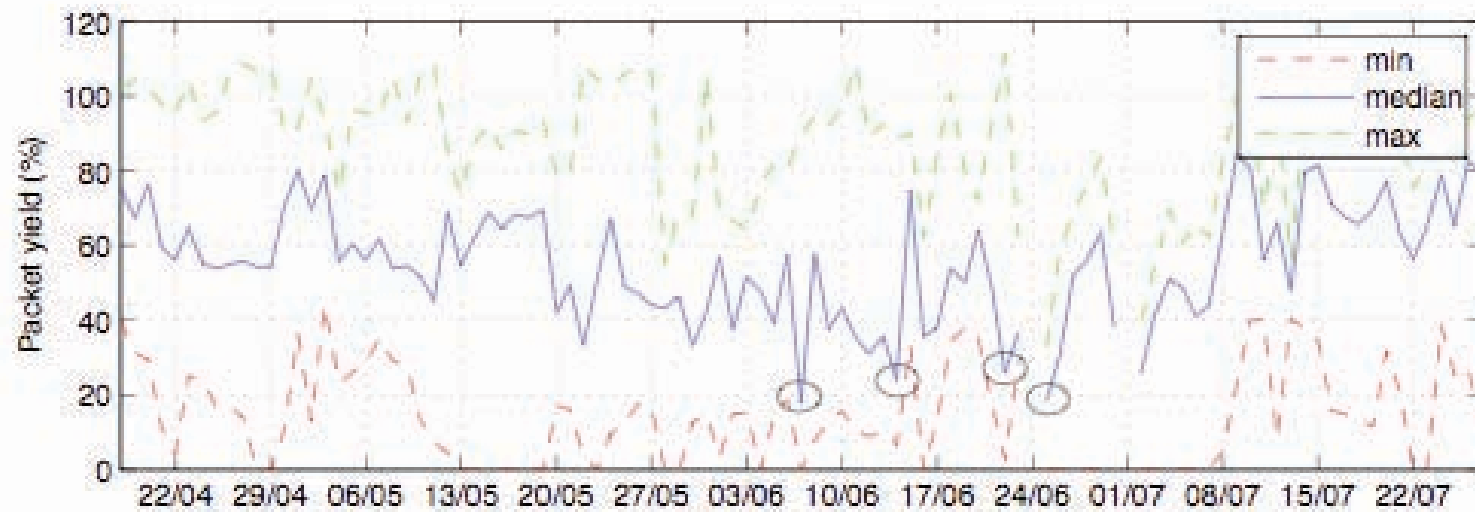
# Learnings

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# Temporal patterns in link performance



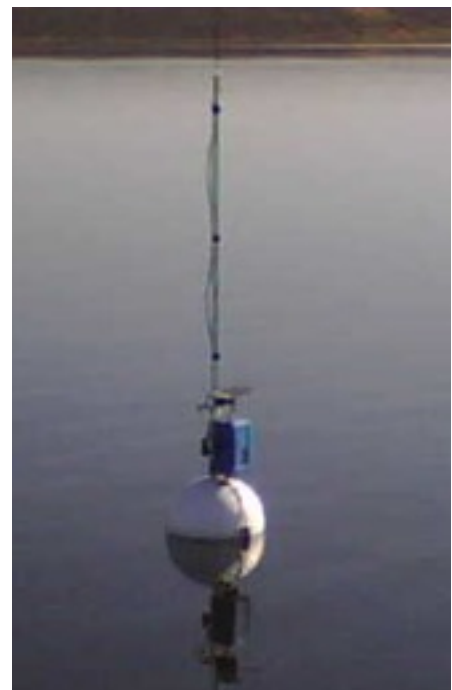


# Learnings

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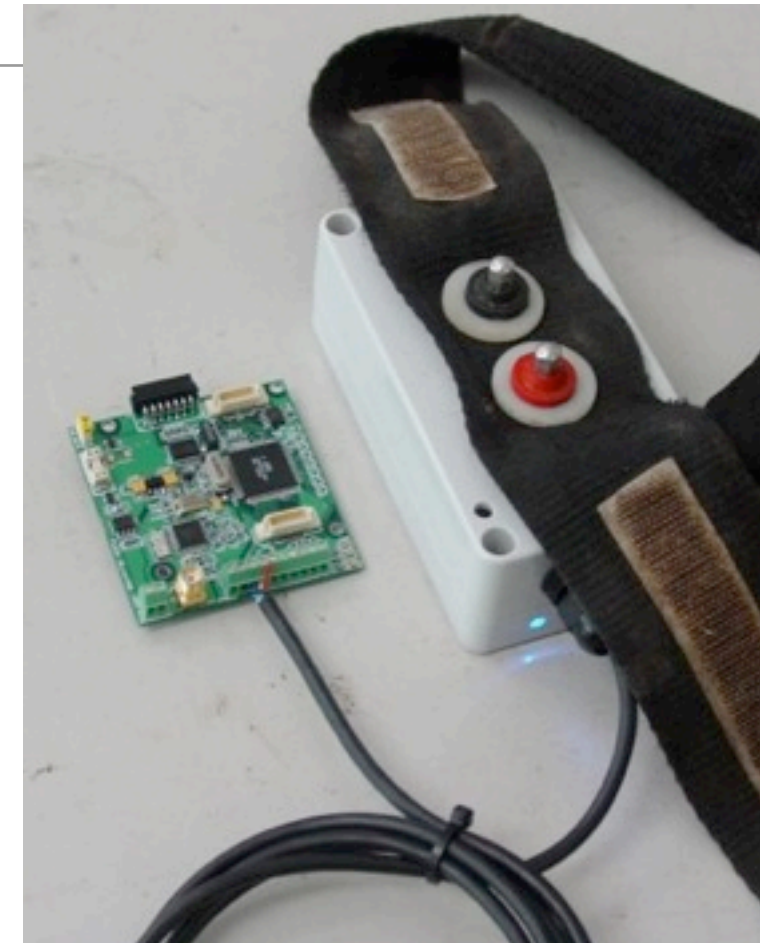
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Animal welfare studies monitored  
animal heartrate and stress hormones

# Animal control

- Exploit conditional learning
  - Cue (a sound)
  - Control (an electric shock)
    - Upto 1.5kV, cf. electric fences – 5kV
    - Like some dog collars





# Domain problem: Bull separation

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- Bulls are high value animals (up to \$100,000 each)
- Serious challenges in preventing bulls from injuring each other

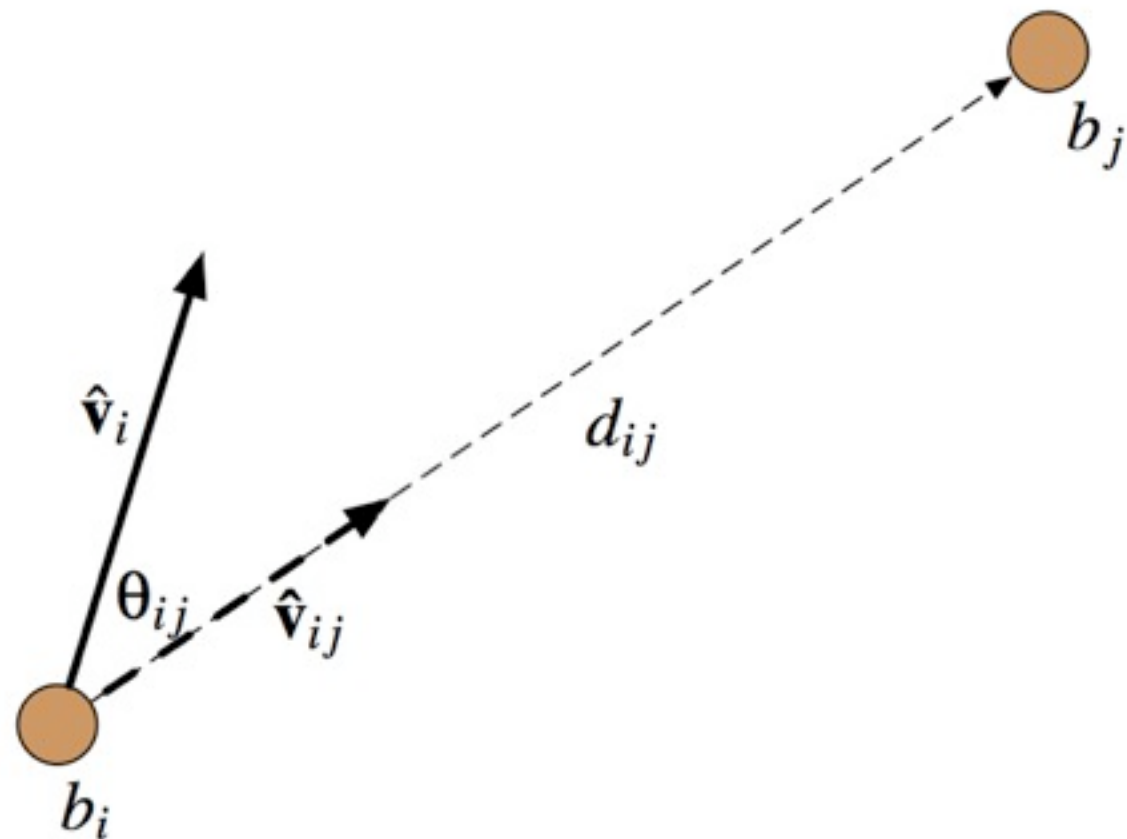




# On-board processing

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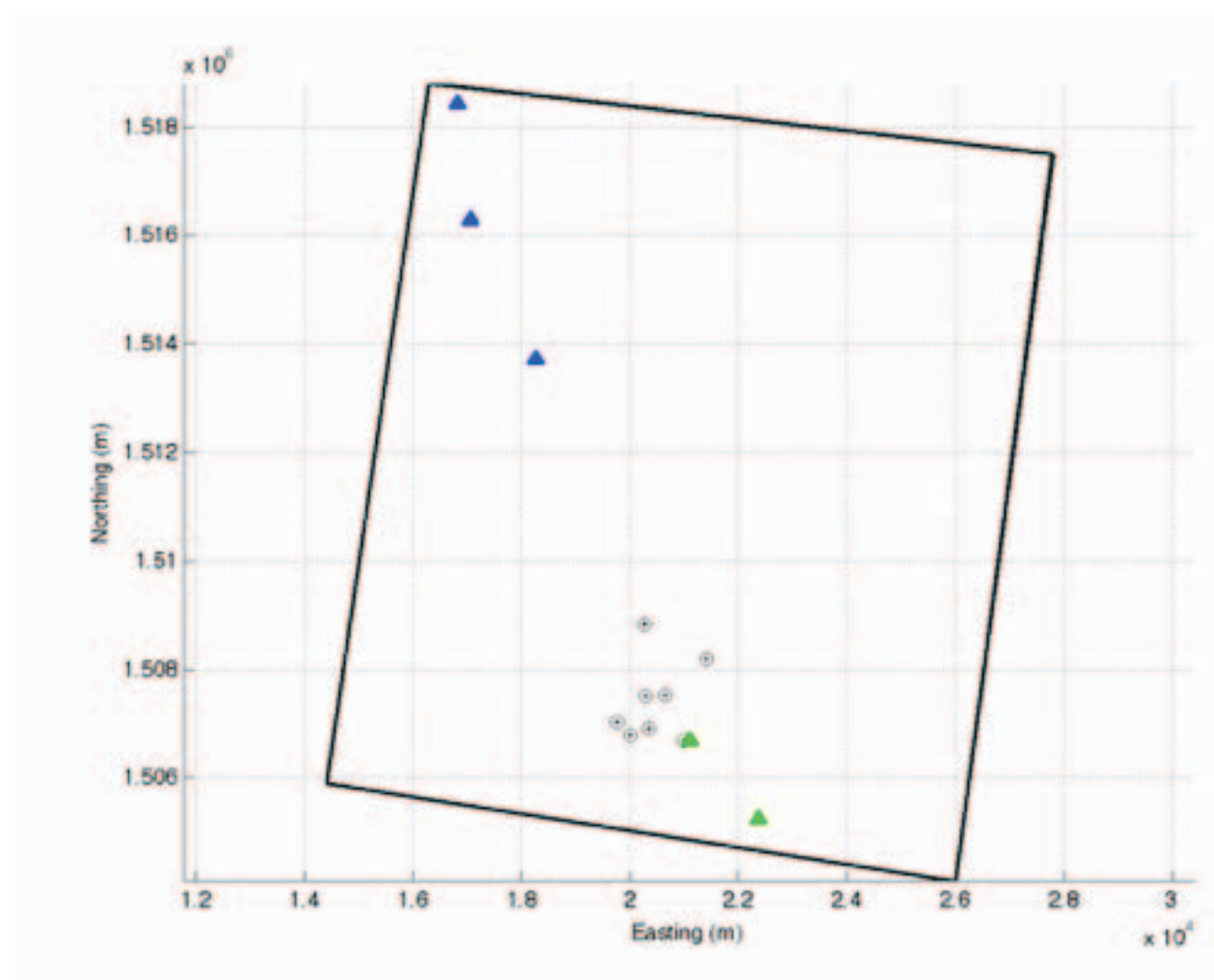
- Based on incoming beacons from other bulls and local information, each node can determine:
  - Distance from other bulls
  - Relative heading angle  $\theta$
  - Projected speed toward





# Bull separation

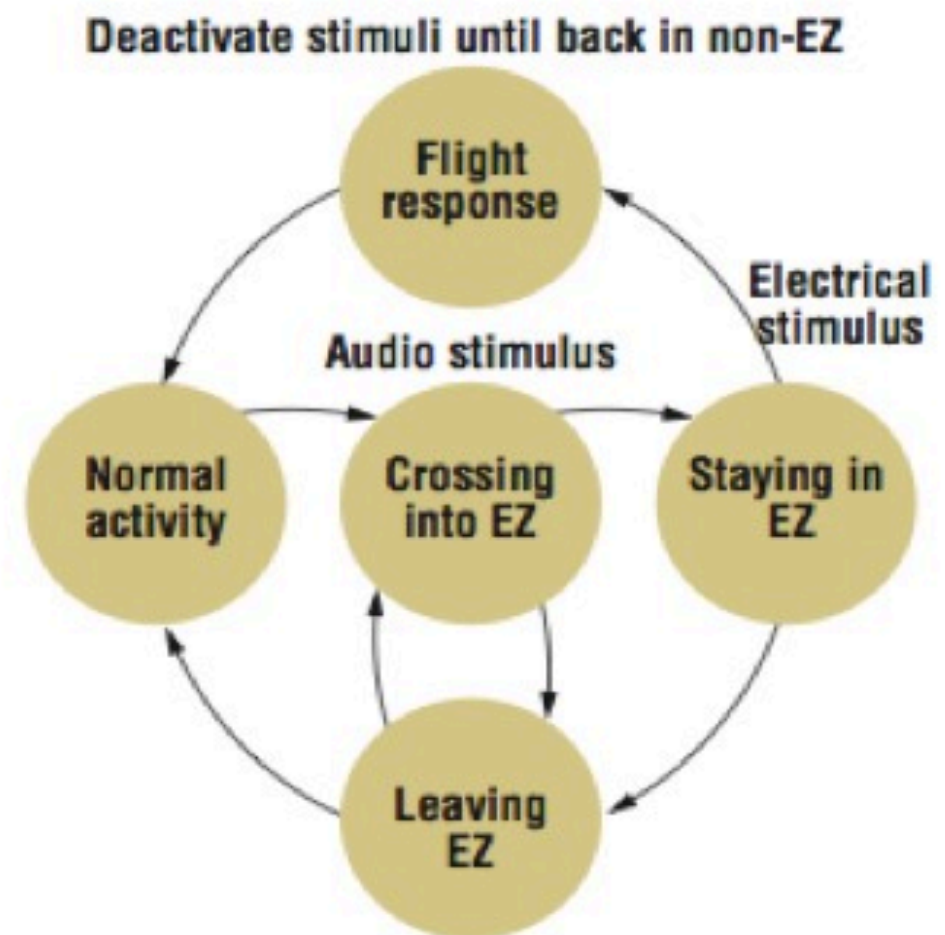
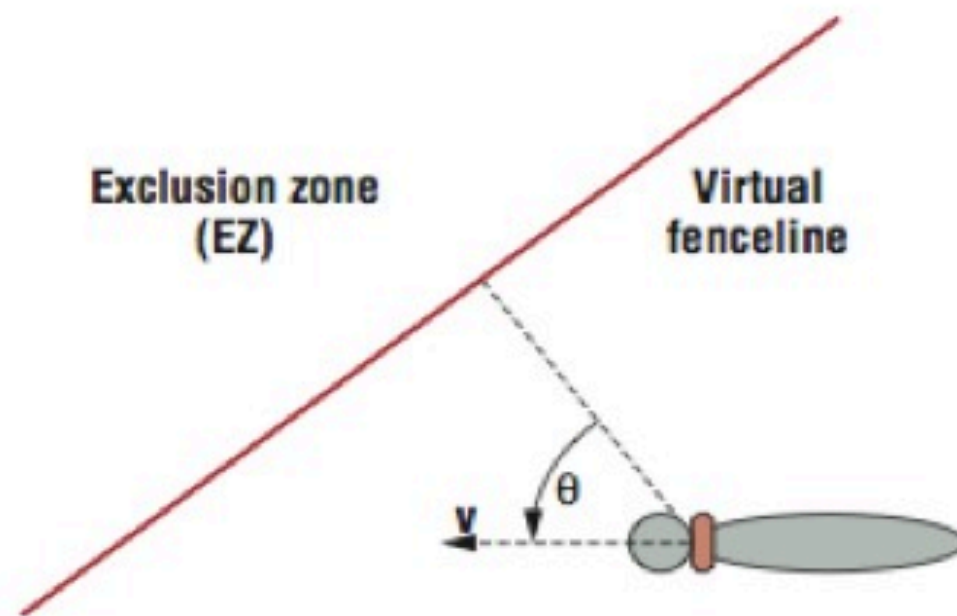
- Bulls in multi-sire paddocks fight and seriously injure each other
- Animal behaviour estimated by a peer-to-peer network
- Aversive stimulus applied to the aggressor





# Virtual Fencing: Environmental Protection

- State of animal relative to virtual fenceline is used for spatial animal control





# Virtual Fencing: Controlling spatial pasture utilization

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# Learnings

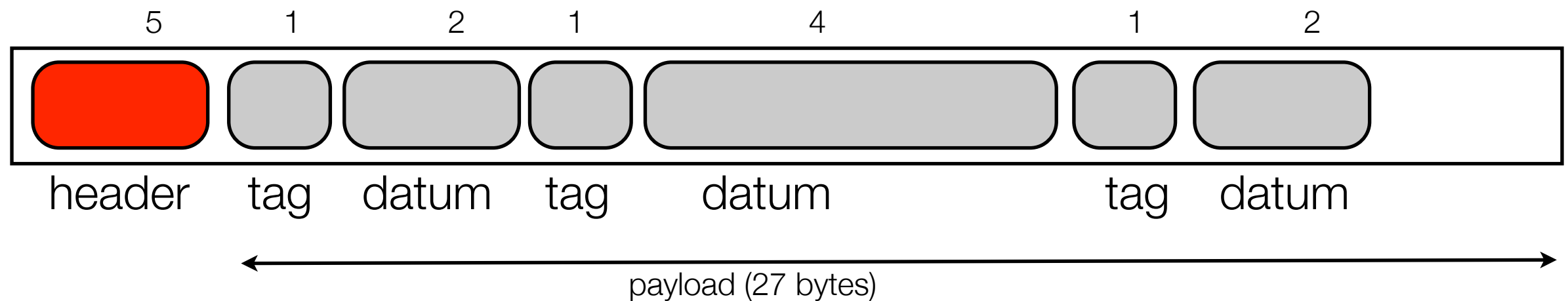
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- Changing hardware and software at the same time is painful
- Good enough networking
- Code balance was changing
  - 12,000 lines of kernel (in C)
  - 23,000 lines of support code (in Python)
  - RPCs were showing their value
- Message formats got out of control



# Self describing messages

---



## Fleck 3 radio message

```
#include "fos/tdf.h"

// update the packet payload

fos_tdf_clear();

fos_tdf_add_word(TDF_BATTERY_VOLTAGE, fos_power_battery_voltage() );
fos_tdf_add_word(TDF_BATTERY_CURRENT, fos_power_battery_current() );
fos_tdf_add_word(TDF_SOLAR_VOLTAGE, fos_power_solar_voltage() );

fos_tdf_flush();
```

# Remote procedure calls

```
1  ret = rpc.power();
2  ret = ret[0];    # note
3  print "battery    %.2fV" % (ret.vbattery/1000.0)
4  print "solar cell %.2fV" % (ret.vsolar/1000.0)
5  print "solar cell %.2fmA" % (ret.isolar/1000.0)
```

Internet connected client call

Node-based  
service

```
include "fos/power.h"

power(uint16_t vbattery, uint16_t vsolar,
      uint16_t isolar <= )
{
    vbattery = fos_power_battery_voltage();
    vsolar = fos_power_solar_voltage();
    isolar = fos_power_battery_current();

    return OK;
}
```

actions/power.rpc



# Some standard services

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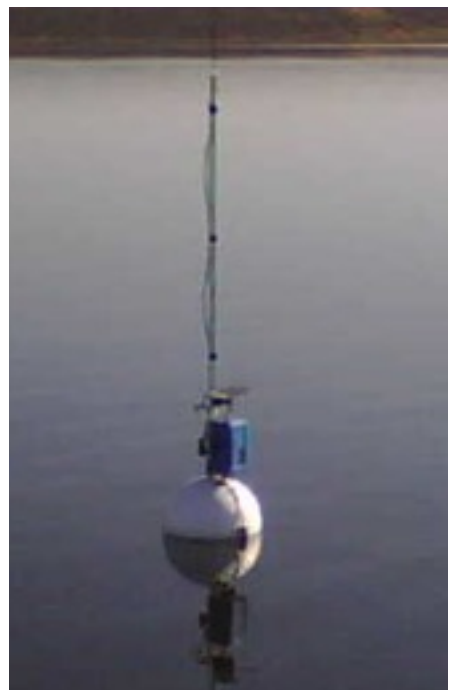
kernel	get FOS system memory statistics
leds	set or toggle LEDs
power	get battery and solar cell status
rtc_get	get time from the real-time clock
rtc_set	set the real-time clock
temp	get temperature from the onboard sensor
adc	return value from specified ADC channel
threads	get information about threads, label and stack usage
txpwr_set	set radio transmit power
reboot	reboot the node
read_eeprom	read from EEPROM
read_ram	read from RAM
write_eeprom	write to EEPROM
write_ram	write to RAM

# A simple shell

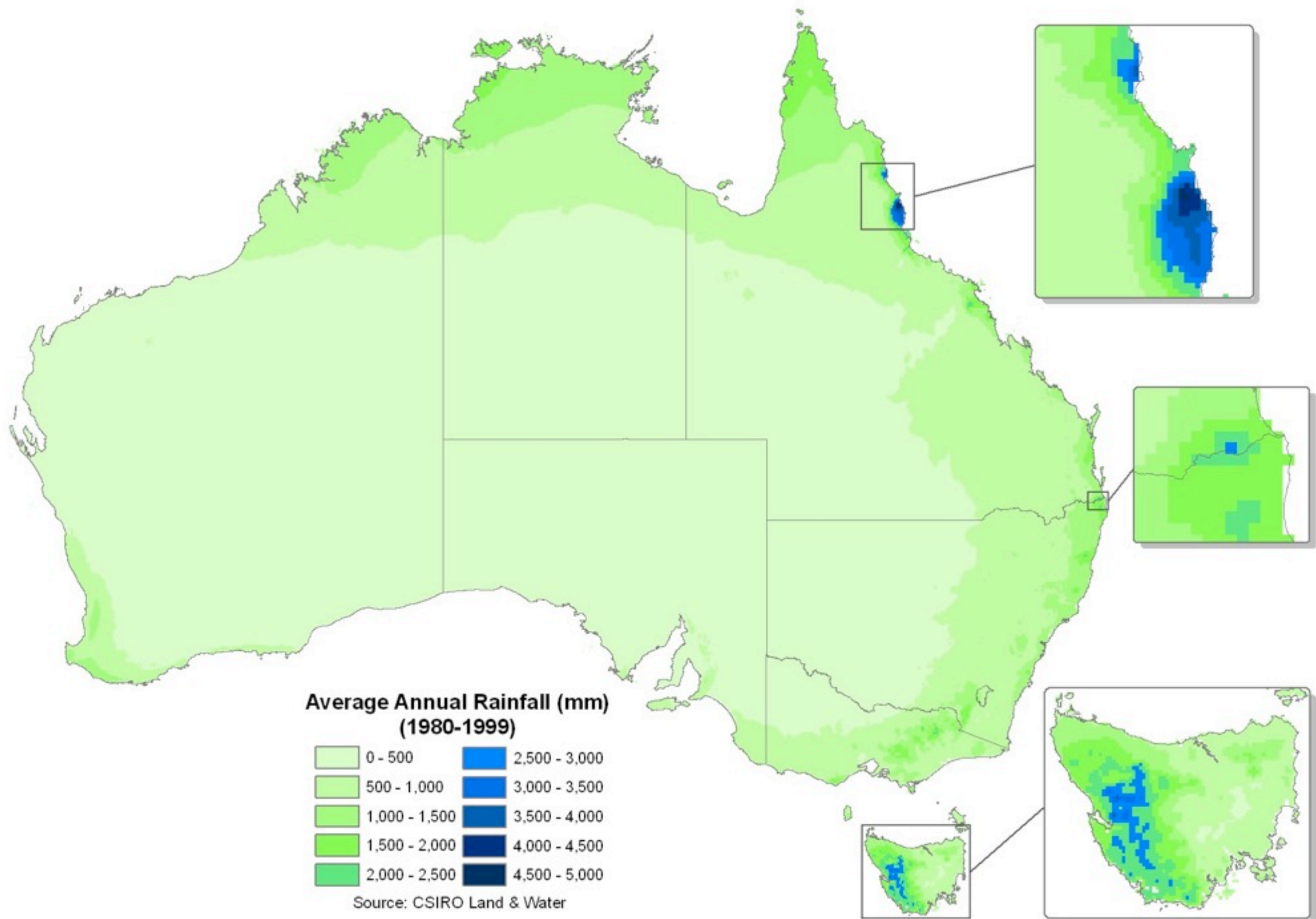
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```
1 ratbert % fosmon.py --addr 7
2 Connecting to listener localhost:9001 ...
3 Connected to node 7 (h for help)
4 fosmon@7 --> volts
5 battery      3.52V
6 solar cell   3.74V
7 solar cell   0.02mA
8 fosmon@7 --> temp
9 temp         29C
10 fosmon@7 --> mem
11 free memory 2875 bytes
12 fosmon@7 --> q
13 ratbert %
```





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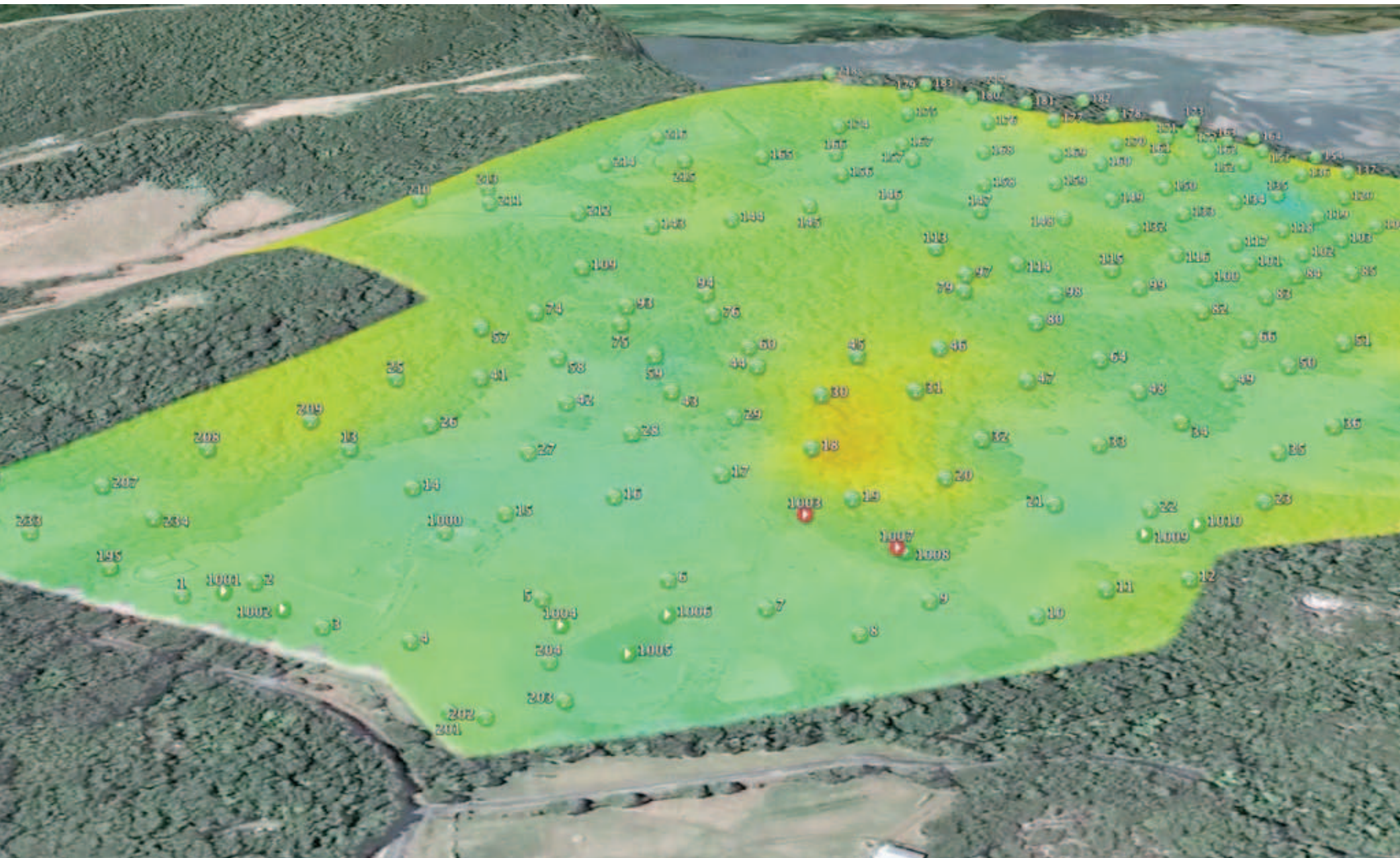




# Wireless Sensor Networks (Springbrook)





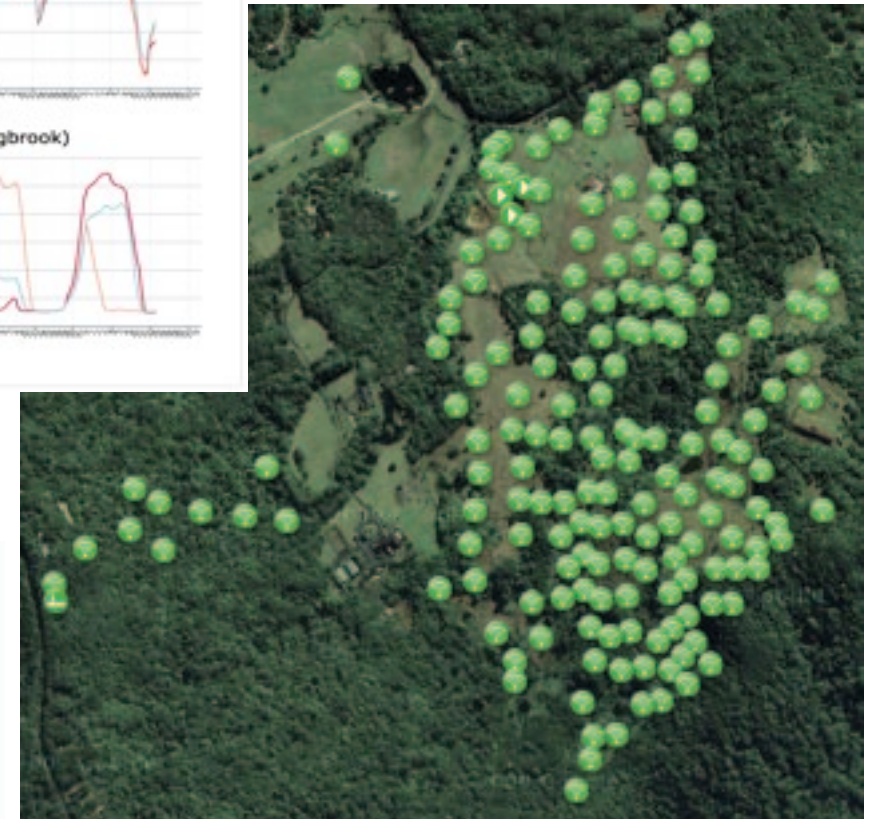
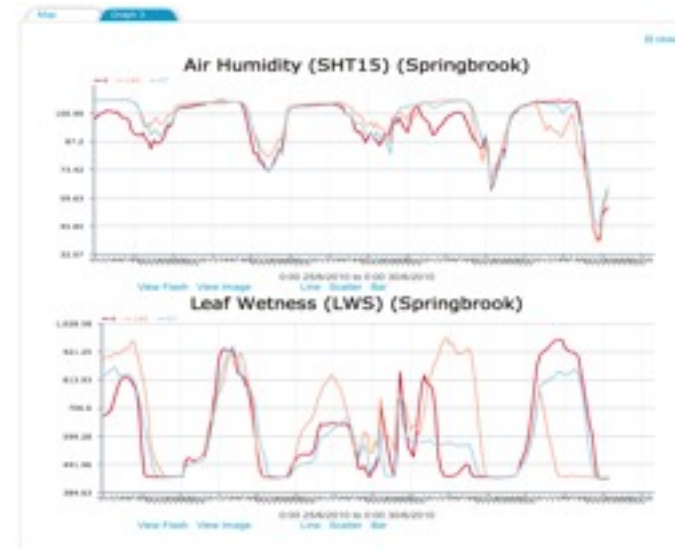


[www.sensornets.csiro.au](http://www.sensornets.csiro.au)



# Restoration Ecology - Springbrook

- 175 microclimate nodes
  - 642 environmental sensors
  - 5 min sample period
  - ~250,000 samples per day
- 10 “multimedia” nodes
  - Acoustic / image capture
  - Compute acoustic biodiversity metric



# Learnings

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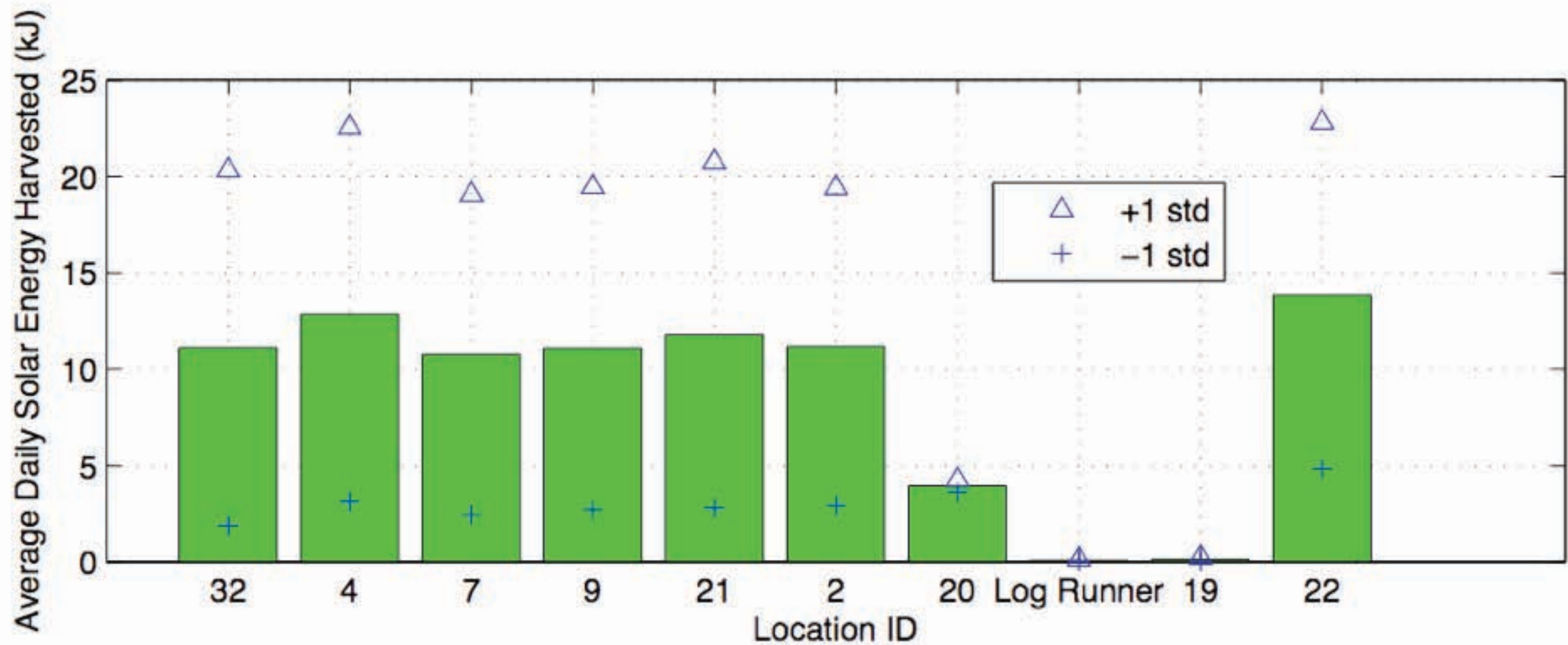
- Radio propagation is poor through dense wet forest
- Not much solar energy in a dense forest
- Is “deploy and forget” realistic or misguided?

*“Ubiquitous computing’s dream of wireless sensors everywhere is accompanied by the nightmare of battery replacement and disposal”*

*— Paradiso and Starner.*



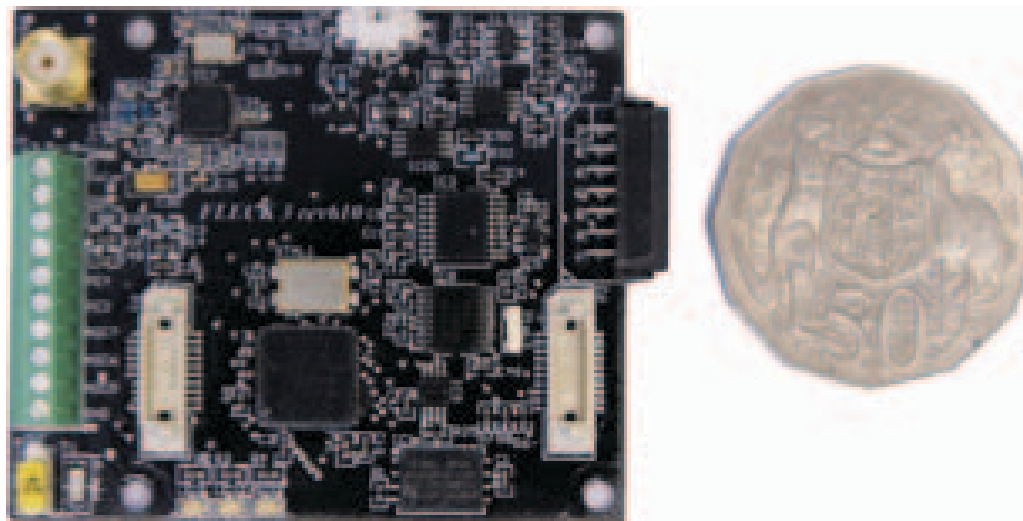
# Energy harvest



# Energy consumption

- “Traditional” Wireless Sensor Network (WSN) node:

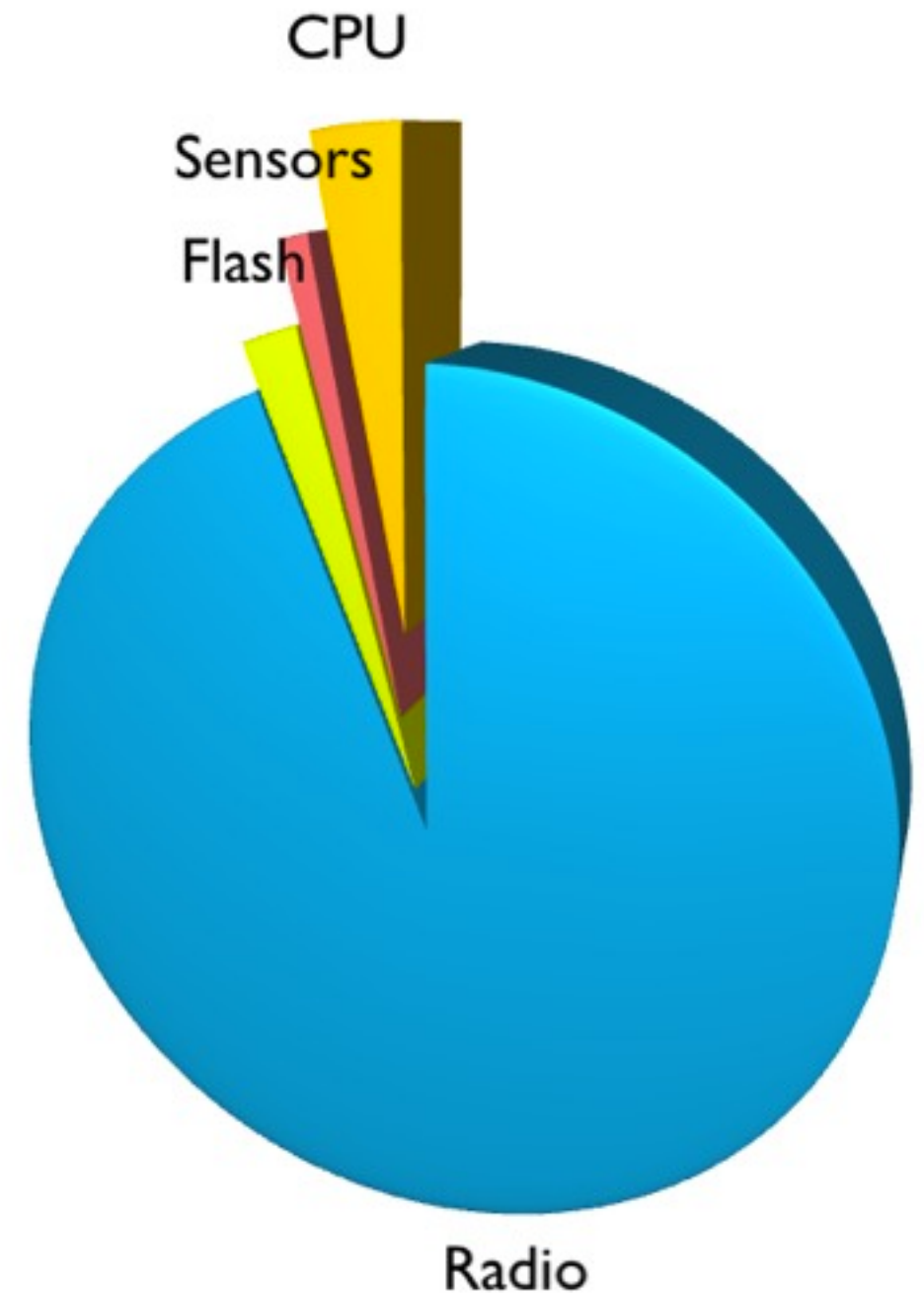
- Sample-and-send operation
- Low-power sensors (e.g. temp/humidity)



“Mote” class device

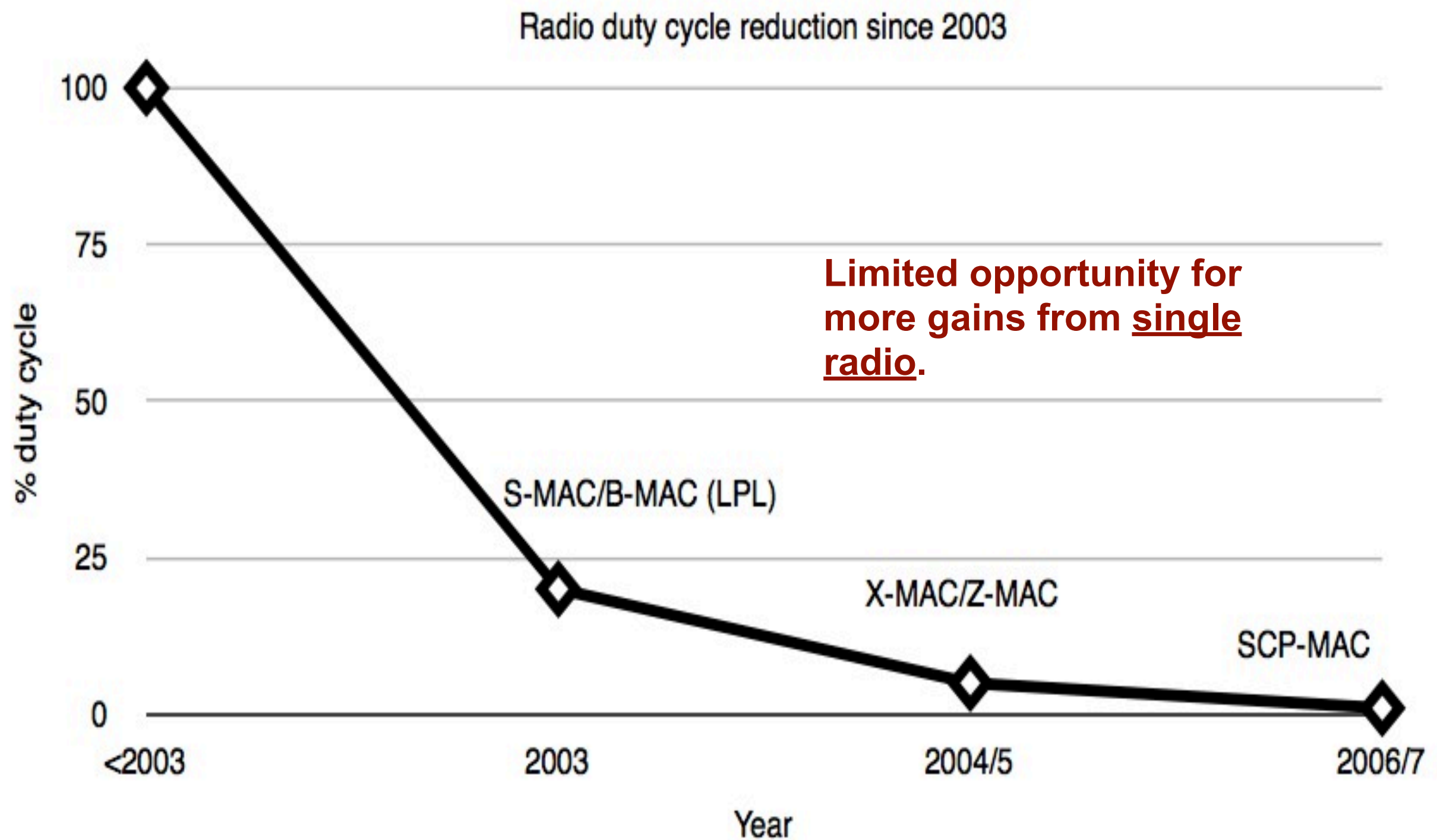
- Key research question:

- How can we significantly **reduce energy** being consumed by **radio**?





# Duty-cycle radio



# Learnings

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- Radio propagation is poor through dense wet forest
- Not much solar energy in a dense forest
- Is “deploy and forget” realistic or misguided?



# Security

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- The thing we never speak of...
- Issues
  - Confidentiality
    - ➡ message content is private
  - Identity
    - ➡ we really know who sent it
- Symmetric cyphers are cheap, but have the key exchange problem
- Asymmetric (public key) cyphers are expensive (to achieve strength)

# Exploiting commodity crypto technology



- Cheap: cost < USD4.5
- Small: 6.1 × 9.7 mm, less than 2% of area of Fleck

```
1  /* trustedFleck public key collector. */
2  uint8_t fos_tpm_getPubKey(uint8_t *pubKey);
3
4  /* Asymmetric key encryption/decryption. */
5  uint8_t fos_tpm_encryption(uint8_t *msg, uint16_t len,
6                             uint8_t *pubKey, uint8_t *cipher);
7  uint8_t fos_tpm_decryption(uint8_t *cipher, uint8_t *msg,
8                             uint16_t *len);
9
10 /* Digital signature and verification. */
11 uint8_t fos_tpm_sign(uint8_t *digest, uint8_t *signature);
12 uint8_t fos_tpm_verifySign(uint8_t *signature, uint8_t *pubKey,
13                             uint16_t *digest);
14
15 /* Symmetric session key encryption/decryption. */
16 uint8_t fos_xtea_encipher(uint8_t *msg, uint8_t *key,
17                             uint8_t *cipher, uint8_t nRounds);
18 uint8_t fos_xtea_decipher(uint8_t *cipher, uint8_t *key,
19                             uint8_t *msg, uint8_t nRounds);
20
21 /* Symmetric session key retrieve and store*/
22 fos_xtea_getkey(uint8_t *key, uint8_t location);
23 fos_xtea_storekey(uint8_t *key, uint8_t location);
```



# Evaluation (1)

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Table I. Comparison of RSA Encryption Times

Public Exponent ( $e$ )	Software 1024 bits	Software 2048 bits	Hardware 2048 bits
3	0.45 s	65 s	N/A
65,537	4.185 s	450 s	0.055 s

Table II. RSA Computation Time in TrustedFleck for  
 $e = 65,537$  and 2048 Bit Key

Encryption	Decryption	Sign	Verification
55 ms	750 ms	787 ms	59 ms

# Evaluation (2)

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**Table 4.** secFleck (RSA and XTEA) encryption energy consumption for *one bit* of data.

Platform	Current (mA)	Time ( $\mu$ s)	Energy ( $\mu$ J)
RSA (software, $e = 65,537$ , 2048 bit key)	8.0	219,730	7,030.0
RSA (hardware, $e = 65,537$ , 2048 bit key)	50.4	27	5.4
XTEA (software, 128 bit key)	8.0	18	0.6

- [1] W. Hu, H. Tan, P. Corke, W. C. Shih, and S. Jha, “Towards trusted wireless sensor networks,” *ACM Trans. Sensor Networks*, vol. 7, no. 1, pp. 1–25, 2010.
- [2] W. Hu, P. Corke, W. C. Shih, and L. Overs, “secFleck: A public key technology platform for wireless sensor networks,” in *Wireless Sensor Networks, 6th European Conference (EWSN)*, pp. 296–311, 2009.



# More challenges

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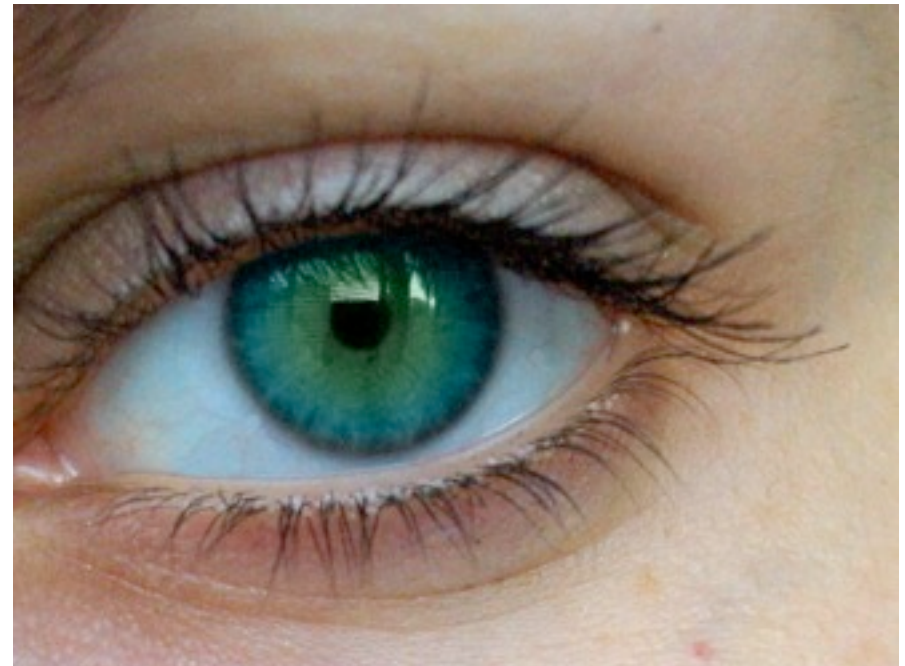
- What about jamming?
  - What about attacks on routing tables?
  - Is end-to-end security enough?

# Complex signals

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- Humans mostly understanding the world by

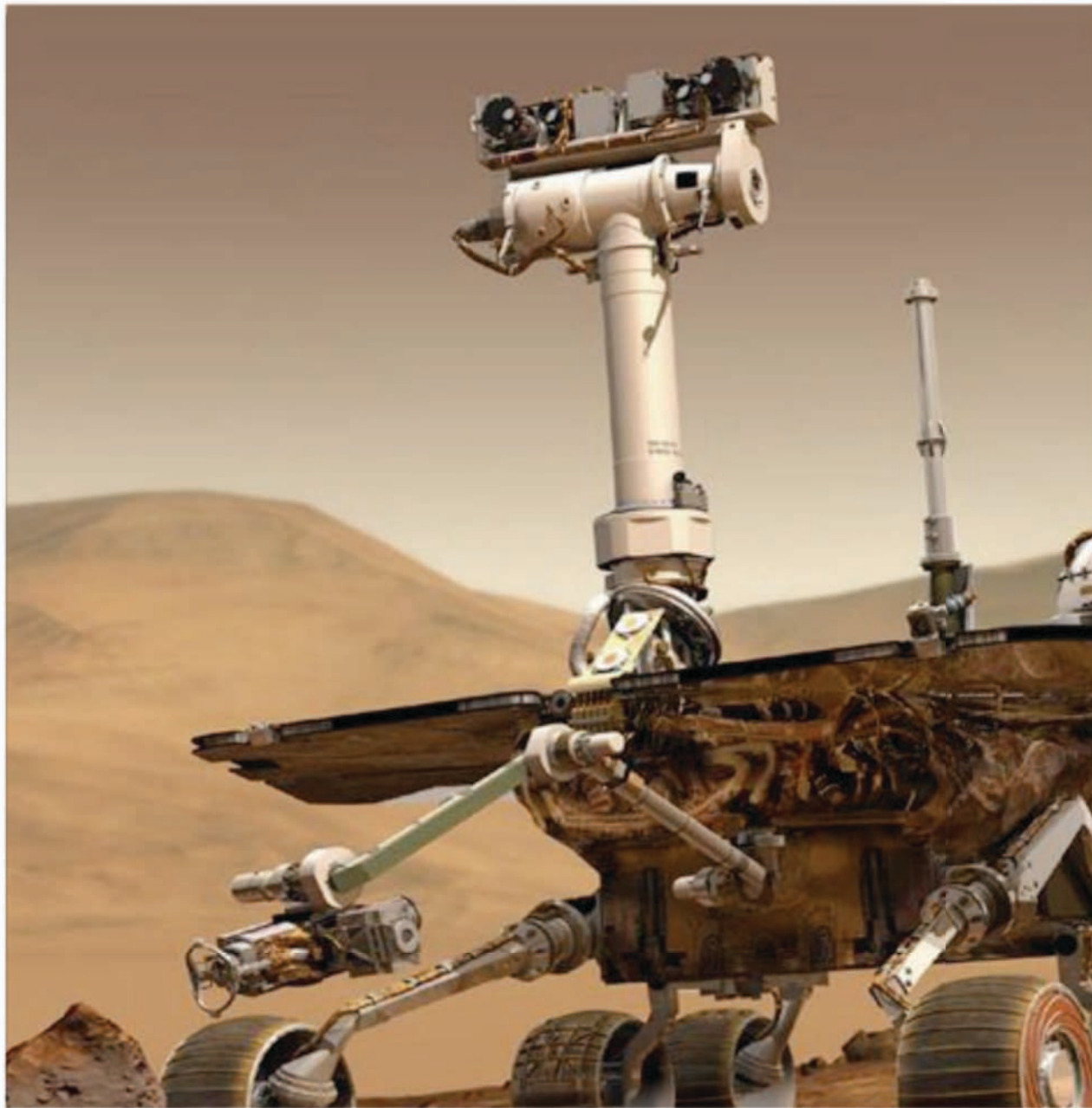
- looking
- listening



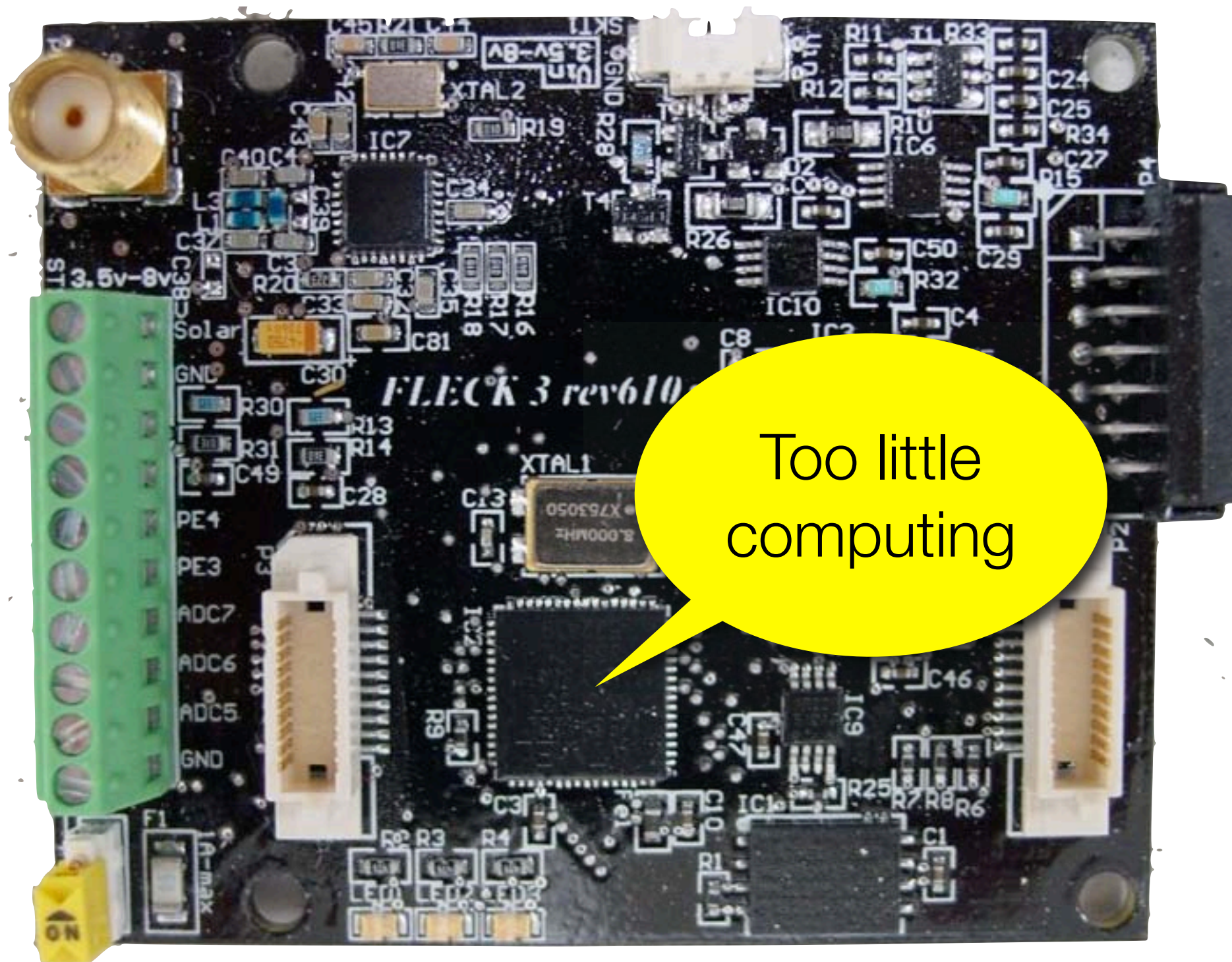






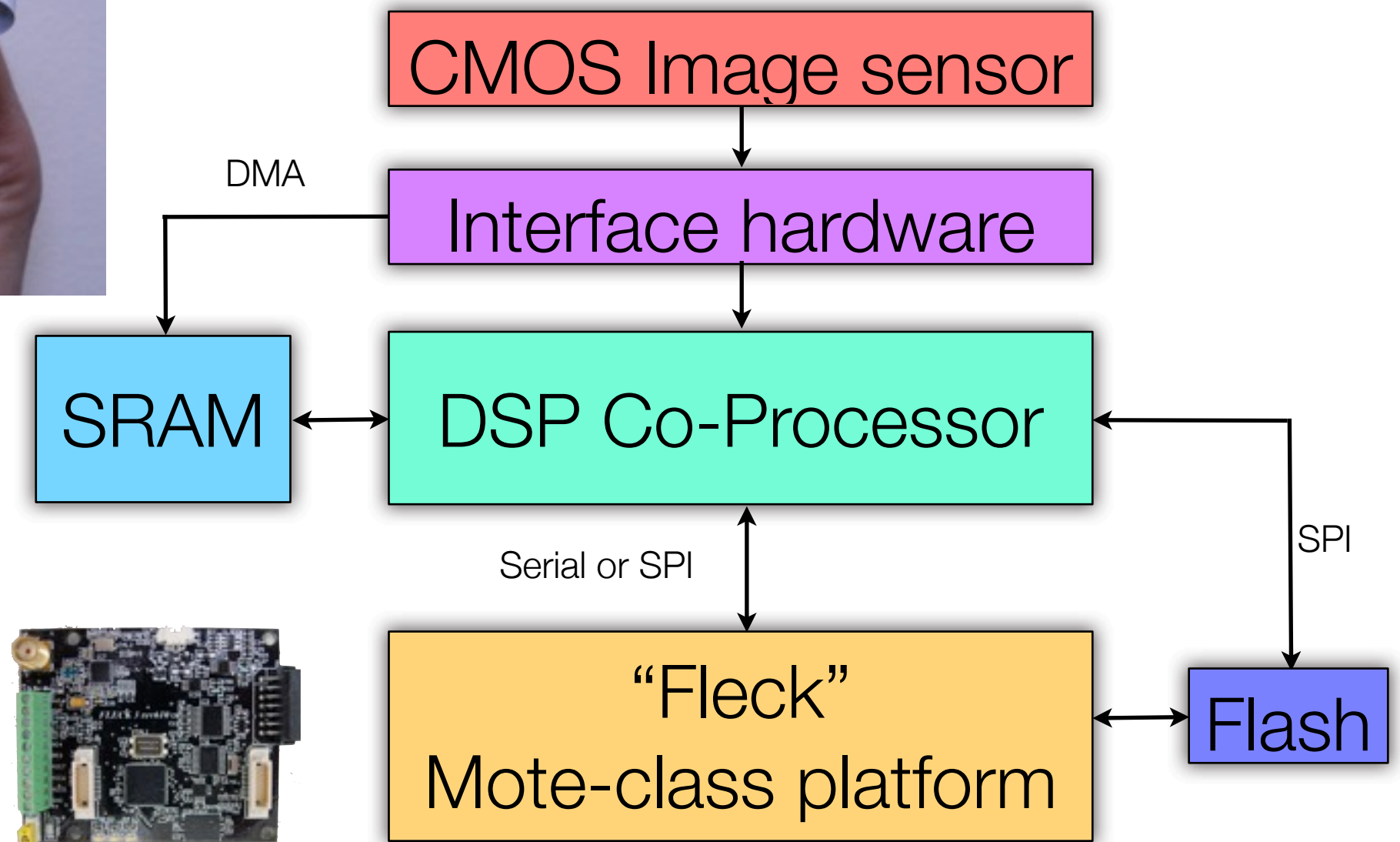






Too little  
computing

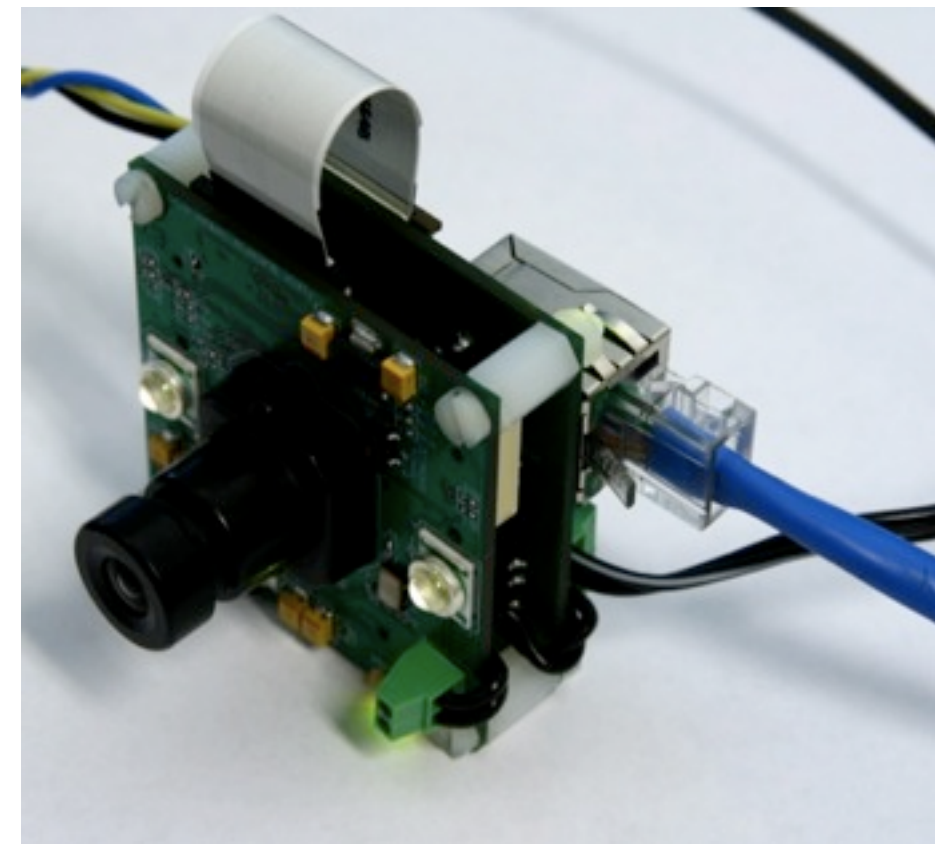
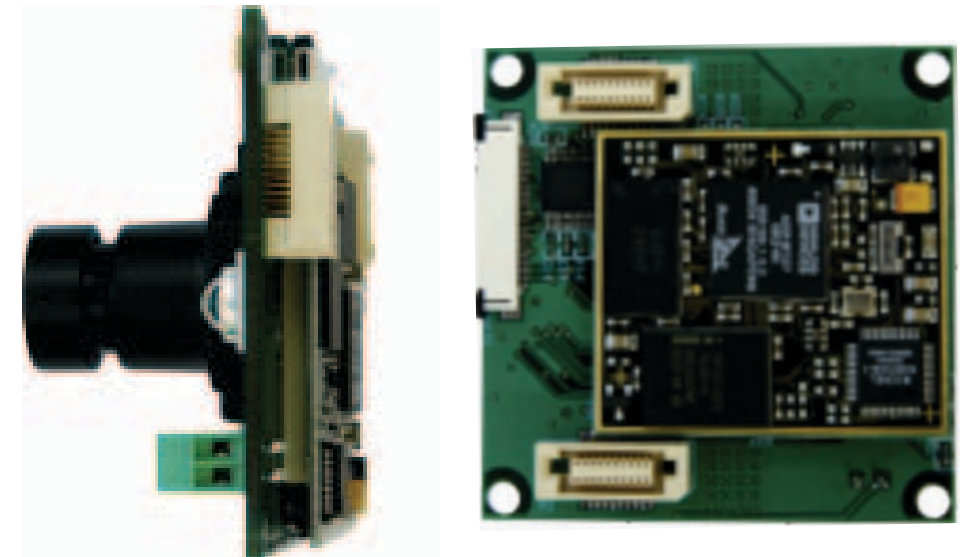
# Multi-media hardware architecture





# AD Blackfin DSP / Camera Board

- **Blackfin DSP (ADSP-BF537)**
  - AD 32 bit, 600 MHz processor
  - 132KB SRAM + 32MB external SD RAM
  - 4MB flash
  - 16bit external memory bus
  - No MMU
  - Runs uClinux or AD Visual DSP++
- **Programming**
  - JTAG or ethernet interface for programming
- **Fleck interface**
  - Serial
  - (Currently implementing SPI interface - with Fleck as SPI master)



# Image Transfer - Energy Comparison (TI)

---

	Camera On	DSP on	DSP → MMC	MMC → TX
Voltage	3.3V	3.3V	3.3V	3.3V
Current	30mA	240mA	270mA	50mA
Power	99mW	792mW	891mW	165mW
Time	0.03s	0.1s	1.5s	40s
Energy	3.0mJ	79.2mJ	1336mJ	6600mJ

**8018mJ**

	Camera On	DSP on	DSP → TX
Voltage	3.3V	3.3V	3.3V
Current	30mA	240mA	260mA
Power	99mW	792mW	858mW
Time	0.03s	0.5s	0.8s
Energy	3.0mJ	396mJ	687mJ

**1086mJ**

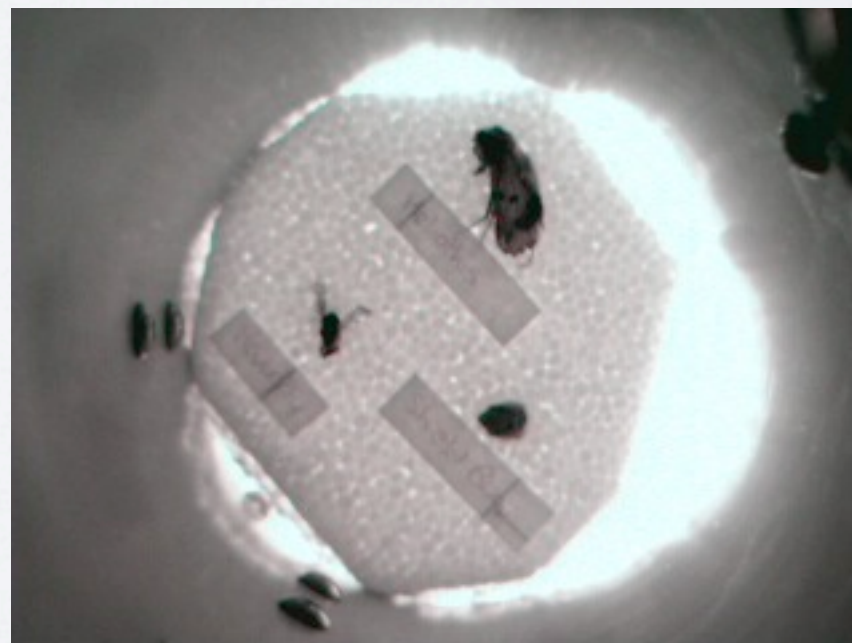
**8 x times less energy with  
compression**







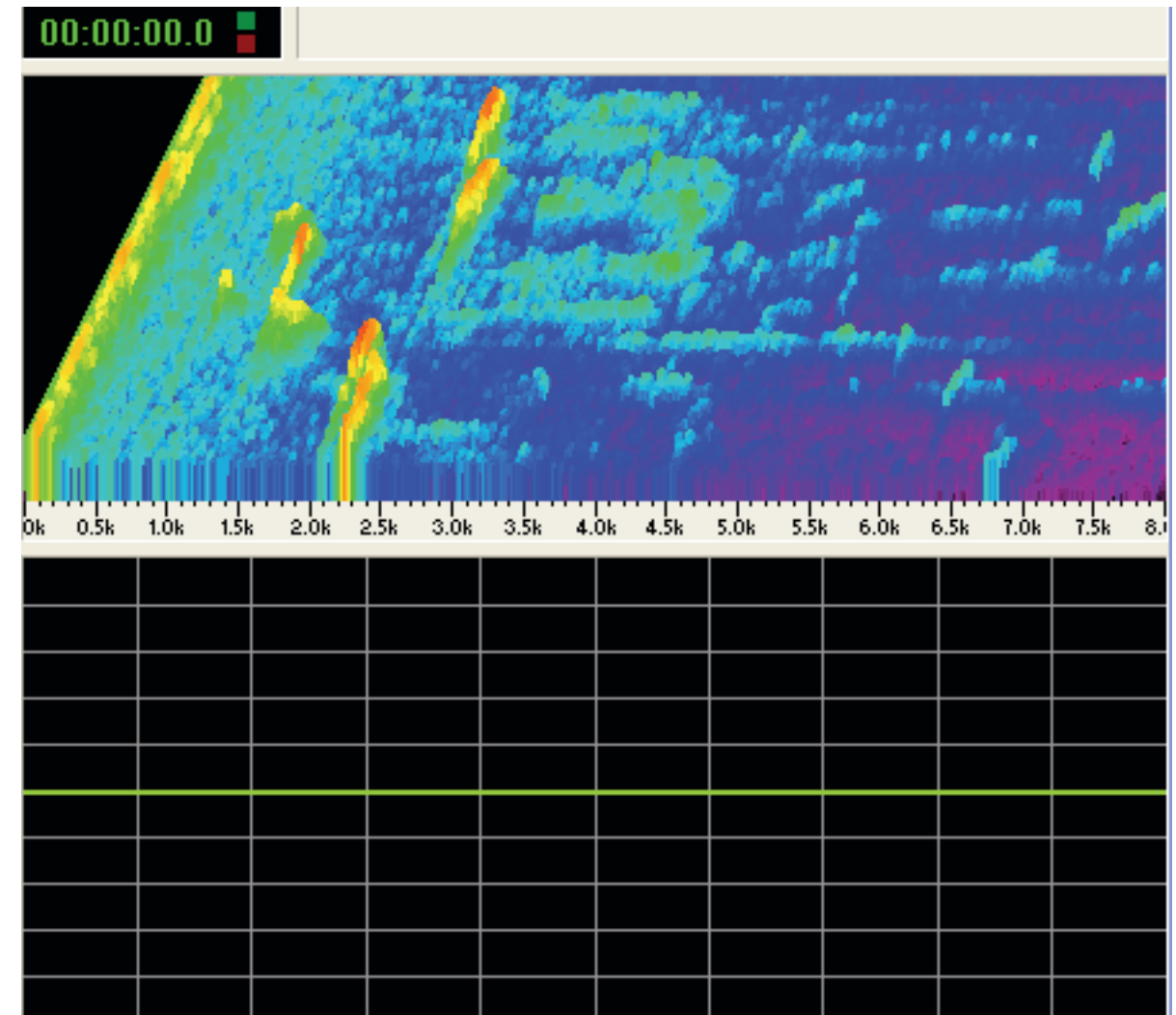
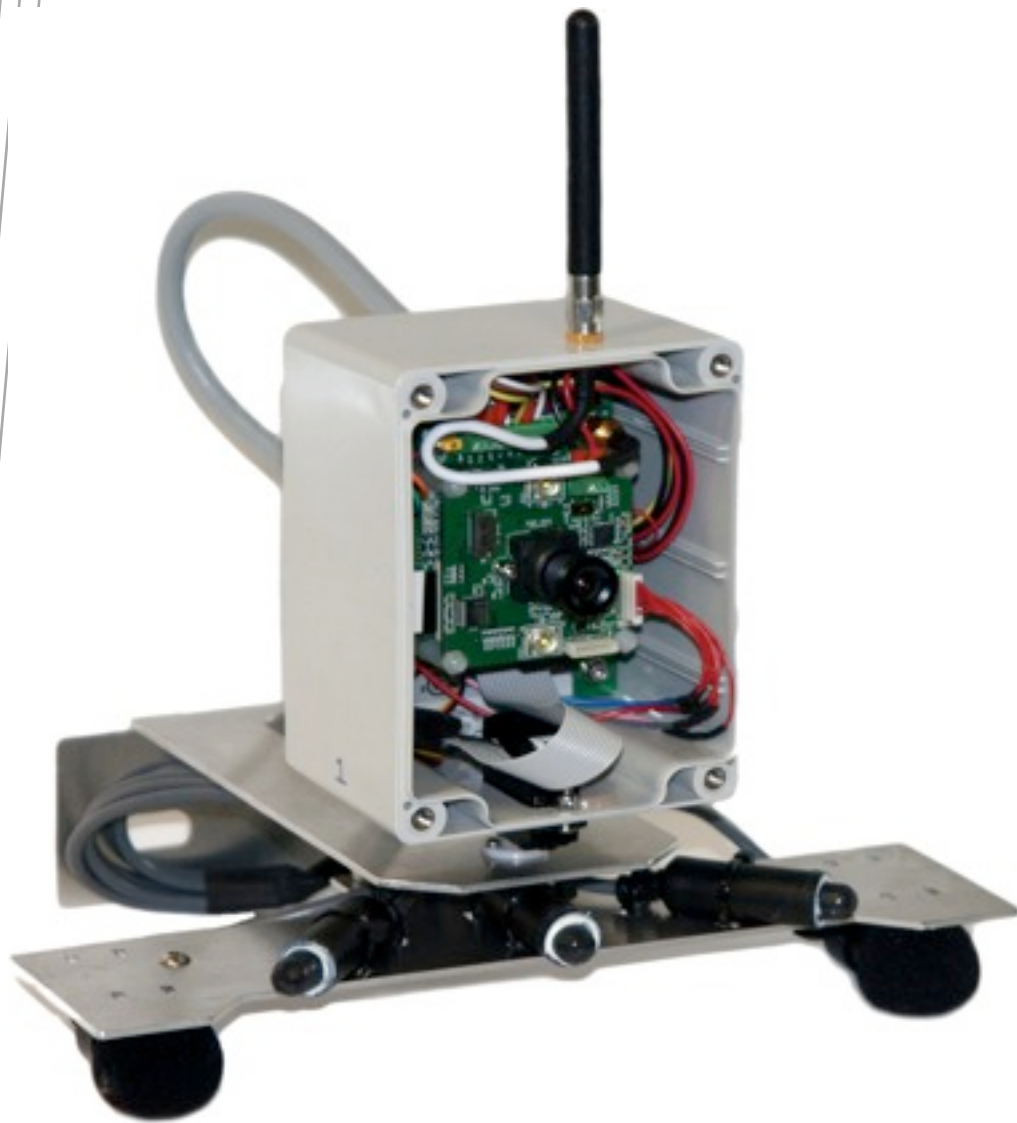






# Audio/Video nodes

- Local-computation class nodes
- Event detection
- Complex signals (e.g. audio or video)



O'Rourke D., Liu J., Wark T., et.al, "Towards a Framework for a Versatile Wireless Multimedia Sensor Network Platform," ACM/IEEE Information Processing in Sensor Networks (IPSN), 2010.

Hu. W, Bulusa N, Chou C T., et.al, "The Design and Evaluation of a Hybrid Sensor Network for Cane-toad Monitoring", *ACM Transactions on Sensor Networks (TOSN)*, Volume 5, Issue 1 , 2009.

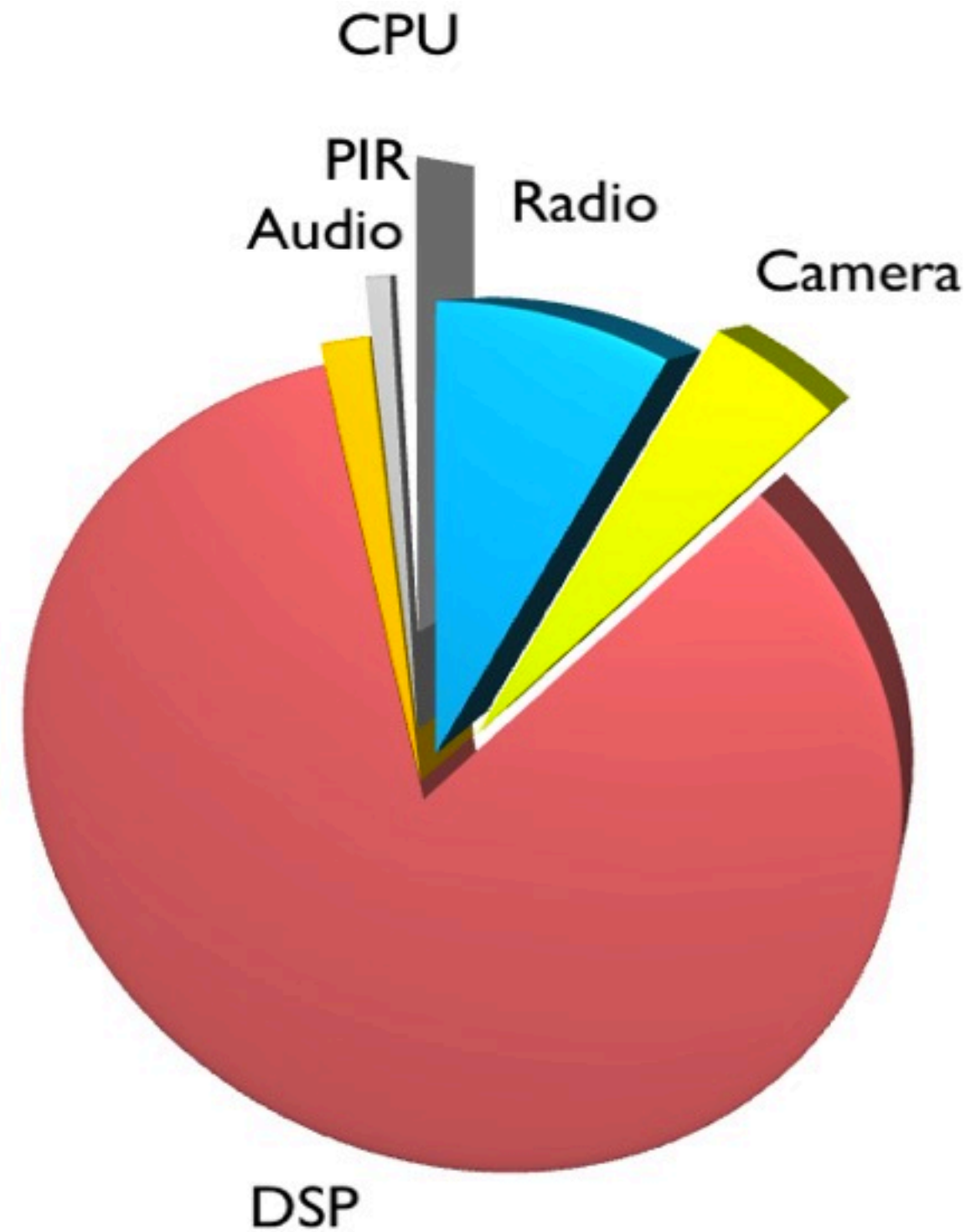
Wark T., Corke P., Liu J. and Moore D., "Design and evaluation of an image analysis platform for low-power, low-bandwidth camera networks", *Proc. ImageSense /ACM Sensys*, 2008.

# Where does the energy go?

---



computation







2003	2005-6	2006-7	2007-9	2008-9	2009-9
TOS 1.x	TOS 1.x	TOS1.x	FOS	FOS	FOS
ZTDMA	ZTDMA	MintRoute	Diffusion	LQ/LPL	LQ/LPL
Fleck1C	Fleck2	Fleck3	Fleck3	Fleck3	Fleck3

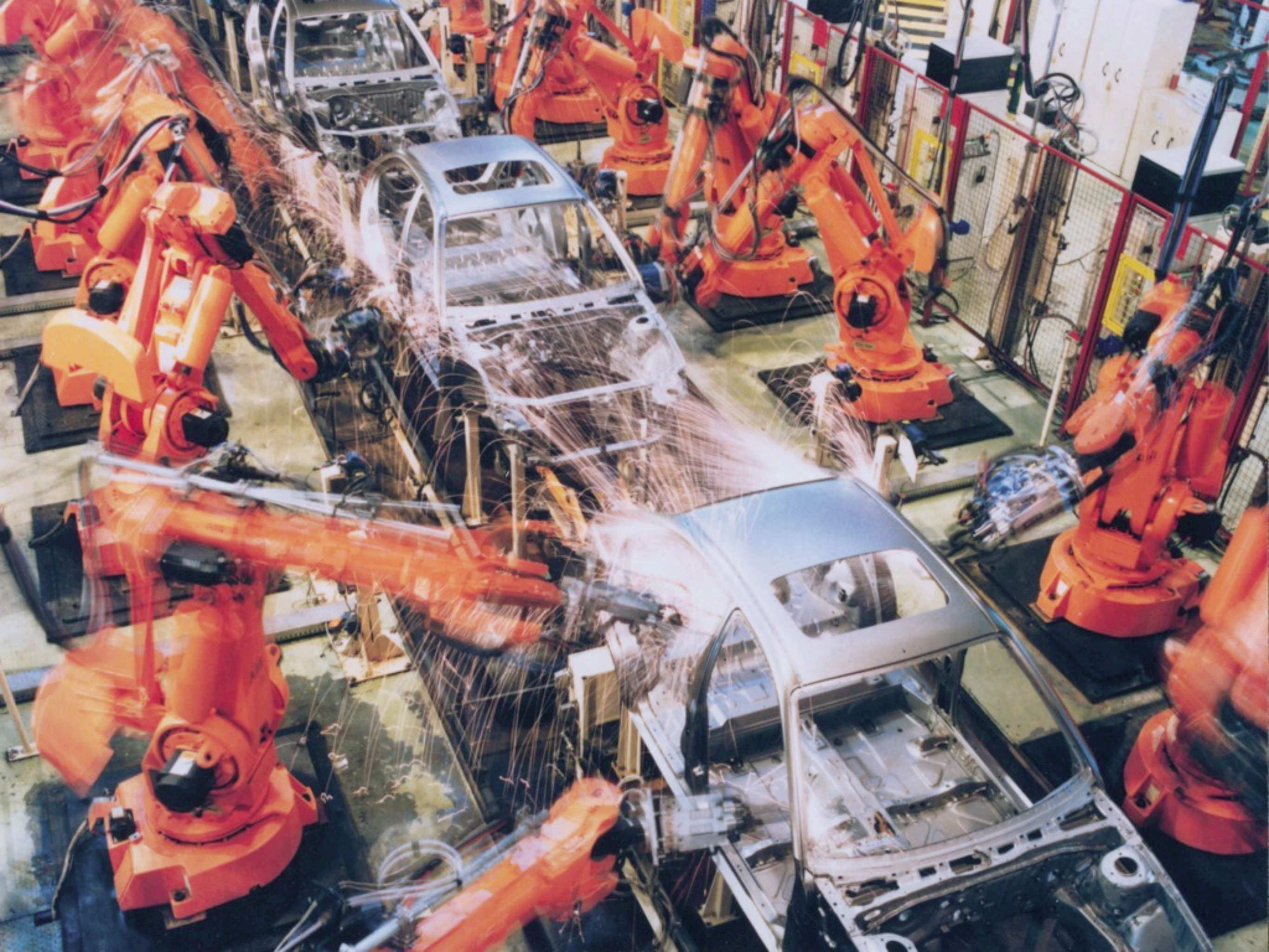


**But what's  
happening  
here?**

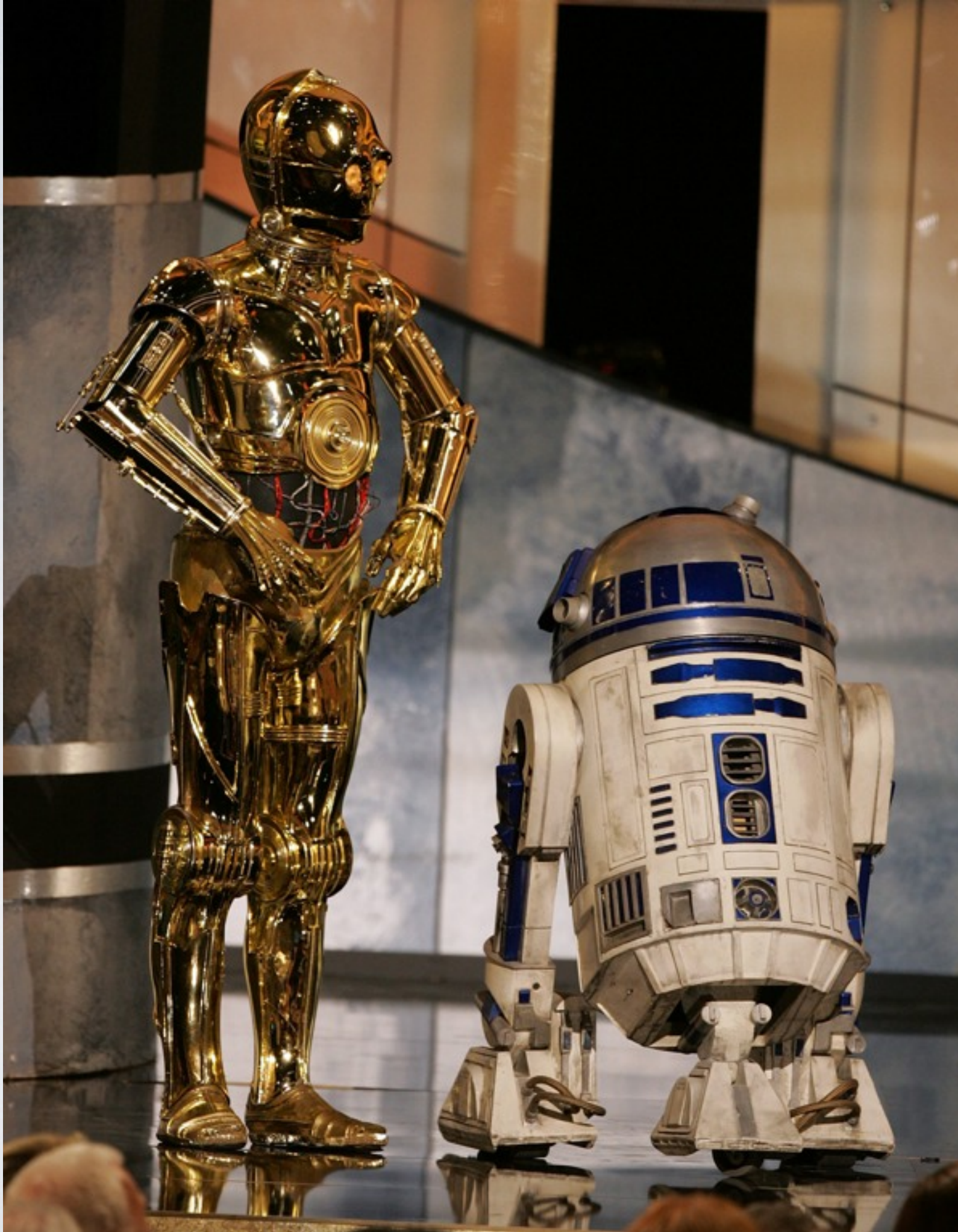


T=24C

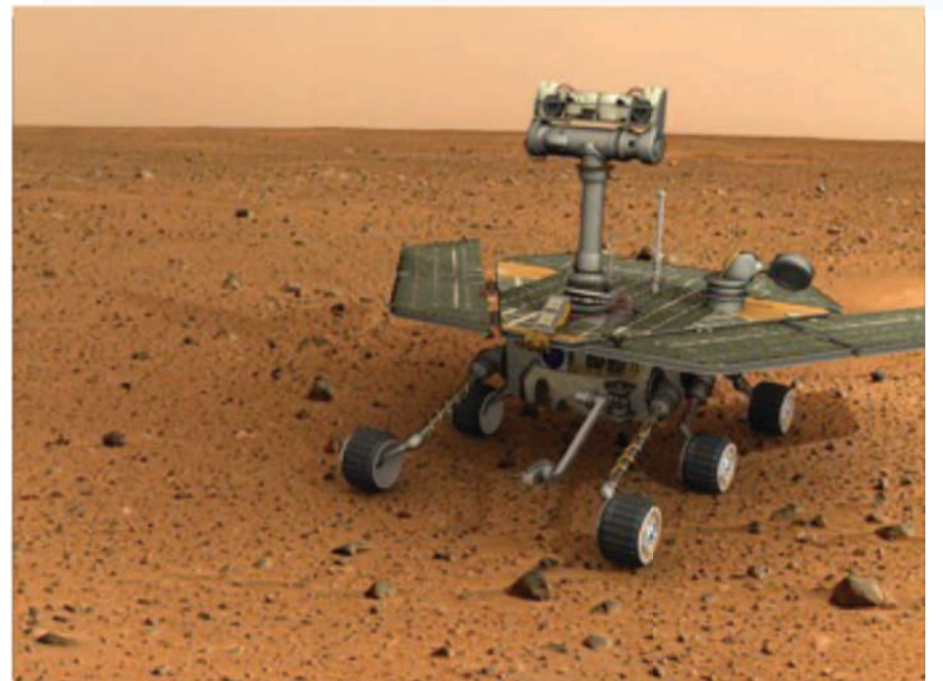




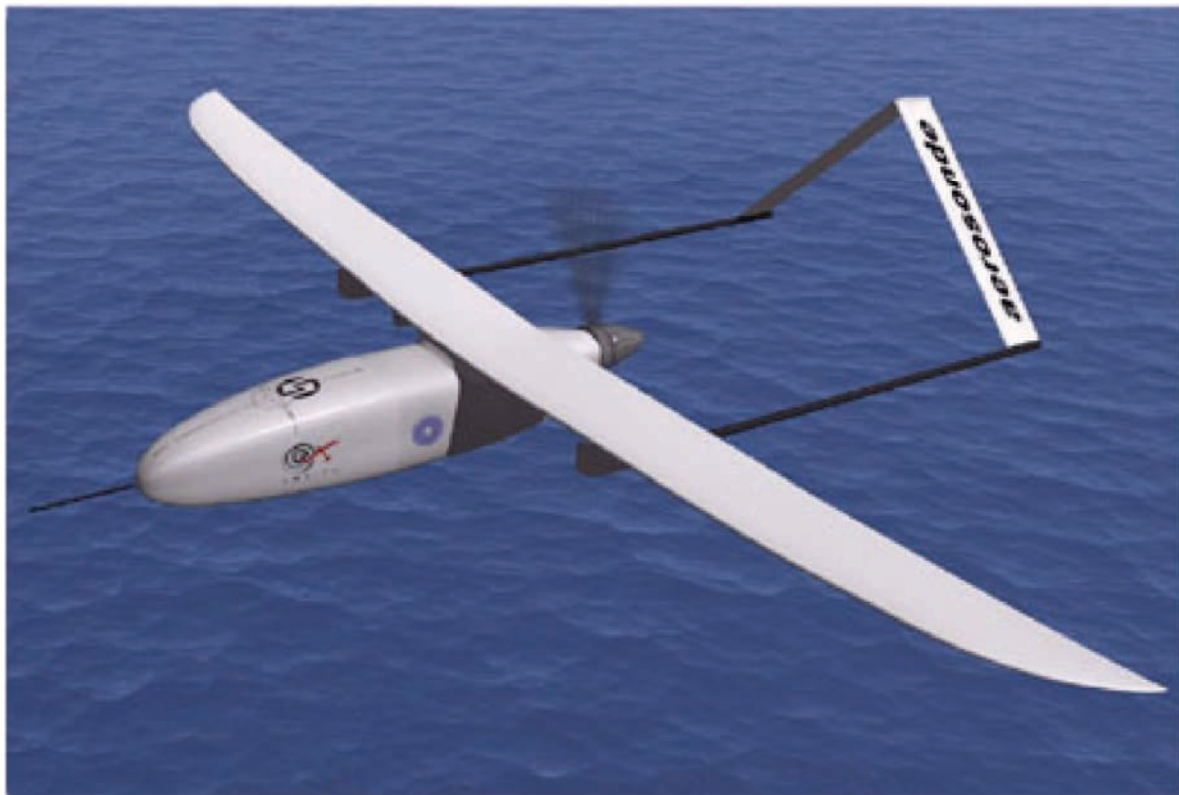




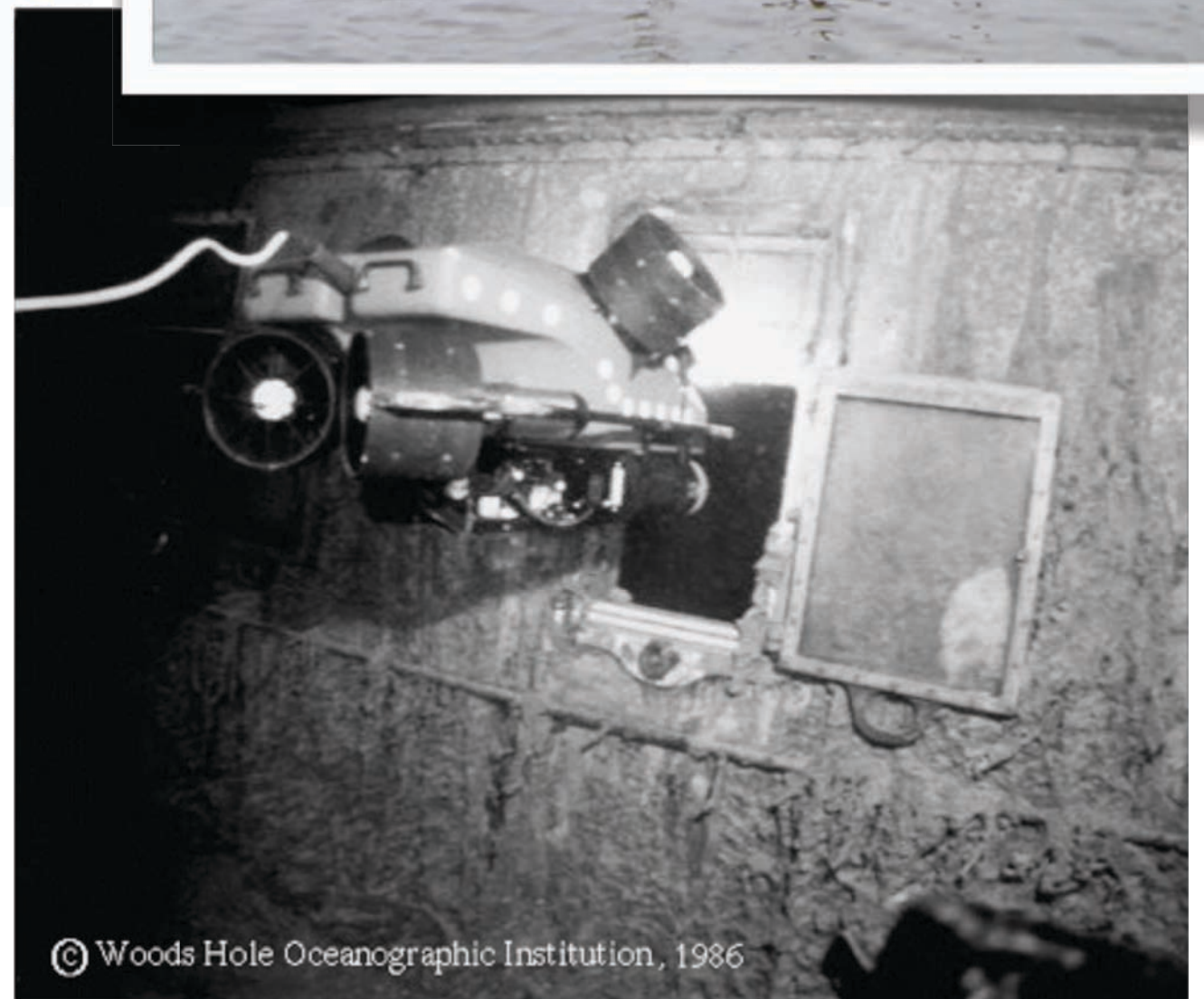
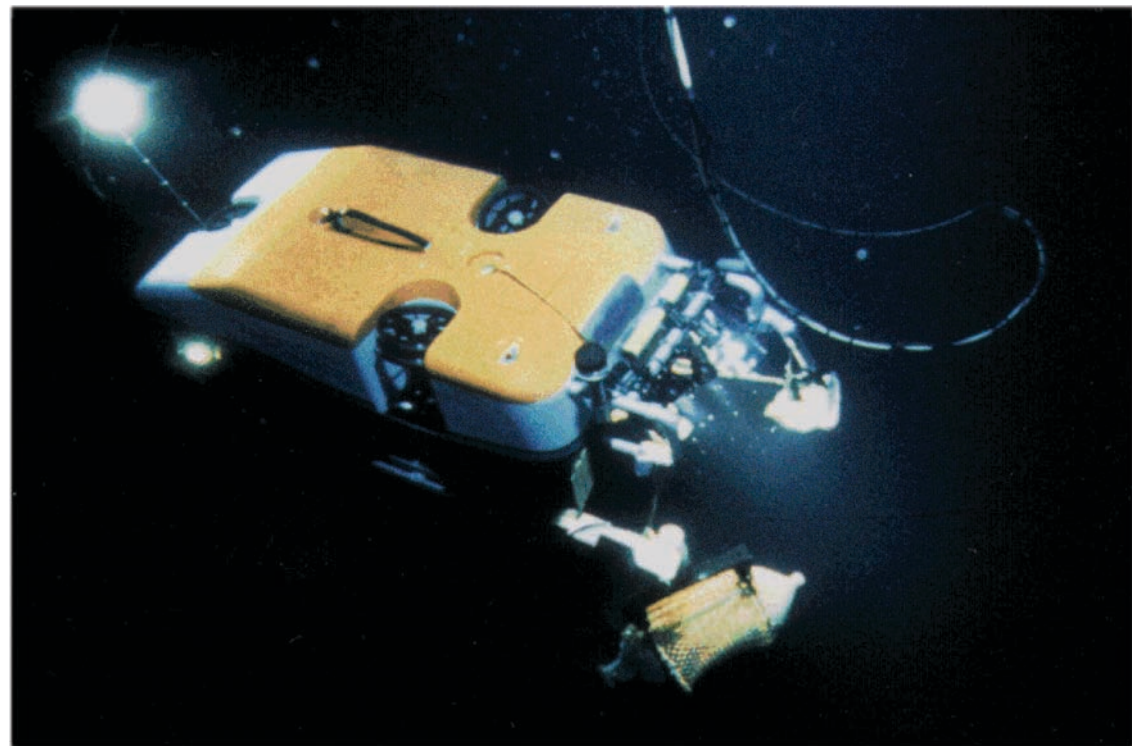
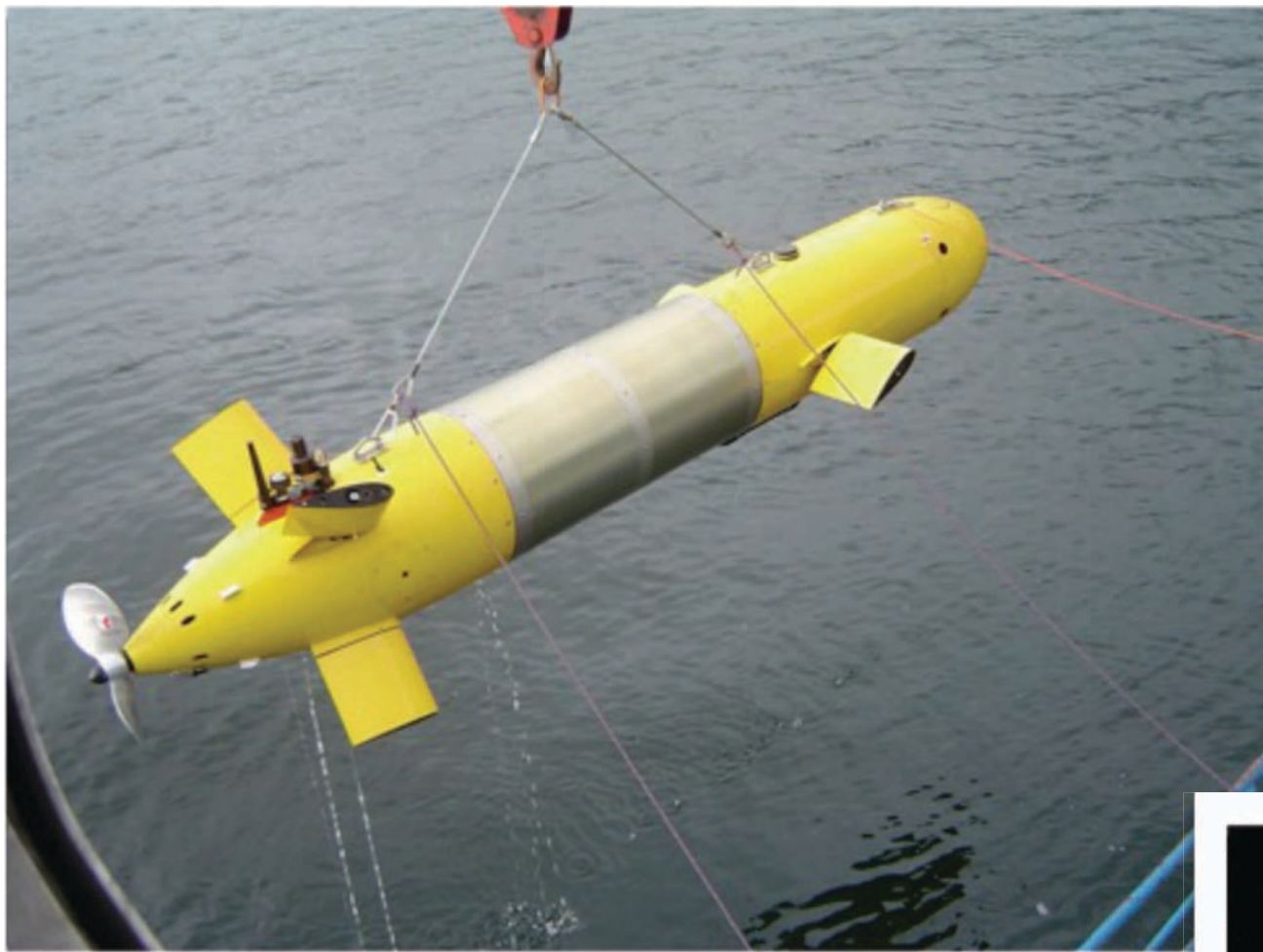












# Sensor networks and robots are complementary

---

- **SN**

- Sense globally (sparse)
- Static
- Limited resources
- Network to transport robot's data
- Localize a robot

- **Robot**

- Sense locally
- Mobile
- Abundant resources
- Physical transport of SN's data
- Localize nodes
- Deploy nodes







# Robotic deployment



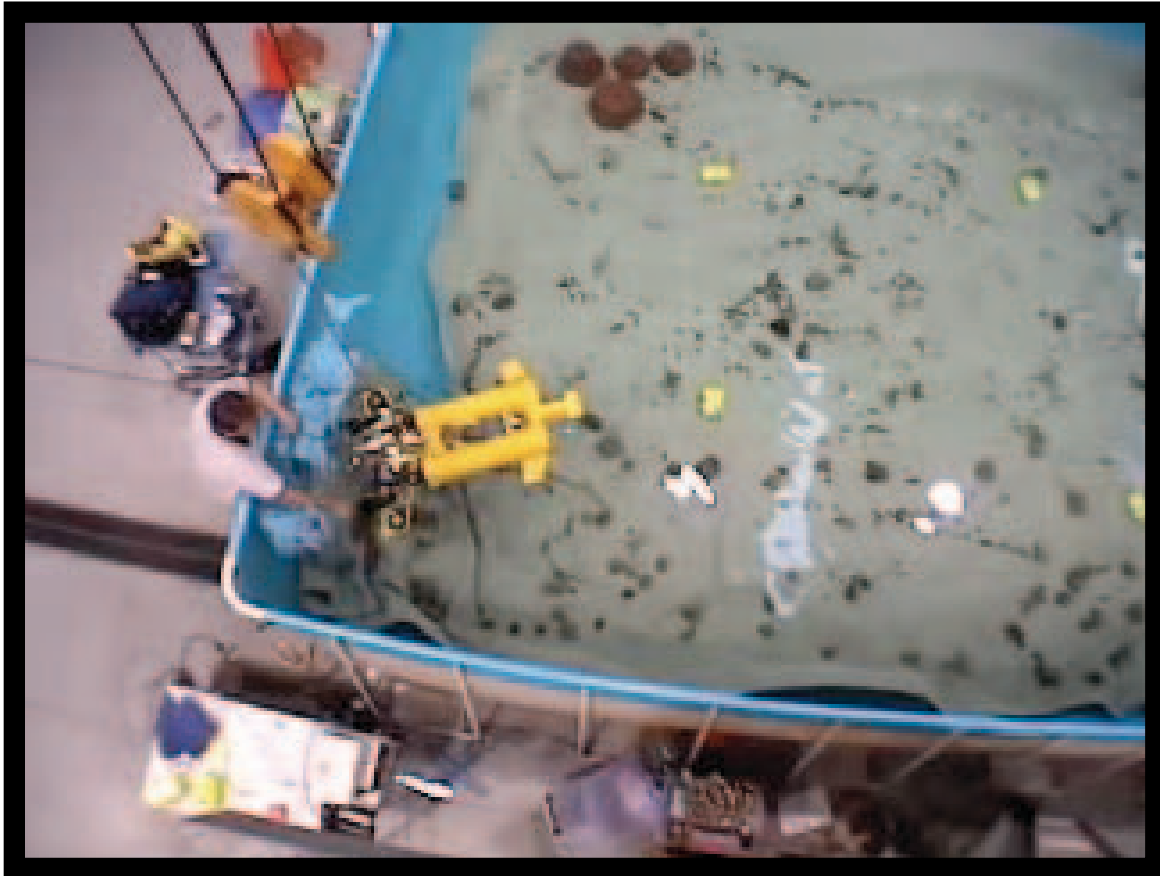
with USC and MIT

**2003**

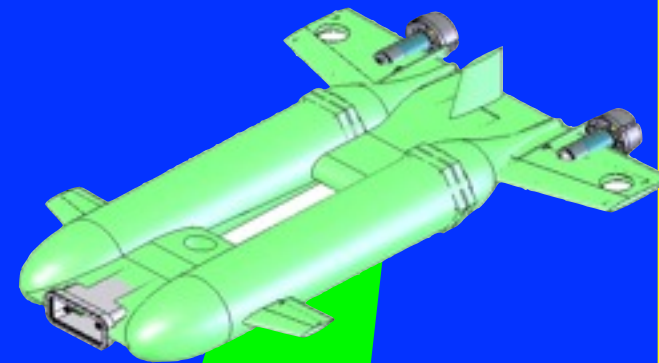


# Robotic data muling

CSIRO-MIT experiments  
2005

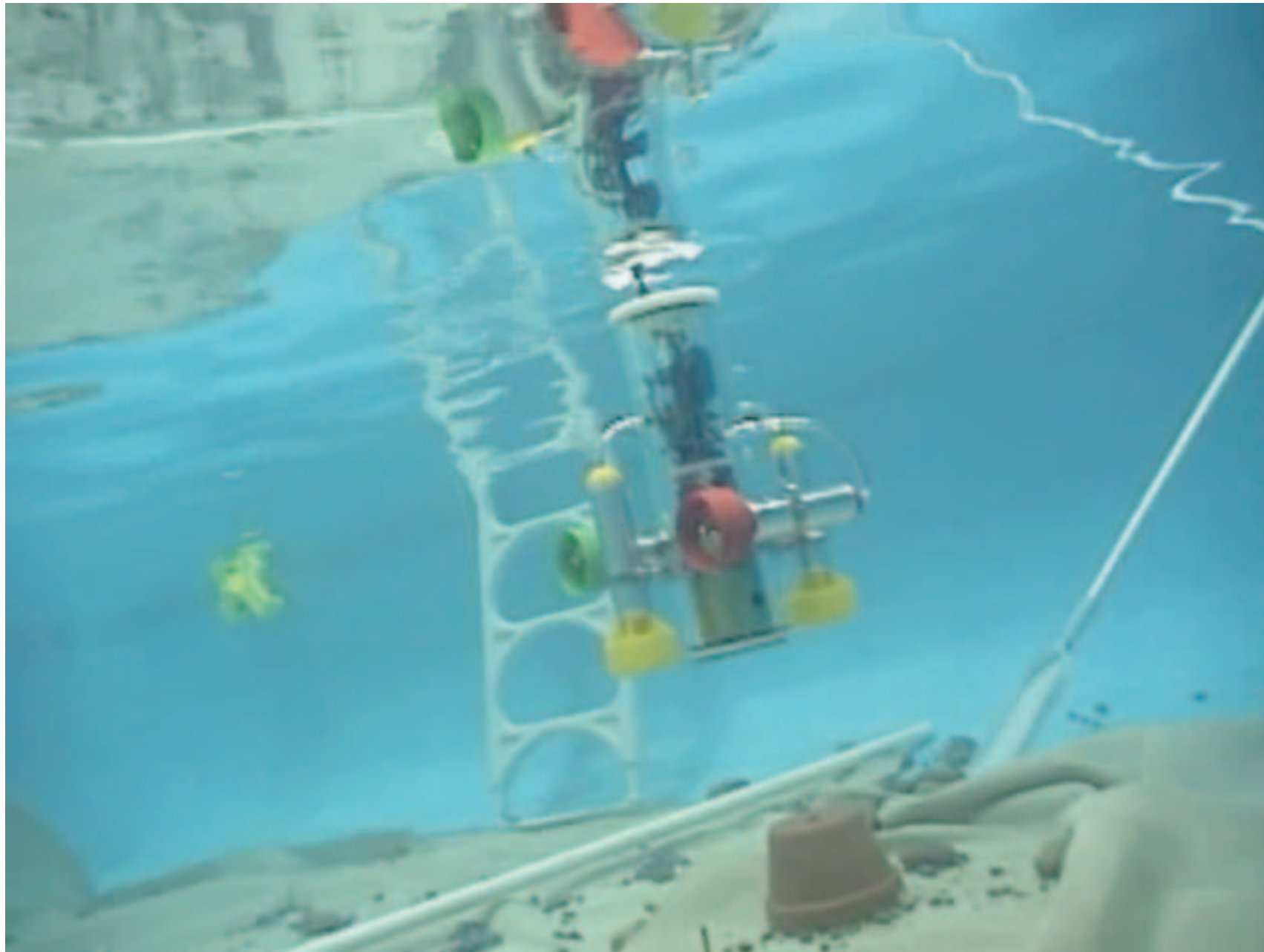


Optical comms



# Robotic node pickup

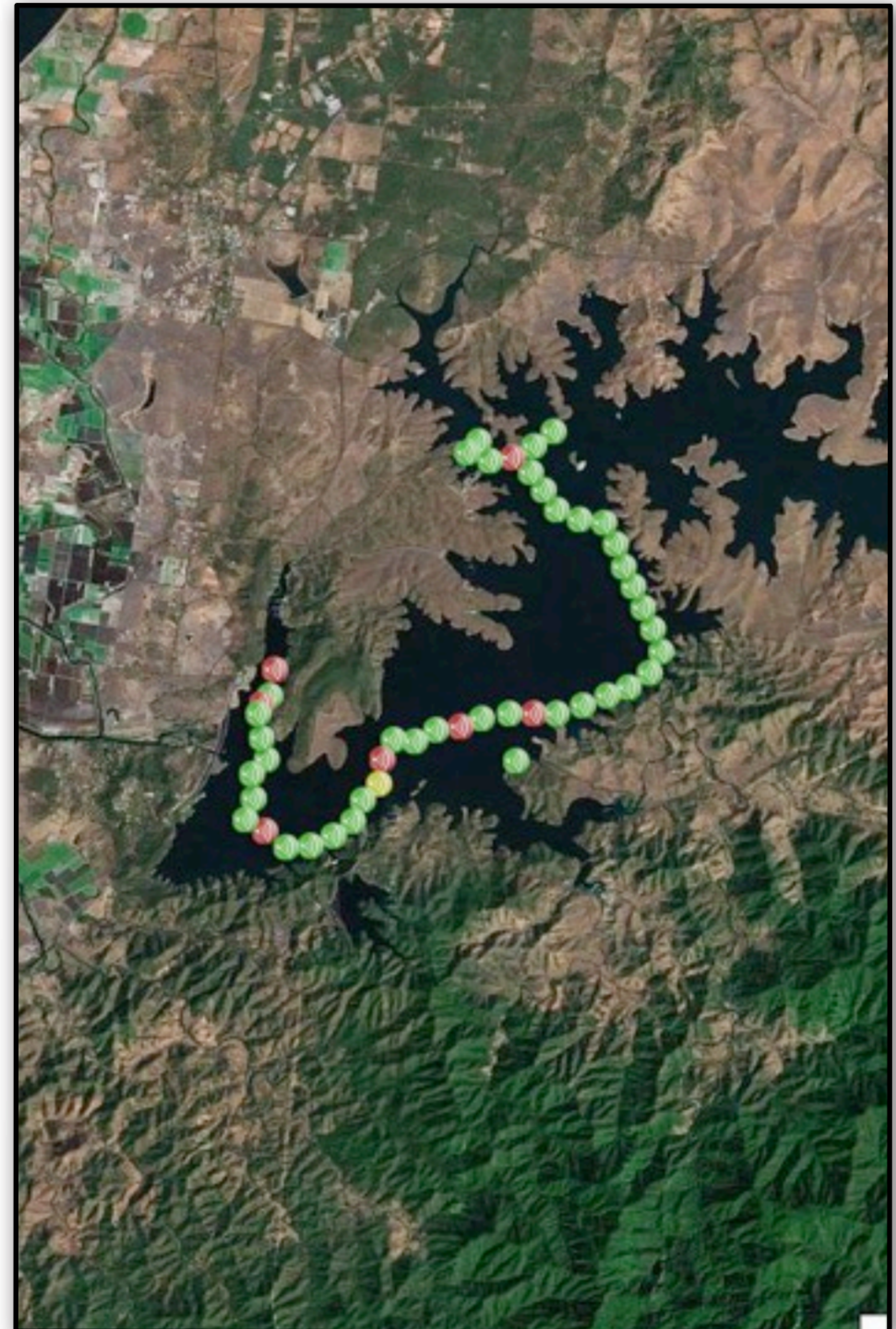
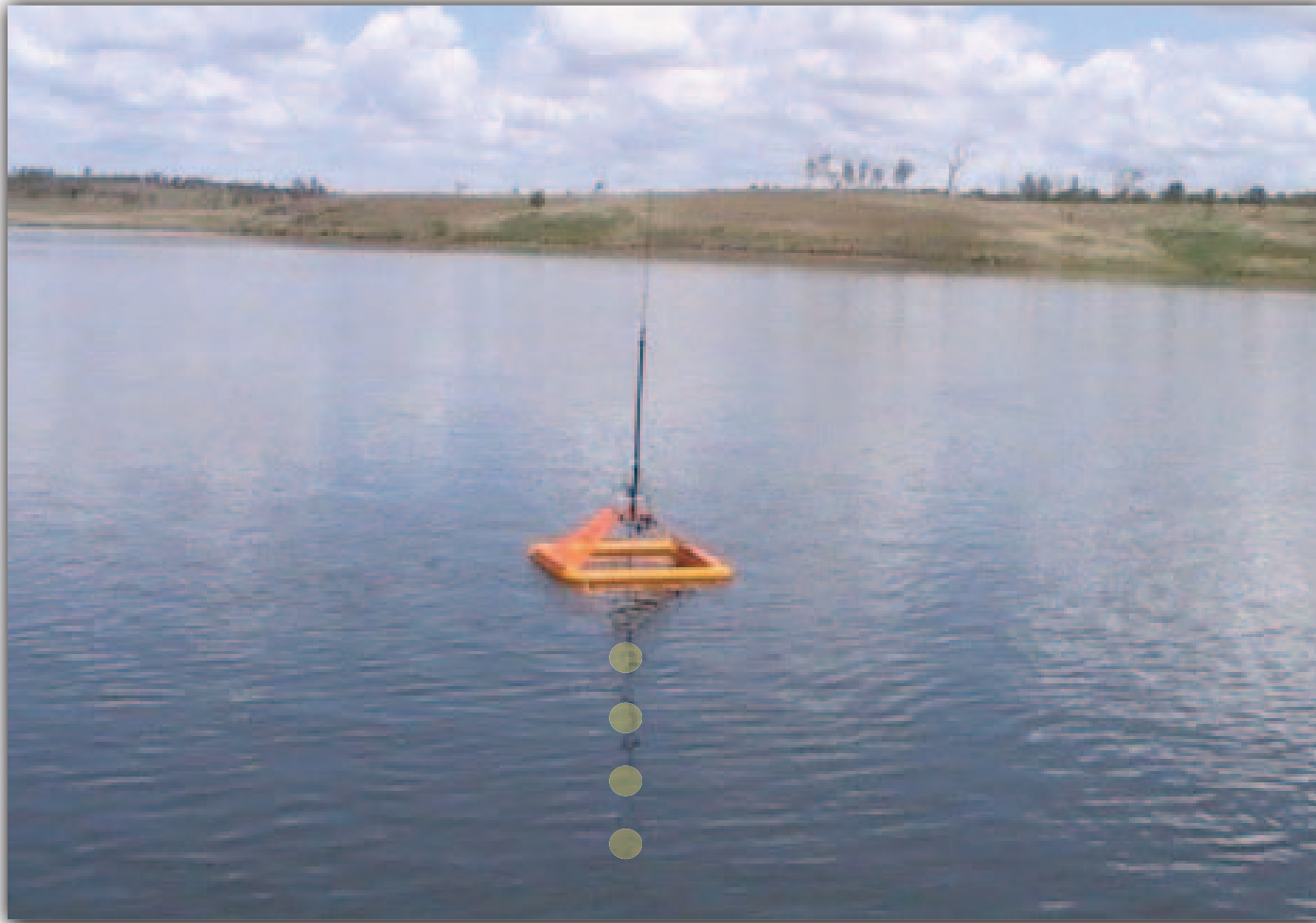
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# Application: Lake Monitoring

---

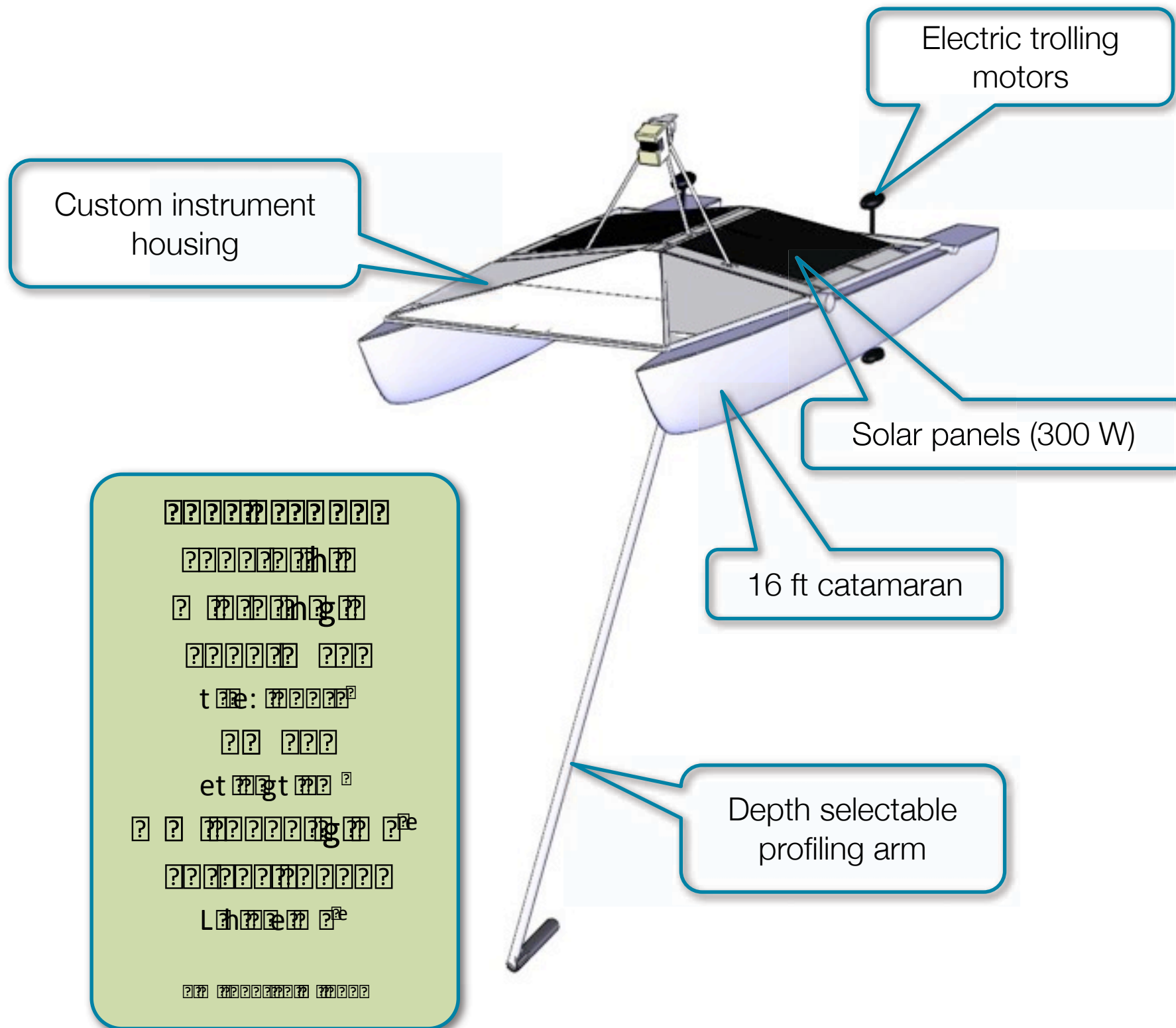








# ASV Nikki



## Navigational sensors

- Laser scanner
- GPS / compass
- Camera
- Depth sounder
- Wind speed

## Environmental sensors

- Optical Methane Detector
- YSI Sonde
- Rhodamine Fluorometer
- Odyssey light logger
- Tritech Profiling Sonar

# Calibration and mobile sensing

Calibration information

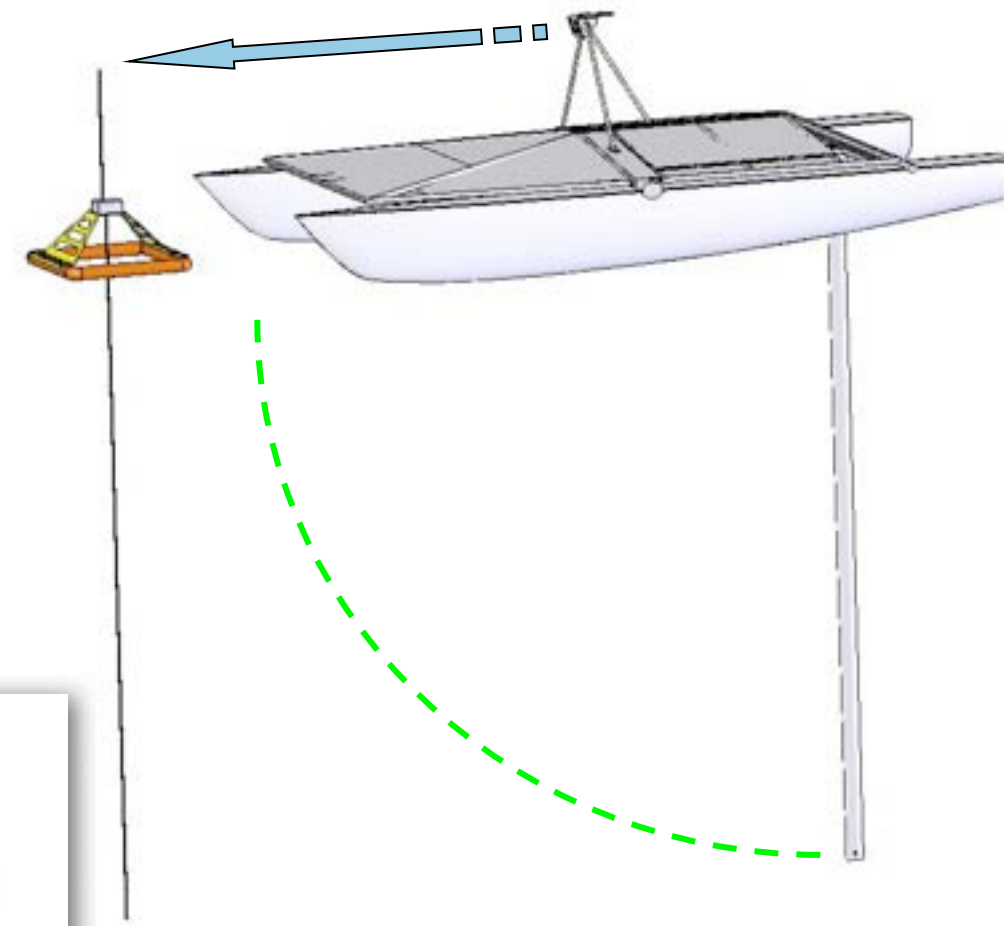
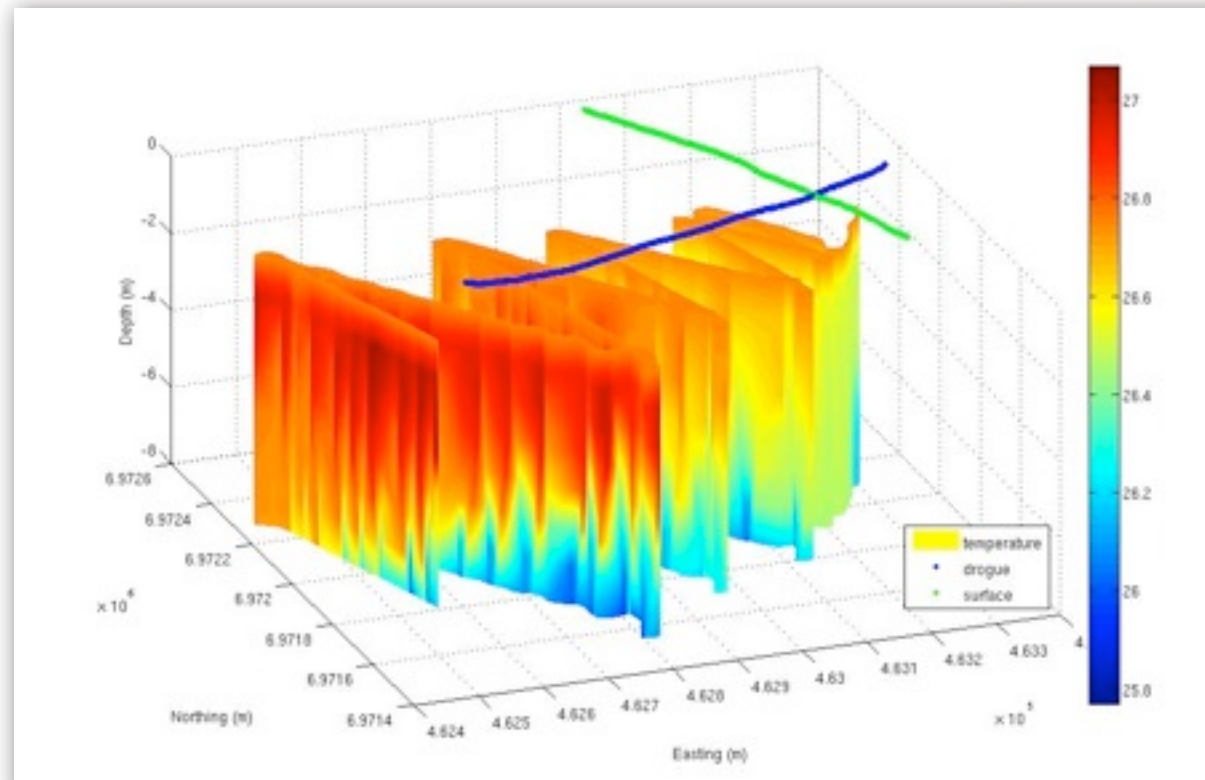
- In-situ node temperature calibration

- Offset determination
- Relay information to node

- Node inspection

- Localization
- Condition assessment

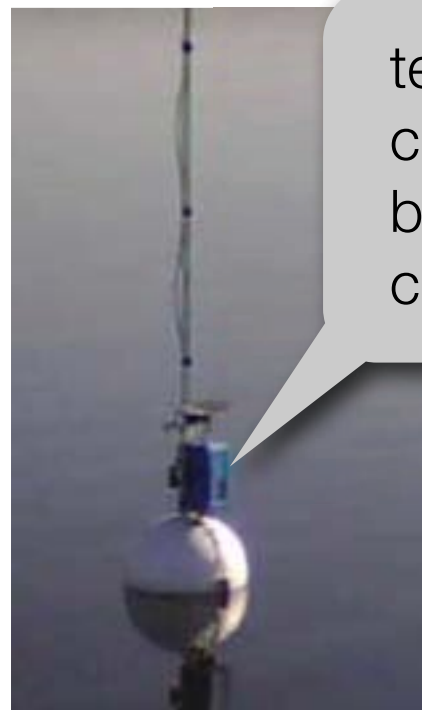
- 3d temperature profiling



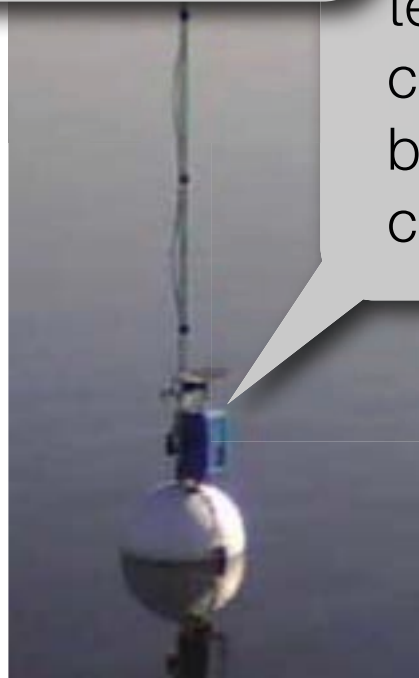


# Abstraction: Service-based sensor network

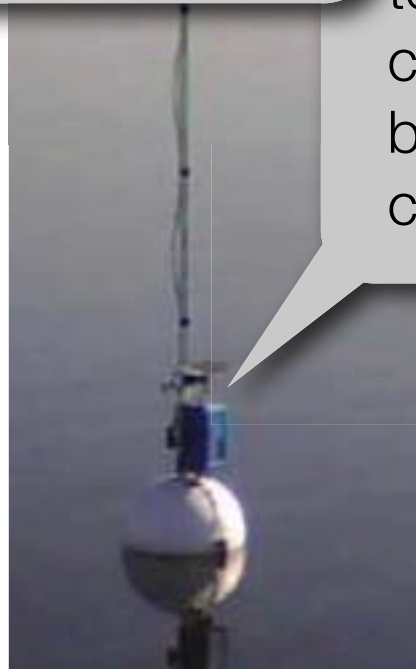
---



temperature()  
charging()  
battery()  
comms\_stats()



temperature()  
charging()  
battery()  
comms\_stats()



temperature()  
charging()  
battery()  
comms\_stats()



goto(x, y, speed)  
location  
temperature(d)  
battery

# Learnings

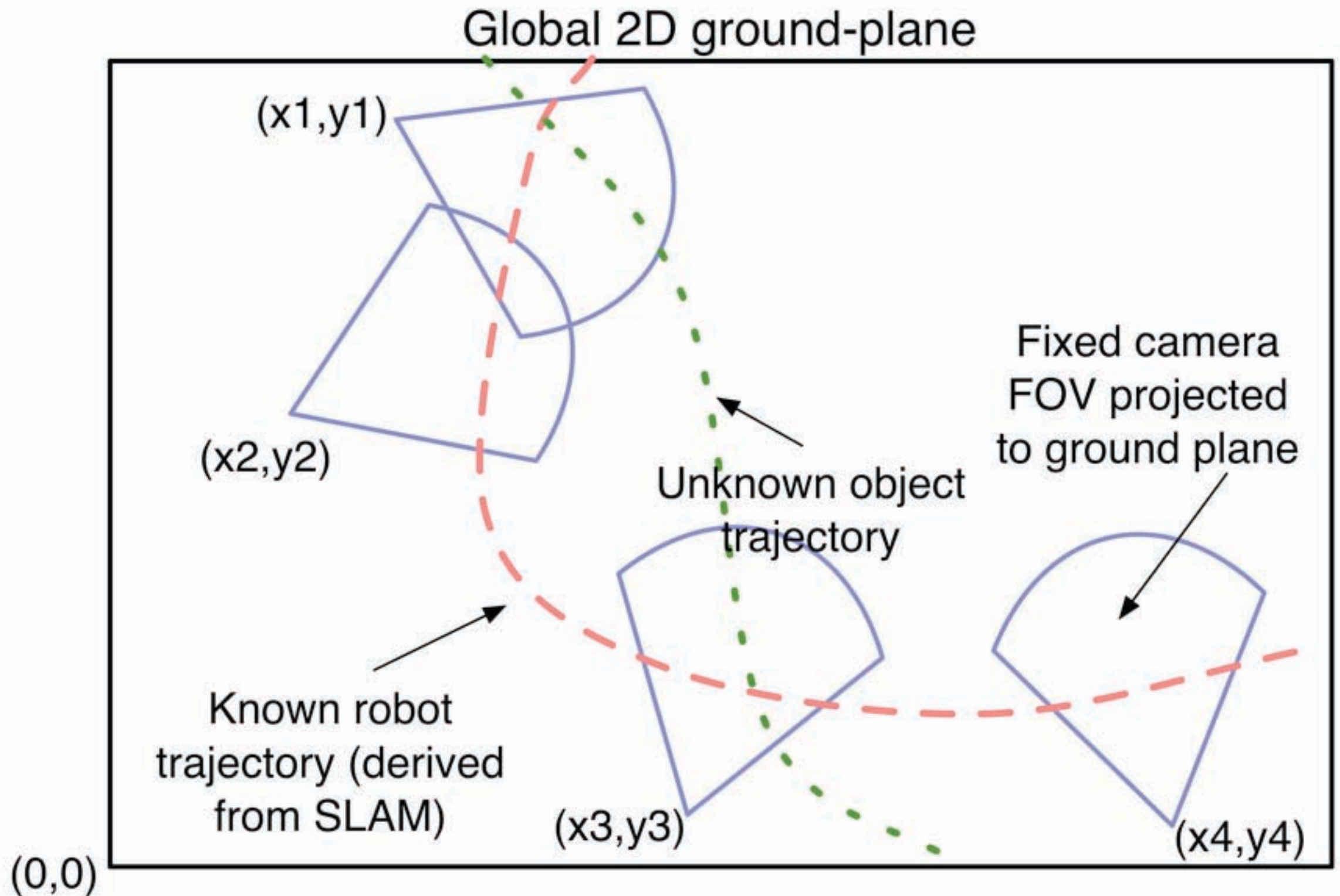
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- Radio propagation is poor over water (~ 150m)
- RPCs make life easy
- Physical robustness important



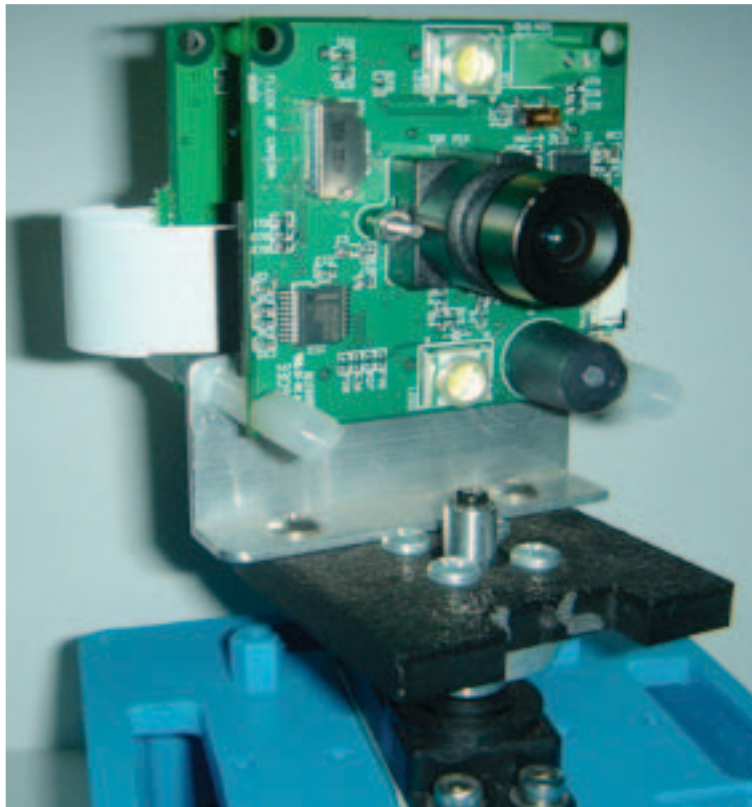


# Camera-based surveillance



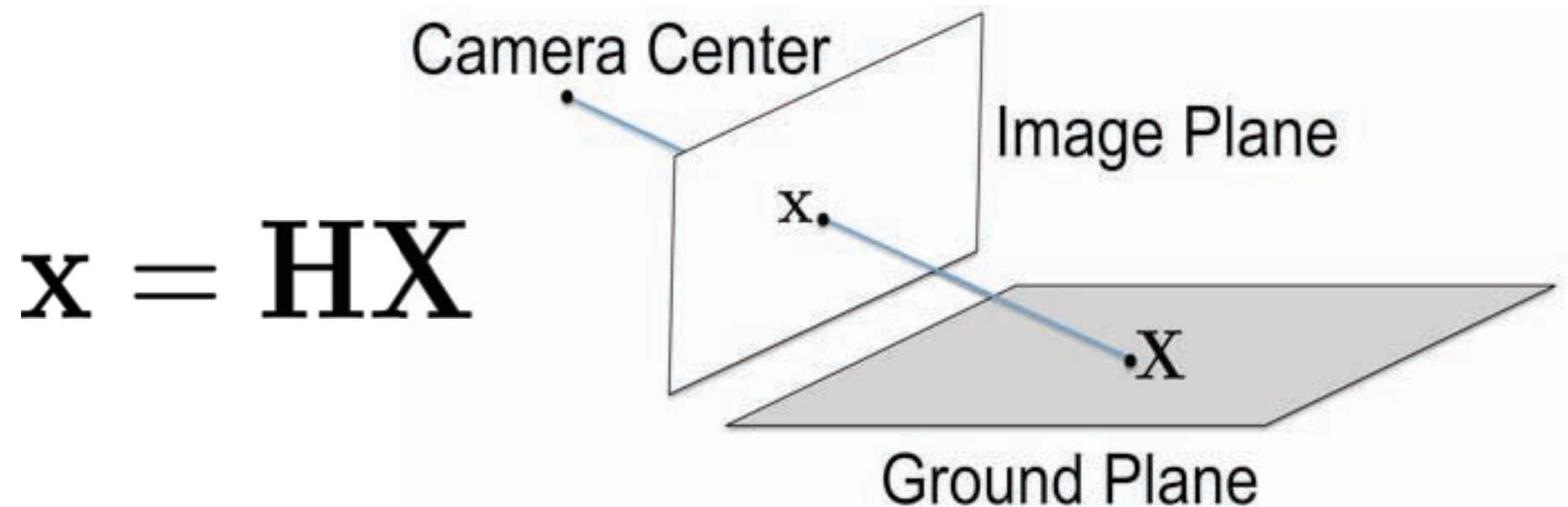
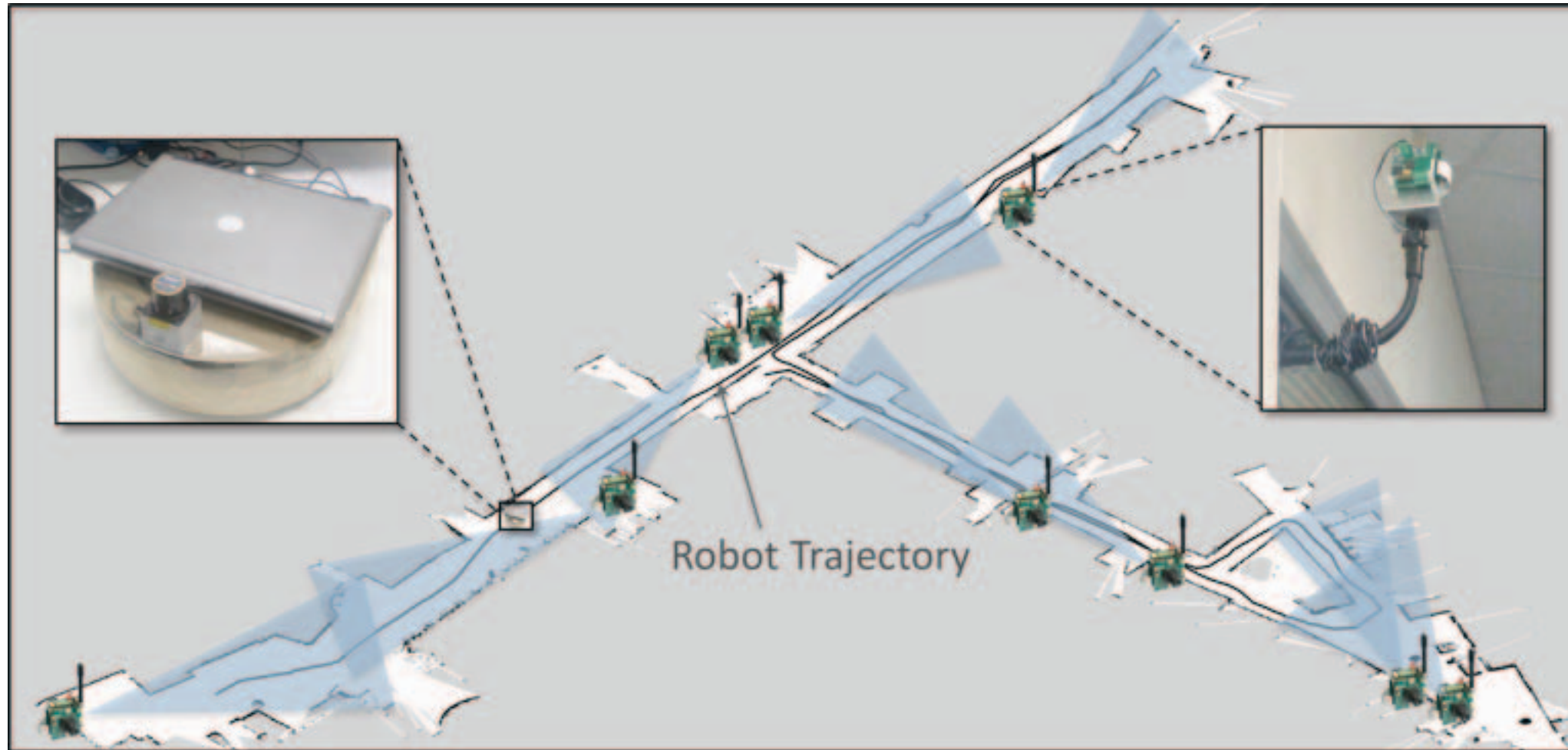
# Object tracking

---

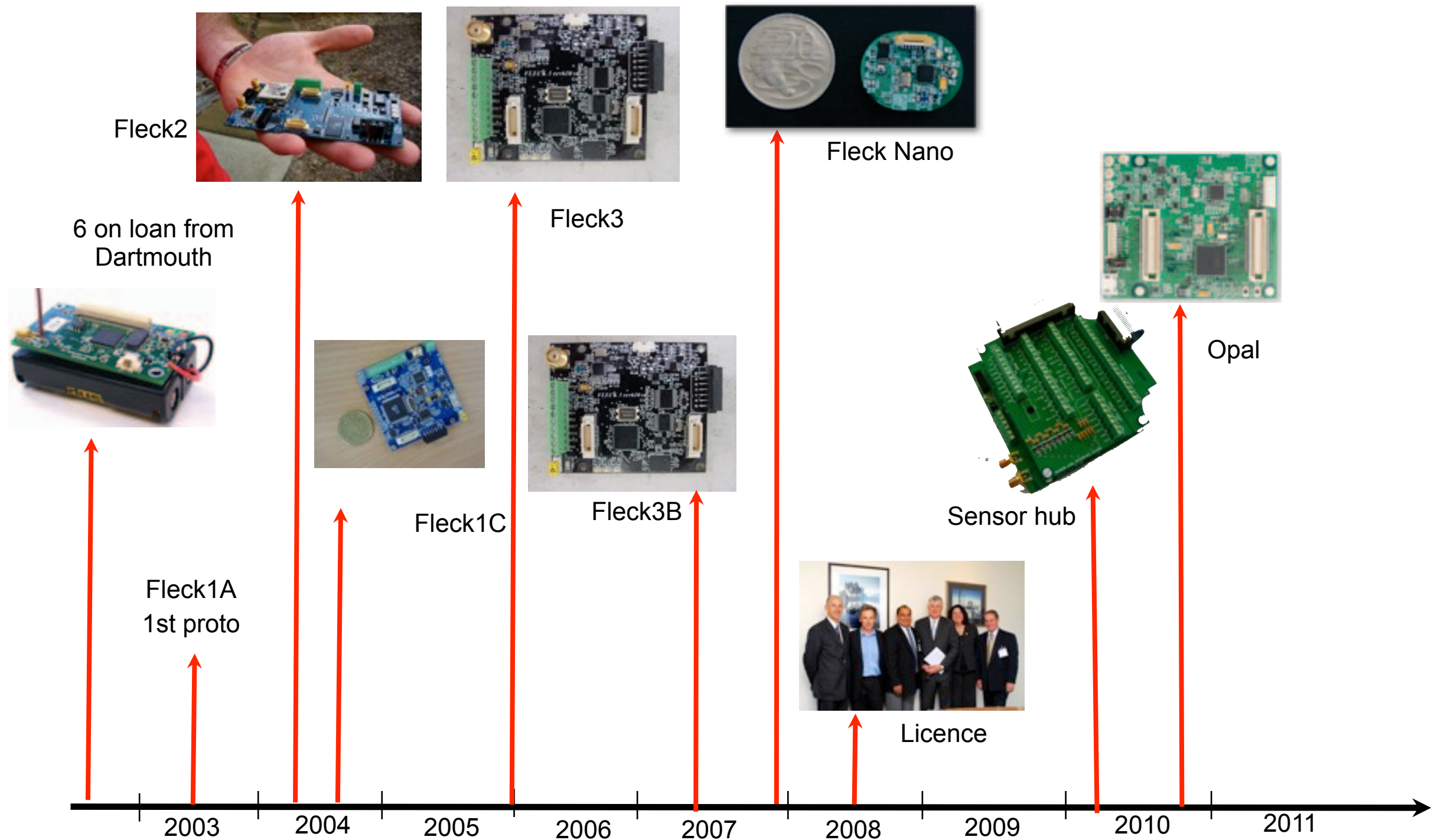




# Where are the cameras?



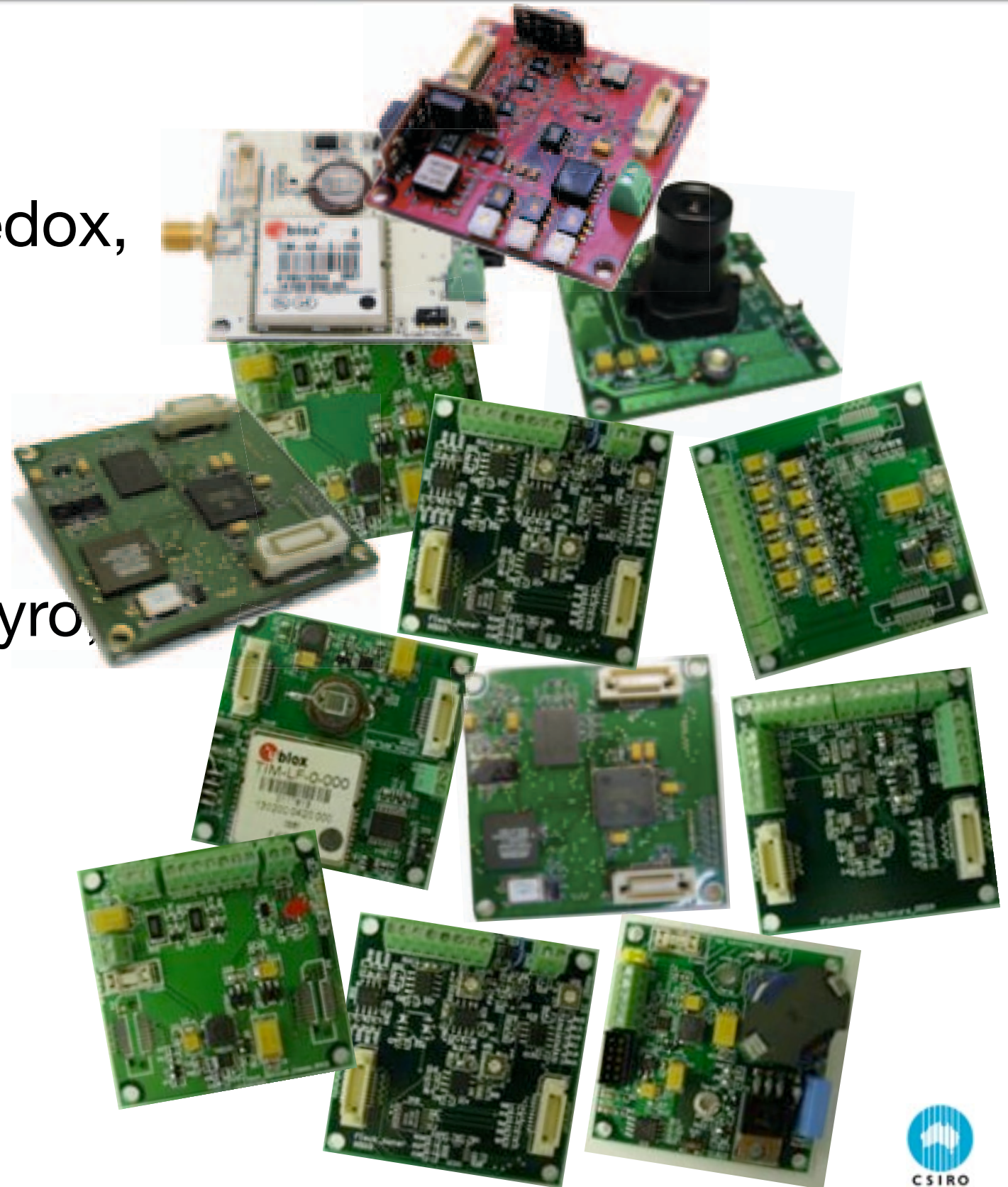
# History of the CSIRO's Fleck™ Hardware



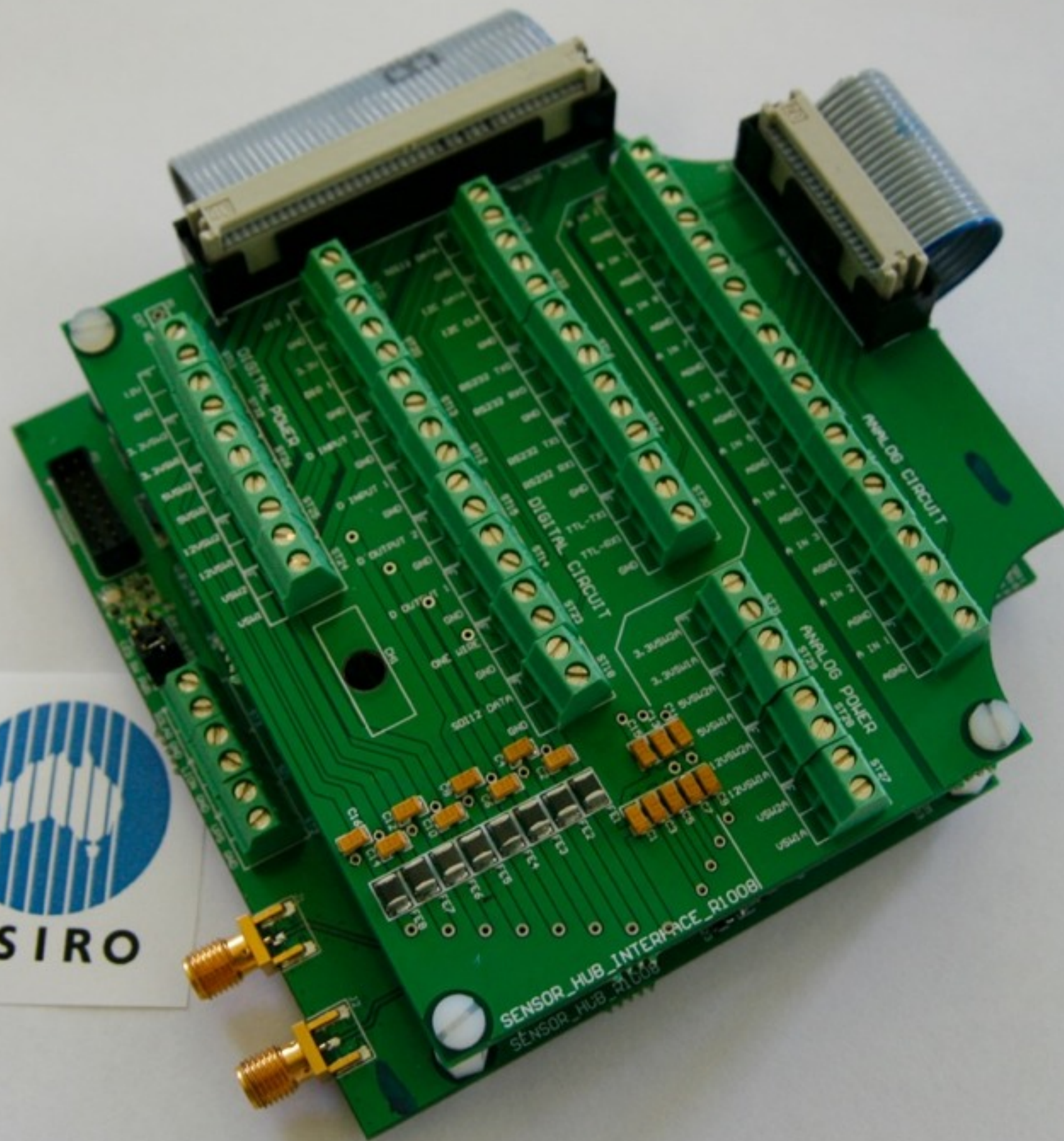


# Sensor boards

- Light, Temp
- Water Quality: pH, Redox, Temp, Conductivity
- Soil Moisture
- Motion: GPS, Accel, Gyro, Magnetometer
- Strain Gauges
- DSP: Audio, Video



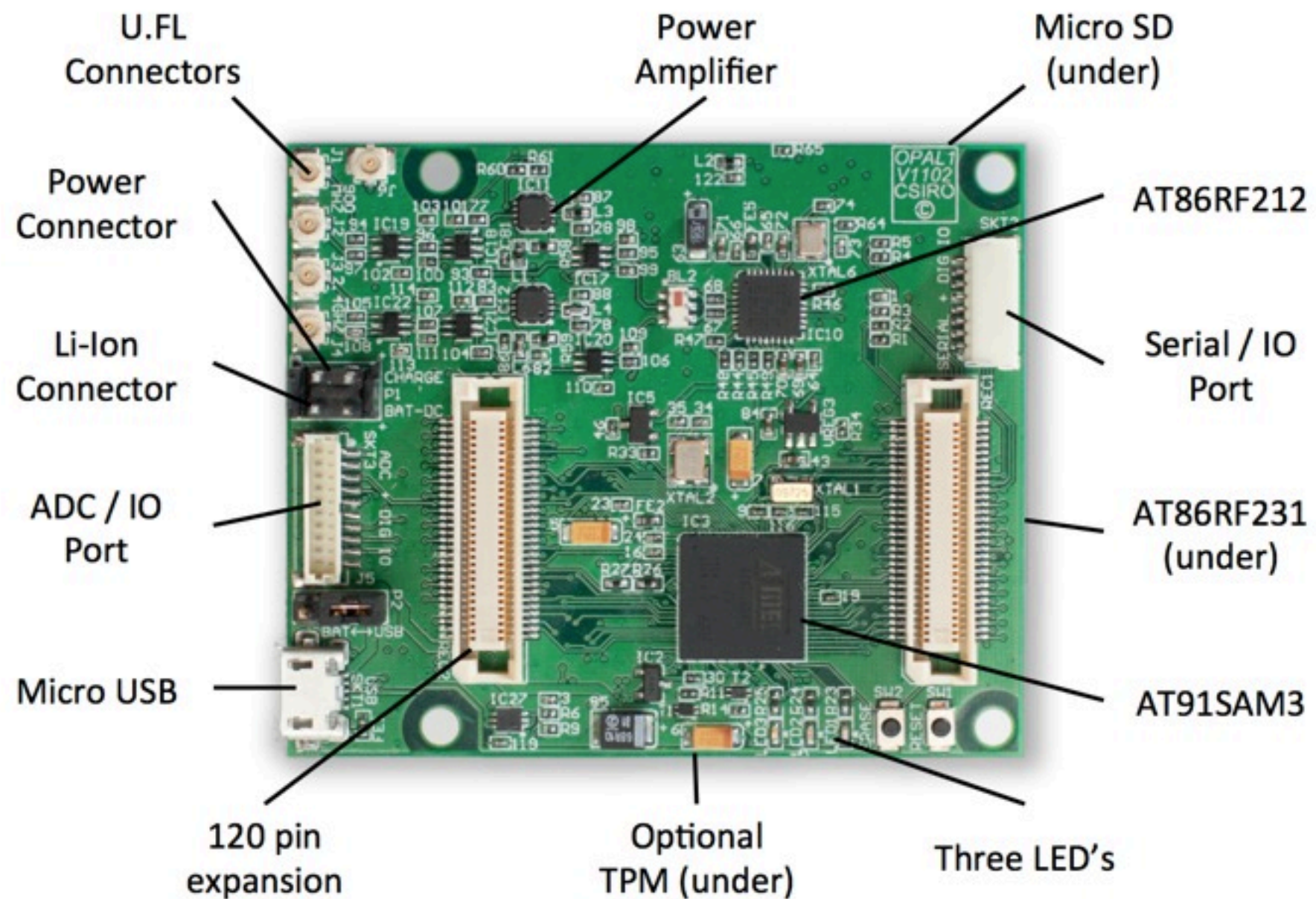






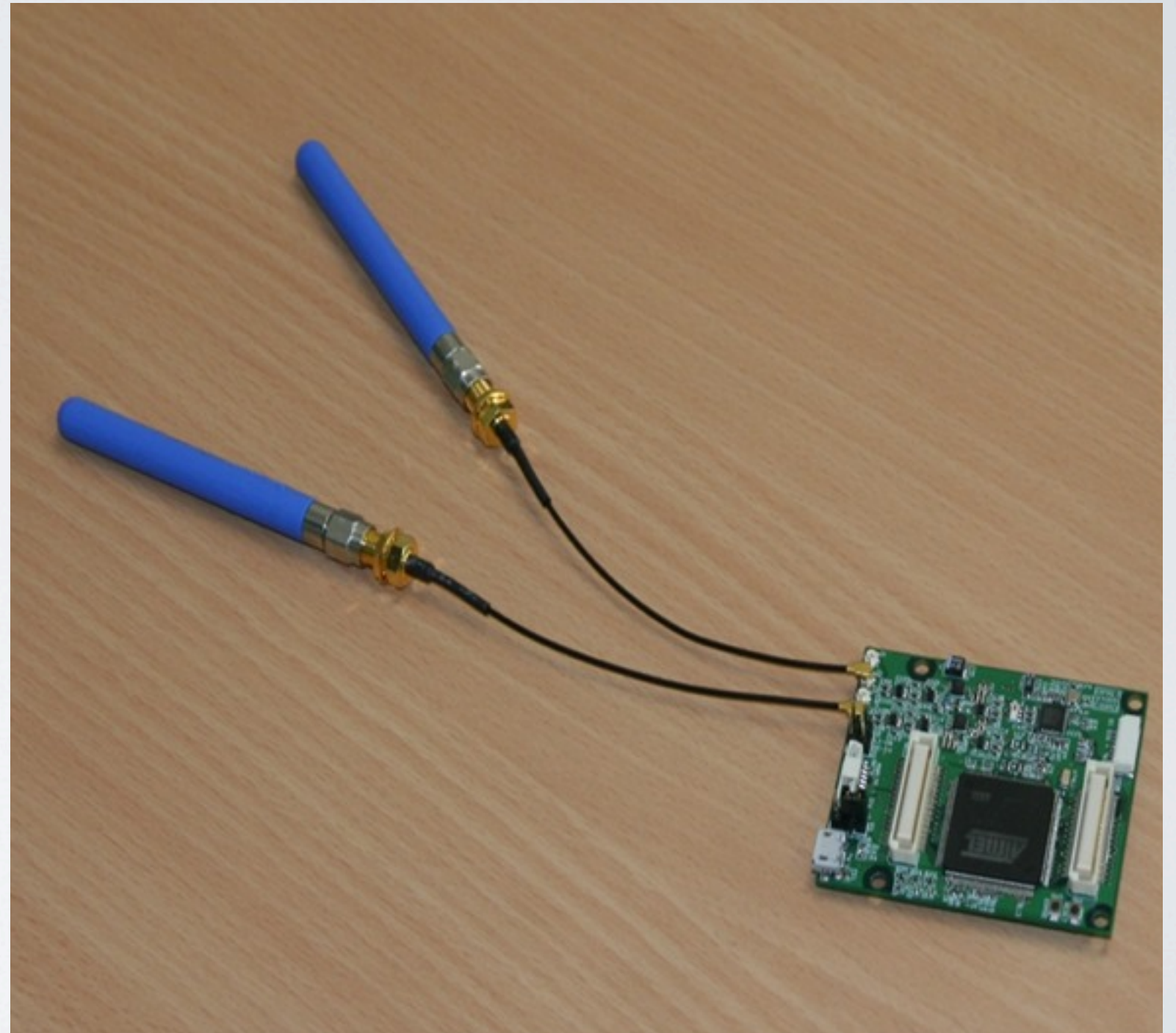
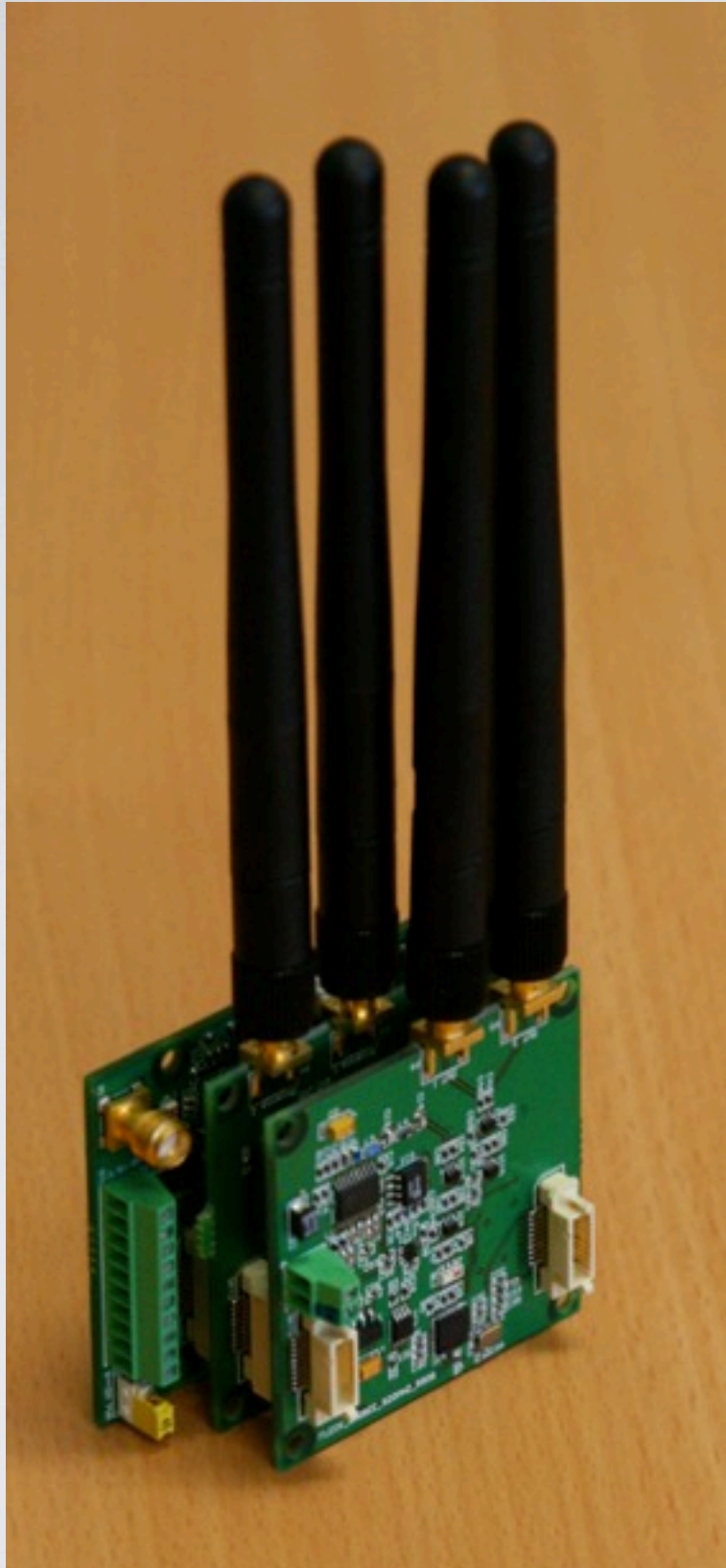
# The CSIRO's Opal Sensor Node

A next-generation WSN node. Dual-frequency dual-antenna.



R. Jurdak, K. Klues, B. Kusy, C. Richter, K. Longendoen, M. Bruenig. "Opal: A Multi-radio Platform for High Throughput Wireless Sensor Networks", IEEE Embedded Systems Letters, December 2011.







# Current Practices to Improve Link Reliability

- Careful selection of node locations
  - Hand-place nodes for direct line of sight
- Over-provisioning
  - Link-level retransmissions (e.g., 30x by CTP)
  - Node spacing of one 20<sup>th</sup> or 50<sup>th</sup> of the expected radio range
  - Placement of additional forwarders in poorly connected areas
  - Use of high gain directional antennas for communication backbone
- Consequence: increased cost and time to deploy sensors!!!



# Improving Link Robustness Through Diversity

## Frequency diversity

- Embrace wide-band solutions
- Operate multiple radios simultaneously to avoid synchronization complexity

## Spatial diversity

- Use multiple antennas
- Connect each radio to a separate antenna

## Time diversity

- Spreading, done by 802.15.4 chips already

## Our reference architecture

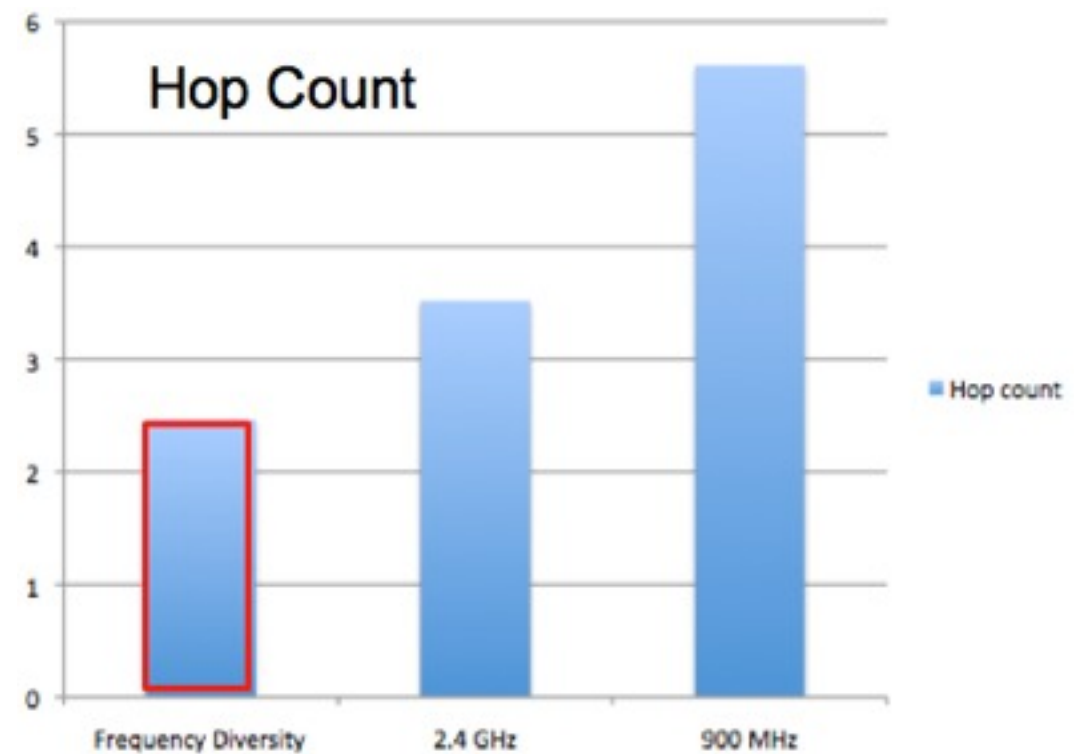
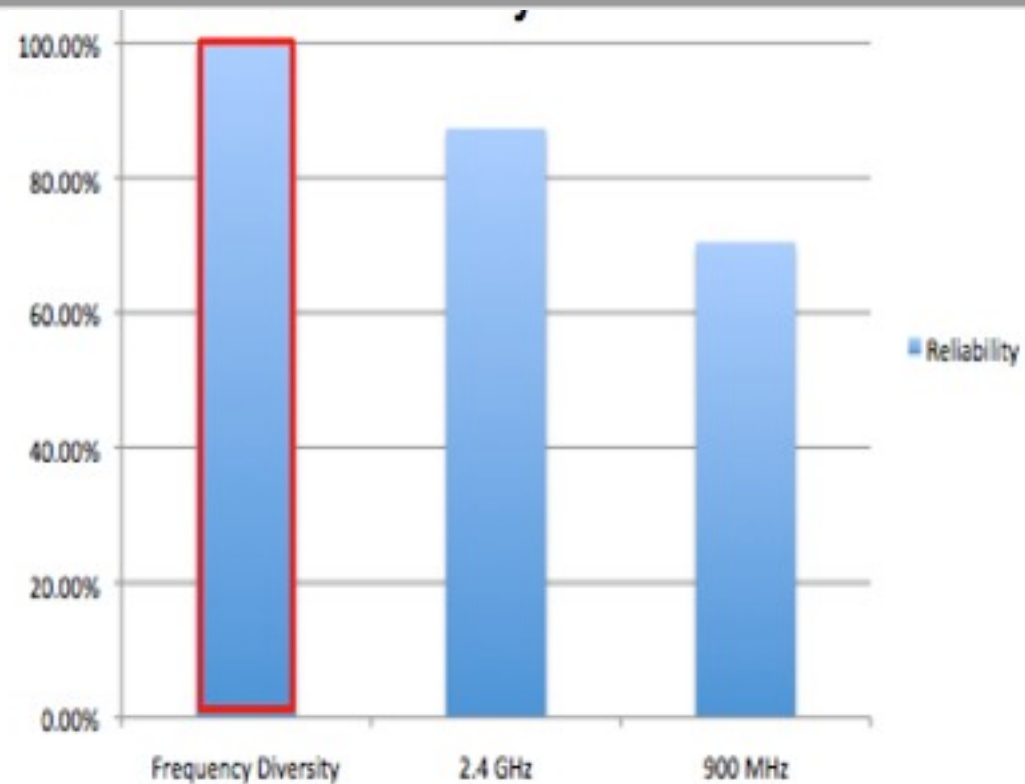
- Use two 802.15.4 radio chips
- Radio frequencies separated by 1.5GHz
- Antennas separated by 0.5m



Metric	AT86RF212	AT86RF230
Frequency	779-787MHz 863-870MHz 902-928MHz	2405-2480MHz
Data rates	BPSK: 20, 40 kbps, O-QPSK: 100, 200, 250, 500, 1000 kbps	O-QPSK: 250 kbps
TX power	-11 to 10 dBm	-17 to 3 dBm
Sensitivity (250kbps)	-101 dBm	-101 dBm
Link budget (250kbps)	111 dBm	104 dBm



# The CSIRO's Opal Sensor Node



B. Kusy, C. Richter, W. Hu, M. Afanasyev, R. Jurdak, M. Bruenig, D. Abbott, C. Huynh, and D. Ostry. "Radio Diversity for Reliable Communication in WSNs," In Proceedings of the 10th International Conference on Information Processing in Sensor Networks (IPSN), Chicago, USA, April, 2011.

# Implementation

## Dual radio driver in TinyOS

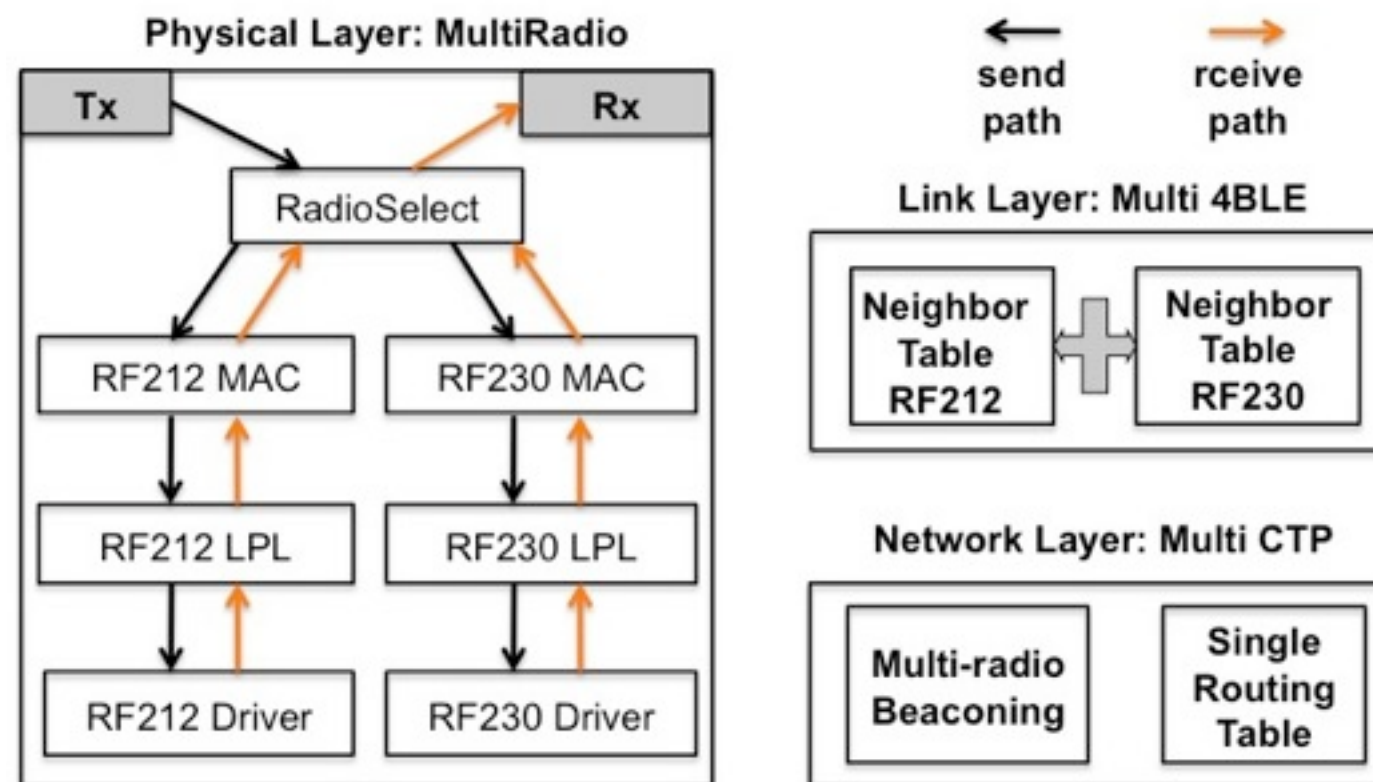
- Sleep, transmit, receive packets independent of each other

## Link estimation and data collection layers

- Extended to work with multiple radios, two neighbor tables, etc

## Conform to standard TinyOS interfaces and packet headers

- Our platform works with existing applications and deployments!!!





# Real progress over the decade

---

- Communications
  - Radio hardware
    - 802.15.4 standard, more sensitive receivers, duty cycling, encryption, bigger packets, higher bit rate, support for TOF measurement
    - more than one radio per mote, more than one antenna per radio
  - Protocols, IPv6
- Mote software, Contiki & TinyOS, widely used, large user communities, good platform support, threads
- Processor, moving beyond AVR and MSP; 32 bit, frequency scaling on the horizon
- Energy: processor consumption has fallen, more efficient algorithms, energy harvesting is real (vibration, solar etc)
- Testbeds
- Simulation tools (communications, protocols, energy etc.)

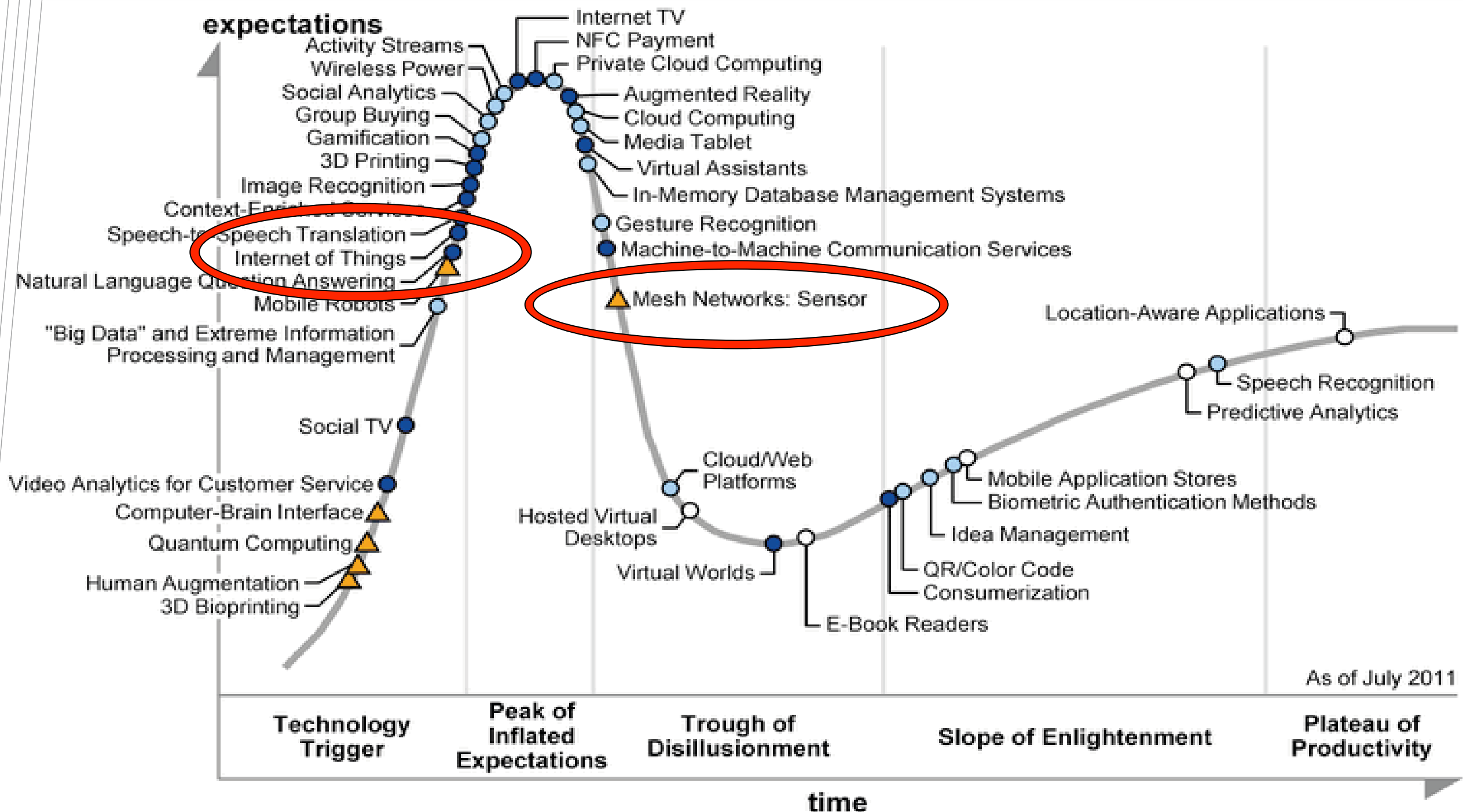
# Areas for future work

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- Secure reprogramming and network control
- Automatic network diagnosis
- Pre-deployment planning tools
- In-situ audio and video processing
- Automated data collection, robots and sensor networks as appropriate and integrated
- Task-level programming, stop programming the mote
- Visualization and mining of sensory data streams
- Mobile phone class processors: Cortex + DSP + GPU



# Gartner Hype Cycle



**Years to mainstream adoption:**

○ less than 2 years

● 2 to 5 years

● 5 to 10 years

▲ more than 10 years

obsolete

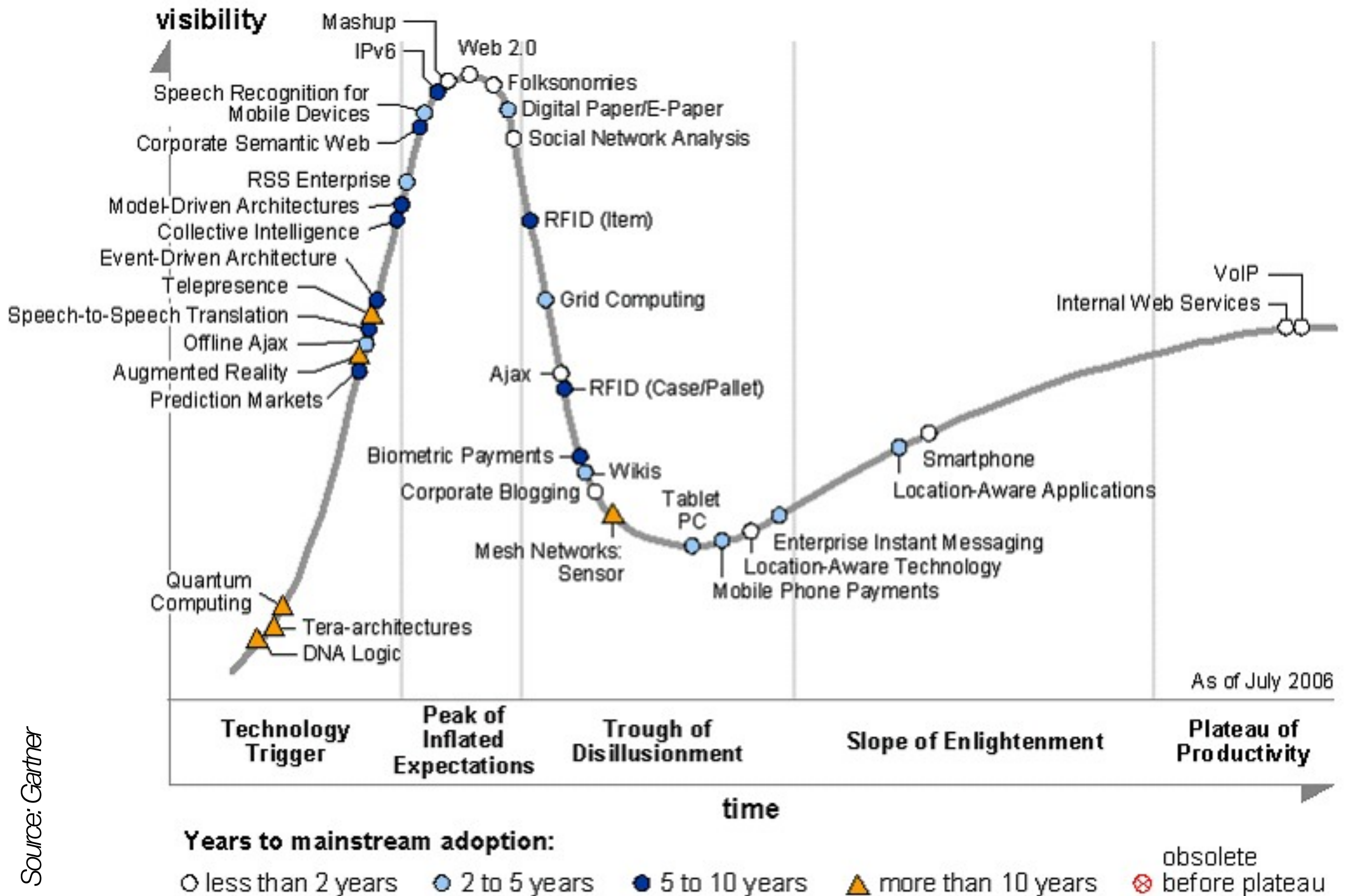
⊗ before plateau

Source: Gartner.com



CSIRO. Sensors and Sensor Networks Transformational Capability Platform.

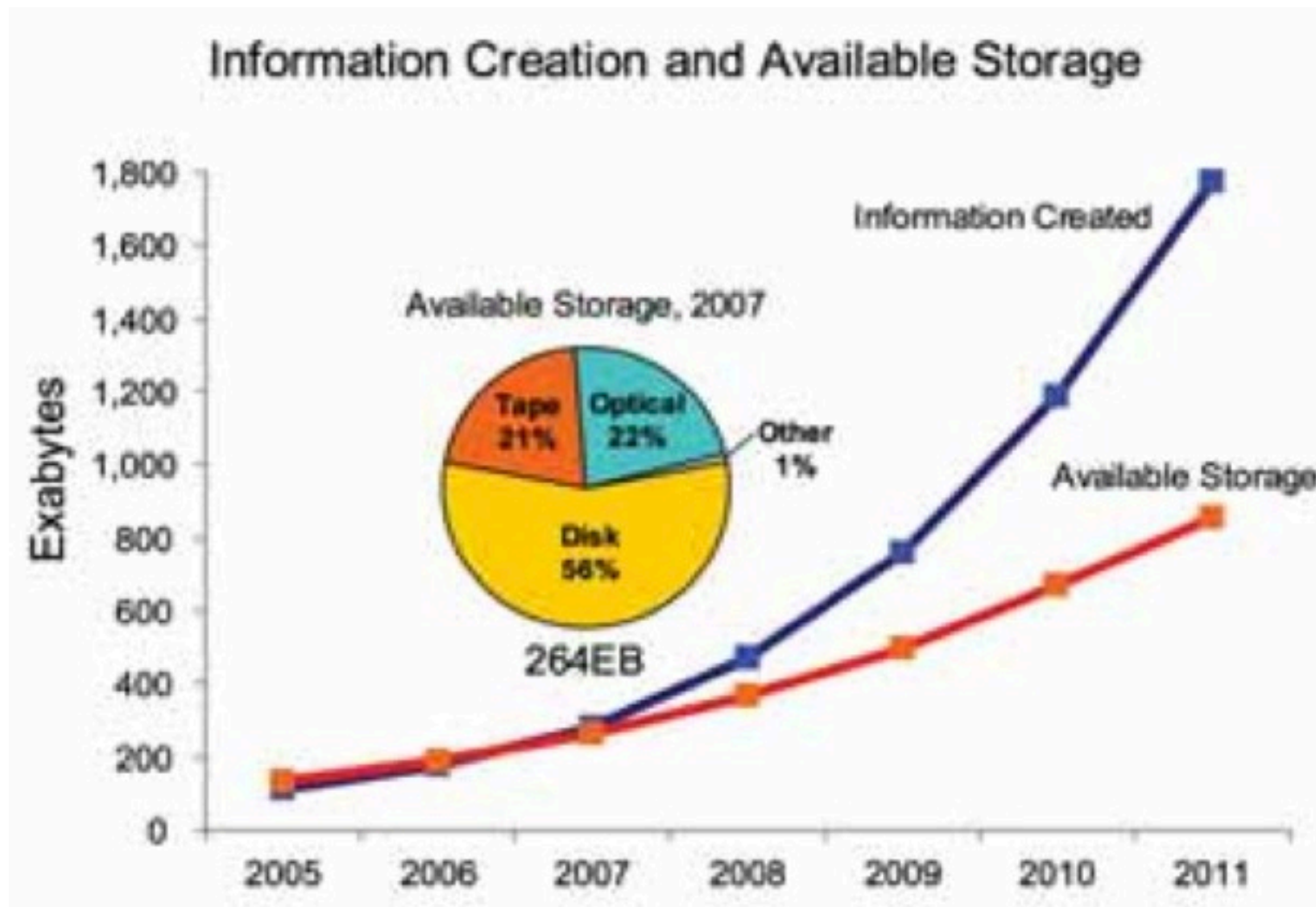
# The Hype Cycle



Source: Gartner



# Information Creation vs. Available Storage



Source: IDC White paper, The diverse and exploding digital universe, March 2008

# Engagement Opportunities

## • Students

- Full scholarships
  - **Endeavour Postgraduate Fellowships:** provide financial support for international students for up to 4 years to undertake a postgraduate qualification at a Masters or PhD level in Australia (**applications due in June**)
- Internship support
  - **Endeavour Research Fellowships:** support research towards a Masters degree or PhD in home country; or postdoctoral research (**applications due in June**)
  - **CSIRO traineeships:** support research towards a Bachelors, Masters or PhD in home country (**applications open**)

## • Faculty

- Distinguished Scholar Visits
  - Research-oriented
  - 3-12 months
- Endeavour Executive Awards
  - Professional development
  - 1-4 months
- Joint proposals through international funding schemes
- Resource (hardware) sharing for joint research
  - Currently sharing nodes with MIT, ETH-Zurich, TUM, Johns Hopkins, TU Delft..





Cyber-Physical Systems Lab  
Queensland University of Technology

<https://wiki.qut.edu.au/display/cyphy>



<http://sensornets.csiro.au>

# Questions?

or email me: [peter.corke@qut.edu.au](mailto:peter.corke@qut.edu.au)